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Prediction of the surface cracking pattern of an oxidized polymer induced by residual and bending stresses.

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Abstract. The objective of the paper is to analyze four point bending tests performed on samples of an epoxy-type thermoset polymer oxidized under several conditions, and to predict the failure mechanisms. Different responses are observed depending on the oxidation time: for small durations there is a linear elastic phase followed by an abrupt failure of the specimen whereas for higher oxidation times, the elastic phase is followed by a nonlinear one corresponding to the development of numerous superficial micro-cracks prior to failure. In order to predict this behavior, a finite fracture mechanics approach based on the coupled criterion is used. This criterion requires an energy and a stress condition to be fulfilled. This approach is here extended to take into account the gradient of properties of the oxidized layer: Young's modulus, tensile strength, toughness. One novelty of the approach is to implement the model in a periodic representative cell in order to process an increasing number of cracks. Despite the large scattering in the experimental detection of the initiation of the micro-cracks and their counting, the predictions agree rather well with the observations: the oxidation times leading either to a sudden failure of the sample or to micro-cracking are well reproduced, and

the loads triggering the crack onset as well as the increase in number of cracks are somewhat well predicted.

1. Introduction

The use of fiber reinforced polymers is becoming more common in transportation industries, particularly in the manufacture of aircrafts. The weight ratio of composites is more than 50% in the two recent aircrafts Boeing-B787 and Airbus-A350. For similar performances, composites offer a substantial gain in weight that leads to a reduction in fuel consumption with all the well-known positive economic and ecological consequences. In return the polymers, used as a binder, suffer from an ageing phenomenon that alters their properties with time and that must be perfectly controlled for safety reasons. Three main sources for this ageing: the action of humidity, UV rays and oxidation. This work focuses on the latter mechanism that damages the exposed surfaces and that can even lead to cracking (Colin et al., 2005; Verdu, 2012). Therefore, it is important to quantitatively estimate this damage for having a better knowledge of the influence of the degradation on the composite performance (Vu et al., 2012; Vu et al., 2013; Daghia et al., 2015).

Several studies have been conducted on the behavior of the PR520 resin (Cycom, 2014), a polymer used in the aircrafts industry (Fard et al., 2014; Pecora, 2014; Pecora et al., 2016), both on the pristine and the oxidized material. They show that it is difficult to estimate the mechanical properties of the oxide as a function of the oxidation time, especially because, due to a large scattering, it is tricky to interpret tests on thin films supposed to be homogeneously oxidized. Thus measures must be carried out on thick specimens undergoing gradients of properties. This is accentuated when addressing the fracture properties: it is known that the material becomes more brittle with oxidation but it is virtually impossible to evaluate the tensile or flexural strength as well as the toughness, function of the oxidation time. In (Pecora, 2014) and (Pecora et al., 2016) 4-point bending tests are carried out, up to failure, on specimens after a controlled oxidation at 120 °C, either in air or in O₂ pressurized atmosphere at 3 bars. In the context of oxidizing thermomechanical loading of Carbon/epoxy composite laminates, some attempts have been done to identify the matrix toughness reduction with oxidation level through a micro-damage model (Lubineau et al., 2006; Lubineau et al., 2009). An interesting and challenging feature is that for low oxidation times samples failed abruptly after a linear elastic phase, whereas micro-cracking and non-linearity appear prior to failure for longer oxidation times.

Micro-cracking is a complex phenomenon that has been more often studied in thin films bonded to a substrate (Laws and Dvorak, 1988; Nairn, 1989; Xia and Hutchinson, 2000, Kim and Nairn, 2000; Fu et al., 2013). Unlike the present case, the crack length is known (the thickness of the thin layer) and the problem is much easier to address. Micro-cracking is also observed during quenching of ceramics (Shao et al., 2010; Bahr et al., 2010; Jiang et al., 2012) or in drying processes (Jenkins, 2009; Maurini et al., 2013; Leguillon, 2013; Leguillon et al., 2014).

In the present case the situation is a little more intricate because surface micro-cracking occurs in a material with a gradient of properties through the oxidized layer. The model we proposed is based on the coupled criterion (CC) (Leguillon, 2002; Leguillon and Yosibash, 2003; Martin and Leguillon, 2004) which enters the framework of Finite Fracture Mechanics (see the review paper by Weissgraeber et al. (2015) for an extended list of references in the topic). It requires the knowledge of both the tensile strength and the toughness of a material to predict the onset of a new crack at stress concentration points. In order to take into account multiple cracks, it is implemented in a cell that is assumed to be representative of the whole cracked domain by periodic repetition. A major obstacle to overcome is the lack of knowledge of the mechanical parameters through the oxidized layer.

The first section presents the ageing process and the experiments carried out up to failure on polymer specimens. It shows known material parameters and the way they vary as functions of the oxidation time and the depth in the oxide layer, together with some assumptions made to overcome the unknowns. The next section is dedicated to an extension of the CC to materials with a gradient of properties. The numerical model based on the representative periodic cell is explained in the next section. It is followed by a first group of numerical results dedicated to long oxidation times and another one devoted to smaller oxidation times. A full FE simulation of the 4-point bending test is carried out for comparison on the onset of the first crack. A conclusion completes this work.

2. Material properties and experiments

Material, techniques and experimental conditions

The studied material (Cycom PR520) is an epoxy-type thermoset polymer, processed according to the parameters suggest by the supplier (Cycom, 2014). Complete curing of the material has been checked through DSC analysis leading to a glass transition temperature equal to 160°C. Specimens have been cut according to the geometry prescribed for a standard

4-point bending test (L=120mm, l=10mm, h=3.5mm), and aged in an isothermal environment, at 120°C, under neutral or oxidizing gaseous atmospheres (respectively N₂ and O₂), for different durations (Table 1).

Environment	Pressure (bar)	Duration (h)	Temperature (°C)	
Nitrogen (N ₂)	3	200	120	
Oxygen (O ₂)	3	100 / 200 / 400 / 600	120	7
L	1	I		1

Table 1. Ageing conditions for PR 520 samples.

The change in local elastic properties of the resin, due to thermo-oxidation, was characterized by Ultra-Micro-Indentation tests: the indentation elastic modulus (EIT) evolution was followed along the thickness of the specimen, from the surface exposed to the environment towards the sample core according to the protocol set up (Ho et al. 2006, Olivier et al., 2008). In Figure 1, the results of indentation tests are presented. Elastic indentation modulus (EIT) values have been normalized compared to that of the virgin material. So an oxidation tracer γ has been defined as

$$= \frac{EJT_{measured}}{EIT_{virgin}} - 1$$

The mean value of $\text{EIT}_{\text{virgin}}$ for the non-oxidised resin has been evaluated from 140 measures, and each point of the graphic in Figure 1 tallies with the average value of a twelve-measure series, realised at the same distance from the external surface in contact with environment. To better understand the figure, the error associated with the average values is not represented on the graphic. Nevertheless, the error, evaluated through statistical analysis, is less than 1%.



Figure 1. Elastic indentation module profiles (oxidation tracer γ) for PR520 samples aged at 120°C for different durations, under neutral (3 bar N₂) and oxidizing (3 bar O₂) environments.

In Table 2, the characteristics of the oxidized layers for the considered ageing conditions are summarised. The indentation module variation, EIT (%), is the value of the parameter γ at a distance from the external surface of 30 μ m, and the oxidized layer depth is defined as the zone size for which γ values are higher than 1%.

Table 2. Elastic indentation module variation and depth of the oxidized layer for different resin specimens, aged at 120°C in neutral and oxidizing environments.

Ageing conditions	$N_2 200h$	O ₂ 100h	O ₂ 200h	O ₂ 400h	O ₂ 600h
EIT variation (%)	0	5,7±1	11,3±0,9	26,3±0,6	40±0,6
Thickness of oxidized layer (μ m)	0	475±50	600±75	700±100	750±100

In Figure 1 and in Table 2 it can be observed that ageing in a Nitrogen environment does not change the elastic behaviour of the material. On the other hand, during the ageing in oxygen, a gradient of properties develops between the virgin core and the external surface, in an oxidized layer whose dimension and module variation amplitude evolve according to

exposure time. These local mechanical behaviour changes appear similar to those of other epoxy resins (Olivier et al., 2008; Lafarie-Frenot et al., 2010).

To evaluate the ultimate strength of the studied polymer and its evolution with oxidation, a four-point bending equipment has been designed by following the standard ASTM D6272-10 recommendations (ASTM, 2010). The equipment has been placed on the Instron 1195 tensile testing machine (Figure 2) and the tests have been performed at room temperature, under displacement control with a speed of 0.22 mm/min, corresponding to a strain rate on the specimen surface of about 0.012/min. To obtain additional information during the tests, two kind of instrumentations have been used:

- A digital high resolution camera (HR EC11000) recorded all along the test the displacement of the edge of the sample in its central part between loading pins.
- An EPA Acoustic Emission (AE) system was used to reveal in some cases, the onset of cracks. Two micro sensors (diam. 8mm) were clamped on the extremity of the specimens with silicon grease coupling. The data were analysed with AEWin software. A minimum amplitude threshold of about 30 dB was used to filter the noise and the system was calibrated to localize events between the loading pins.



Figure 2. Four-point bending test and its instrumentation: digital camera and acoustic emission.

Experimental results

For each ageing condition, from 3 to 5 samples have been tested in bending (Figure 3) which have shown a very good reproducibility, except on the values of strain at failure. In parallel,

an enhanced beam model (EBM) was used to express the stresses along the tensile surface of the specimens. This improved model was developed in order to take into account the gradient of the Young modulus in the oxide layer (Pecora et al., 2016).



Figure 3. Schematic view of the 4-point bending test, due to symmetry only one half of the specimen is shown.

It has been observed that the virgin material has a non-linear behaviour beyond a maximum bending strain of 3% and that its failure strain is around 6% (corresponding to a failure stress of 187 ± 8 MPa according to the EBM). Moreover, an embrittlement of all oxidized specimens could be noticed: their failure bending strain is always less than 3%, and reach around 1% for highly oxidized specimens. Besides, it could be observed that the specimens aged 400h and 600h under 3 bars of oxygen exhibit a slightly non-linear behaviour consisting in a small decrease in stiffness before their ultimate failure. Contrarily to the other samples that failed suddenly, these highest oxidized samples have been concerned by a multi-cracking phenomenon: several cracks were observed in the lower part of the bent specimens, as shown in Figure 4, either on in-situ observations (Figure 4a), or on X-ray tomography pictures taken after the bending test (Figure 4b). These pictures show that cracks have almost the same length along the thickness, that they cross the entire width of the sample and are regularly distributed in the cracked zone.

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a- in-situ observation



b- RX tomography picture

Figure 4. Multi-cracking phenomenon observed on PR520 resin aged at 120 °C for 400h under $3bar O_2$.

In addition, this multi-cracking phenomenon has been observed and monitored during the whole bending tests, by counting cracks visually on in-situ photographs of the specimen side and by recording acoustic emission. From these data, the number of cracks has been evaluated for many specimens and plotted in Figure 5 vs. the maximum bending strain, according to the duration of ageing (400h or 600h under 3 bar of oxygen).



Figure 5. Number of cracks visually measured (open symbols) or number of acoustic events (solid symbols) as function of the maximum bending strain in PR520 aged at 120° C under 3bar O₂ during 400h (red), 600h (black). S XX denotes the specimen number.

Material parameters for the simulations

The mechanical parameters of the sound material (i.e. prior to any oxidation phenomenon) are given by the manufacturer data sheet (Cycom, 2014): Young's modulus E = 4000 MPa, Poisson's ratio v = 0.4, tensile strength $\sigma_c = 82$ MPa, flexural strength $\sigma_r = 153$ MPa, toughness $G_{\rm Ic} = 1400$ J m⁻², Weibull's modulus m = 16 (Fard et al., 2014).

Now, as already mentioned in the introduction, the main challenge is to know how the material parameters mentioned above evolve during the oxidation process through the oxidized layer. The thickness of the oxide layer is given in Table 2. Young's modulus changes (Figure 6) are supposed to be proportional to that of the EIT (Figure 1) and Poisson's ratio is assumed to remain unchanged. It is observed that Young's modulus almost linearly increases with the ageing time t_{ox} .



Figure 6. Approximation Young's modulus *E* changes in the oxide layer function of the depth *y* for different values of the oxidation duration t_{ox} .

The changes in the tensile strength have been estimated from the load at failure in the 4-point bending tests, using the EBM. It exhibits a dramatic drop (Pecora et al., 2016). However, it must be pointed out that the provided values correspond to the flexural strength whereas it is the tensile strength that is involved in the CC. It is claimed in (Leguillon et al., 2015a) that the tensile strength is the only material parameter, the flexural strength depending on the thickness of the specimens on which measures are done. These values must be corrected twice to recover the tensile strength: a correction deriving from the CC and a correction due to the Weibull statistics, both depending on the thickness. Although Weibull's modulus is known for the pristine material it remains unknown otherwise, it is probably smaller in the more brittle oxide layer. It was therefore decided to take the initial value ($t_{ox} = 0$ h) provided by the manufacturer and then apply the same rule of proportionality as that found in (Pecora et al., 2016) (Table 3). The distribution through the oxide layer is shown in Figure 7.

The evolution of the toughness G_{Ic} is definitely unknown, different attempts have been made to better match the observations as shown later (Table 3). The assumed distribution through the thickness of the oxide layer is depicted in Figure 8. Again there is a dramatic drop as can also be observed in (Han and Nairn, 2003) but in a different context (hydrothermal ageing) and a different material which only allow qualitative comparisons.

Ageing conditions	O ₂ 0 h	O ₂ 200 h	O ₂ 400 h	O ₂ 600 h
$\sigma_{ m c}$ (MPa)	82	23.2	15.6	14.0
$G_{\rm lc} \ ({\rm J m^{-2}})$	1400	500	75	50

Table 3. Tensile strength and toughness functions of the oxidation time.



Figure 7. Assumed tensile strength σ_c changes in the oxide layer function of the depth y for different values of the oxidation time t_{ox} .



Figure 8. Assumed toughness $G_{\rm Ic}$ changes in the oxide layer function of the depth y for different values of the oxidation time $t_{\rm ox}$.

3. The coupled criterion

The failure or the multi-cracking occurring during the 4-point bending tests are crack nucleation mechanisms. The Griffith criterion usually used in brittle fracture mechanics does not work, it can only be applied to the crack growth from a pre-existing crack. There are two conventional alternatives: the cohesive zone models and the CC (Cornetti, 2016; Martin et al., 2016). It must be pointed out that in both cases, two fracture parameters are required, they are either the peak stress and the critical opening in the former case or the tensile strength and the toughness in the latter. The formers are well-known in computational mechanics but lead to solve non-linear problems with the inherent convergence difficulties. In the present work we have selected the second approach. The CC states that two conditions must be fulfilled to predict crack nucleation: an energy condition and a stress one (Leguillon, 2002). To be implemented, only a given number of linear systems are solved.

The energy condition

The first condition derives from a basic energy balance between an uncracked initial state and a final state containing a crack of length a. In a homogeneous material it can simply be written

$$W_{\rm P}(0) - W_{\rm P}(a) \ge G_{\rm L}a \tag{1}$$

Where $W_p(a)$ is the potential energy of the cracked structure and the right hand side member is the energy dissipated to create a crack of length a, G_{Ic} (J m⁻²) is the toughness of the material. Note that in this 2D framework the thickness of the specimen is omitted. The right hand side member can be expressed in term of the energy release rate G

$$W_{\rm P}(0) - W_{\rm P}(a) = \int_0^a G(y) dy \quad \text{with} \quad G(y) = -\frac{\partial W_{\rm P}(y)}{\partial y} \tag{2}$$

In the oxide layer the toughness G_{Ic} varies, it is a function of the depth y and the right hand side member of (1) must be modified as follows

$$\int_0^a G_{\rm Ic}(y) {\rm d}y$$

So that the final formulation of the energy condition is

$$W_{\rm P}(0) - W_{\rm P}(a) \ge \int_0^a G_{\rm lc}(y) dy \tag{3}$$

It is conveniently rewritten

$$\frac{W_{\rm p}(0) - W_{\rm p}(a)}{a} = G_{\rm inc}(a) \ge \bar{G}_{\rm Ic}(a) \text{ with } \bar{G}_{\rm Ic}(a) = \frac{1}{a} \int_0^a G_{\rm Ic}(y) dy$$
(4)

The function $G_{inc}(a)$ is called the incremental energy release rate as opposed to the differential energy release rate defined in (2). Note that, using (2), the expression (4) can be remarkably simplified in

$$\overline{G}(a) \ge \overline{G}_{lc}(a)$$
 with $\overline{G}(a) = \frac{1}{a} \int_0^a G(y) dy$

But this inequality is misleading. It might suggest an empirical weak form of the Griffith criterion involving averages, while it is physically based as explained above. Moreover, the energy condition is employed under the form (4) in the forthcoming calculations without direct references to $\overline{G}(a)$.

The stress condition

The stress condition involves the tensile strength σ_c of the material and states that the following stress condition (5) must be fulfilled, prior to fracture, all along the presupposed crack path of length *a*

$$\sigma(y) \ge \sigma_c \quad \text{for } 0 \le y \le a \tag{5}$$

Where $\sigma(y)$ is the tensile component of the stress field acting on the presupposed crack path. In the domain of applicability of the CC, it is a non-increasing function of y and then (5) reduces to

$$\sigma(a) \ge \sigma_{\rm c} \tag{6}$$

Which looks like a point stress condition although it expresses the non-local condition (5). The simplified formulation (6) is permitted only in homogeneous materials where σ_c is a material constant. In the oxide layer, σ_c exhibits a gradient and the condition (5) must be written

$$\sigma(y) \ge \sigma_{\rm c}(y) \text{ for } 0 \le y \le a \tag{7}$$

In the present case, it is observed that $\sigma_{c}(y)$ is a non-decreasing function of y (see the next section) and together with the non-increasing function $\sigma(y)$, (7) simplifies in

$$\sigma(a) \ge \sigma_{\rm c}(a) \tag{8}$$

The coupled criterion

In order to plot the two conditions (4) and (8) in the same diagram, they are expressed in a dimensionless form

$$\frac{G_{\rm inc}(a)}{\overline{G}_{\rm Ic}(a)} \ge 1 \quad \text{and} \quad \frac{\sigma(a)}{\sigma_{\rm c}(a)} \ge 1 \tag{9}$$

The main difference with a standard situation is that all the parameters depend on a, not only the incremental energy release rate $G_{\rm inc}$ and the tensile stress σ as usual, but also the material parameters $G_{\rm Ic}$, $\bar{G}_{\rm Ic}$ and $\sigma_{\rm c}$.

Whenever possible, using asymptotic expansions to calculate the change in potential energy (Leguillon, 2002) shows that, in most general cases, fulfilling the inequality (3) implies a

crack jump at onset and a finite lower bound a_0 of admissible crack lengths can be derived as a function of the applied load, hence the term Finite Fracture Mechanics due to Hashin (1996). In the same way, the second inequality (6) or (8) provides an upper bound of the admissible lengths. The combination of (3) and (6) or (8) leads to a unique determination of the initiation length a_0 and the load intensity at failure, which is the CC principle.

Once the crack is initiated and using the same dimensionless formulation as (9), the condition for crack growth is the well-known Griffith criterion

$$\frac{G(a)}{G_{\rm r}(a)} \ge 1$$

(10)

4. The numerical model

A weight loss and a chemical shrinkage are accompanying the parameters changes during the ageing process. As a consequence, residual stresses arise, the surfaces are in tension and are balanced by a compression in the core of the specimen. They are calculated using Finite Elements (FE) by adjusting the parameters of a linear thermo-elastic model in order to match with the residual stresses described in (Pecora, 2014; Pecora et al., 2016) (Figure 9).



Figure 9. Tensile component of the residual stress σ^{ch} in the oxide layer function of the depth *y* for different values of the oxidation time t_{ox} .

It is observed in the experiments that this tension is not large enough to trigger spontaneous surface cracking. However, it can be already noted that this holds true despite the fact the tensile stress along the surface is larger than the tensile strength for $t_{ox} = 600$ h (Table 3 and Figure 9), as predicted by the CC as will be seen further.

Then, the specimens are submitted to a 4-point bending load up to failure and different results arise according to the oxidation time t_{ox} . As already claimed, for the pristine material and for $t_{ox} = 200$ h, there is an almost linear elastic phase followed by an abrupt failure. For $t_{ox} = 400$ h and $t_{ox} = 600$ h, a non-linear phase follows the first elastic one, it corresponds to the onset of an increasing number of surface micro-cracks, the final failure is thus delayed.

Our model is focused to best match with these different mechanisms. For this, it has to take into account a large number of small cracks and predict their spacing. To this aim, the active part of the specimen (i.e. between the two inner loading pins) is represented as a periodic sequence of representative cells (RC) (Figure 10). The length d of the cell is an unknown parameter denoting the cracks spacing. For symmetry reasons, the FE calculations are carried out on one half of the RC.





Figure 10. The part of the specimen between the two loading pins and the representative cell.

As already mentioned, the chemical shrinkage is computed using a linear thermo-elastic model by adjusting the parameters to the experimental

Figure 11. The two loading modes of the RC to simulate the residual stresses.

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measures. In particular, it must not be forgotten that the shrinkage depends on the level of oxidation and is therefore variable through the thickness of the oxide layer.

Within one half of the RC, the residual stresses are assumed to be the sum of a thermo-elastic like problem with zero horizontal displacements on the left boundary (Figure 11a), and a mechanical loading with prescribed horizontal displacements on the same boundary (Figure 11b), such that the sum of the resultant forces vanishes. In both cases, symmetry conditions hold on the right boundary and the above and bottom ones remain stress free. The



Figure 12. The two loading modes of the RC to simulate the bending.

displacement field is denoted \underline{U}^{ch} (the index 'ch' holds for chemical). Without crack, comparing with a complete calculation on a full specimen, this approximation proved to be very good in the active part of the specimen (more precisely, except in a vicinity of the two ends of the specimen).

The effects of bending on the RC are simulated by prescribing a rigid rotation proportional to d/2 on the left boundary (Figure 12a). Within the small strains assumption, it amounts to simply impose

appropriate horizontal displacements, the corresponding displacement field is denoted \underline{U}^{be} ('be' for bending). Due to the lack of vertical symmetry when there is a crack along the symmetry axis, the non-zero resultant force must be balanced by a prescribed horizontal displacement (Figures 11b and 12b). Again, symmetry conditions hold on the right boundary and the above and bottom ones remain stress free.

A multiplier f modulates the results in function of the intensity of the applied bending load so that the elastic solution can be written $f\underline{U}^{be}$. This model was sketched in the study of the formation of crack patterns in functionalized thin films (Leguillon et al., 2014).

Since all the material parameters vary through the thickness of the oxide layer, only a full FE calculation can be used to implement the CC, the asymptotic expansions are out of reach. Let us recall that this criterion requires the two conditions (9) to be fulfilled and this allows determining the a priori unknown initiation length of the crack. To this aim, a crack which length is half the thickness of the specimen is inserted along the symmetry axis of the half RC and this length is varied by buttoning the nodes. At each step, the potential energy $W_{\rm p}(a)$ stored in the structure is computed as a function of the crack length *a*

$$W_{\rm P}(a) = \frac{1}{2} \int_{\rm RC} \underline{\underline{\sigma}} : \left(\underline{\underline{\varepsilon}} - \underline{\underline{\varepsilon}}^{\rm in}\right) dv$$

Where $\underline{\sigma}$ and $\underline{\varepsilon}$ denote respectively the stress and the strain tensor, and where $\underline{\varepsilon}^{in}$ is the inelastic strain caused by the chemical shrinkage. The integral is calculated on the RC. Once all the nodes are buttoned, there is no longer any crack, the tensile stress $\sigma(y)$ along the presupposed crack path (the symmetry axis) is calculated as a function of the depth y. The number of linear systems to be solved thus equals the number of nodes to be buttoned along the virtual crack, there are 50 nodes in the present simulations. Whenever matched asymptotic expansions are available, solving only 2 linear systems is required, one for the so-called outer problem and the other for the inner one (Leguillon, 2002).

5. A first group of numerical results for $t_{ox} = 600$ h and $t_{ox} = 400$ h

Figure 13 show the tensile stresses associated respectively with the chemical shrinkage σ^{ch} and with the 4-point bending test $f\sigma^{be}$ for $t_{ox} = 600$ h. The scaling coefficient f is calculated thanks to the CC at the onset of the first crack.



Figure 13. The elastic tensile stress $f\sigma^{be}$ (solid line) and the residual stress σ^{ch} (dashed line), function of the depth y in the specimen for $t_{ox} = 600$ h. The coefficient f is calculated such that the elastic solution $f\underline{U}^{be}$ corresponds to the onset of the first crack.

As already claimed, the total tensile stress $\sigma = \sigma^{ch} + f\sigma^{be}$ on the outer surface (the sum of the two components in Figure 13) at failure is widely above the tensile strength as a result of applying the CC that is, it must be remembered, a non-local criterion (see Figure 14).



Figure 14. The CC at onset of the first crack for $t_{ox} = 600$ h and d = 12 mm : dimensionless tensile stress $\sigma(a) / \sigma_c(a)$ (solid line), incremental energy release rate $G^{inc}(a) / G_{Ic}(a)$ (dashed line) and energy release rate $G(a) / G_{Ic}(a)$ (dotted line) (dimensionless data).

In Figure 14 the initiation length $a_0 \approx 0.26 \text{ mm}$ derives straightforwardly from the CC (conditions on $\sigma(a_0)/\sigma_c(a_0) \ge 1$ and $G^{\text{inc}}(a_0)/\overline{G}_{\text{Ic}}(a_0) \ge 1$ according to (9)). It is an arrest length because at this point $G(a_0) \approx G_{\text{Ic}}$ and G(y) is a decreasing function.

As previously reported, the toughness $G_{\rm Ic}(a)$ was adjusted in order to match with the experimental observations. In Figure 14, it is such that, at the surface $G_{\rm Ic}(0) = 50 \,\mathrm{J} \,\mathrm{m}^{-2}$, if it is smaller, $G_{\rm Ic}(0) = 25 \,\mathrm{J} \,\mathrm{m}^{-2}$, the load at onset is decreased by 12% and a_0 drops to 0.21 mm; whereas if the toughness is larger, $G_{\rm Ic}(0) = 100 \,\mathrm{J} \,\mathrm{m}^{-2}$, then the load at onset is increased by 17% and a_0 moves to 0.28 mm.

Figure 14 is drawn for d = 12 mm, but among the unknowns is the spacing between cracks. Figure 15 shows the elastic stress $f\sigma^{be}$ at the occurrence of a first crack for different values of the size d of the RC. Obviously, above d/2=6 mm there is no longer any significant variation, the curve starts to increase below this value. The loading being monotonic, this means that the minimum spacing between cracks at the first appearance is around 12 mm. The inner span being 16 mm (Figure 10), a single crack appears first (see also the remark at the end of section 5).

To sum up, this single crack appears for $\sigma = \sigma^{ch} + f \sigma^{be} = 20.9 + 29.4 = 50.3$ MPa, to be compared to 41±7 MPa found in the experiments (Pecora et al., 2016). The prediction is slightly above the measured value, but it is still satisfying given the uncertainties on the fracture parameters of the oxide and the large scattering on the appearance of the cracks. Indeed, it is often observed that the first one does not appear in the active zone of the specimen but under one of the loading pin, due to the stress field induced by complex contact conditions. The followings appear as expected in the active zone.



Figure 15. The elastic tensile stress $f \sigma^{be}$ at the onset of the first crack function of the size d of the RC for $t_{ox} = 600$ h.



Figure 16. (a) The half of the RC used to determine the occurrence of the first crack, (b) the half of the RC used for the analysis of further subdivisions.

After the occurrence of the first crack, when increasing the load, conditions for new subdivisions can be met. To model this mechanism, the RC is modified as shown in Figure 16. A short crack of length a_a is inserted along the left boundary of the RC, thus according to the periodicity conditions the spacing between the new set of cracks is d/2 (Figure 16b), and the analysis (buttoning nodes) is carried out on the crack located as before along the symmetry axis. By reducing at each step the half length d/2 of the RC,

similar RC can be used for successive subdivisions. The results are shown in Table 4 in terms of $f\sigma^{be}$. The displayed values are those which would prevail in the absence of micro-cracking but associated with the current value of f. They are directly proportional to the

applied load and thus can be compared to the values proposed in (Pecora et al., 2016) and calculated from the load at failure using the improved beam theory.

Table 4. Elastic tensile stress	$f \sigma^{ ext{be}}$	at the appearance of	the successive	cracks for t_{ox}	=600 h.
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	First crack	First sub.	Second sub.	Third sub.
$f\sigma^{\rm be}$ (MPa)	29.4	31.9	34.1	46.5
Resulting crack spacing (mm)	12	6	3	1.5

It is then possible to compare the predicted number of cracks according to the above procedure with the number of cracks experimentally observed (Figure 17). To this aim, the elastic strain ε was extracted from the FE computations parallel to the tensile stress σ^{be} .



Figure 17. Comparison between predicted (CC, solid line) and experimental (symbols) number of cracks function of the elastic strain ε for $t_{ox} = 600$ h.

The good agreement between predictions and experimental data is quite encouraging. A large part of the observed gap could be attributed to the variability of the fracture parameters according to the Weibull statistics. Note that the final failure is difficult to predict because it

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should be necessary to take into account the simultaneous growth of all the cracks when the load increases, and this is not easily allowed by the current computations based on the RC. The last point of the solid line in Figure 17 is estimated from the growth of a single crack, it necessarily underestimate the actual value, since additional cracks tend to shield the primary one. An explanation will be given further in Section 6 on the arrest lengths, if any. Indeed, at this stage, the model does not control the growth of existing cracks. This could be partially improved assuming they all have the same length and they grow in the same way, which makes it possible to use the periodic pattern.

For $t_{ox} = 400$ h, an analogous reasoning leads to similar results, although with a somewhat less good agreement with the experiments which seem however to be a little more scattered and less consistent (Figure 18). The first crack is found to appear for $\sigma = \sigma^{ch} + f \sigma^{be} = 10.1 + 40.5 = 50.6$ MPa and the arrest length is $a_a \approx 0.35$ mm.



Figure 18. Comparison between predicted (solid line, CC) and experimental (diamonds) number of cracks function of the elastic strain ε for $t_{ox} = 400$ h.

The choice of the onset of the first crack for d/2=6 mm may seem arbitrary because the curve in Figure 15 is very slowly growing between d/2=6 mm and d/2=3 mm but in the end if one chooses d/2=3 mm instead of 6 mm then 2 or 3 cracks may simultaneously appear and the final result in Figures 17 and 18 does not hardly change.

6. A second group of numerical results for $t_{ox} = 200$ h and $t_{ox} = 0$ h



Figure 19. Definition of the bounds a_a and a_A of the crack arrest lengths.

Before going further in the presentation of the results, a few words must be added on the definition of the crack arrest lengths. Let us assume that, there is a new crack of length a_0 , as predicted by the CC. Often at this point $G > G_{Ic}$ (Figure 19), then, according to the Griffith criterion, the crack goes on growing in an unstable manner.

Usually, the arrest length a_a , if any, is defined by: $G(a_a) = G_{lc}$ and G(a) is a decreasing function (for the sake of simplicity, in a first step G_{lc} is assumed constant). But obviously, at this point there is an excess energy corresponding to surface 1 (Figure 19). In an elastic body this excess energy can be dispersed by kinetic energy, acoustic waves... However, a part or the whole excess energy can also be dissipated in fracture (surface 2 in Figure 19), then a_A is defined by

 $\int_{a_0}^{a_{\rm A}} \left(G(y) - G_{\rm Ic} \right) \mathrm{d}y = 0 \iff G^{\rm inc}(a_{\rm A}) = G_{\rm Ic}$

The two lengths a_a and a_A define respectively a lower and an upper bound of the crack arrest lengths. This property holds also true if $G_{\rm Ic}$ varies with the depth y, replacing $G_{\rm Ic}$ with $\overline{G}_{\rm Ic}(a_{\rm A})$

$$\int_{a_0}^{a_A} (G(y) - G_{Ic}(y)) dy = 0 \iff G^{inc}(a_A) = \overline{G}_{Ic}(a_A)$$

It can be observed in Figure 14 that the two arrest lengths a_a and a_A (i.e. the two bounds) merge since $a_0 = a_a = a_A$.

For $t_{ox} = 200$ h (Figure 20) and $t_{ox} = 0$ h (Figure 21), arrest lengths a_a and a_A are out of the framework of the figures limited to a depth y = 1 mm. This can be interpreted in both case as an abrupt failure.



Figure 20. The CC at failure for $t_{ox} = 200$ h and d = 12 mm: tensile stress $\sigma(a) / \sigma_c$ (solid line), incremental energy release rate $G^{inc}(a) / G_{Ic}$ (dashed line), energy release rate $G(a) / G_{Ic}$ (dotted line) (dimensionless data).



Figure 21. The CC at failure for $t_{ox} = 0$ h and d = 12 mm: tensile stress $\sigma(a) / \sigma_c$ (solid line), incremental energy release rate $G^{inc}(a) / G_{Ic}$ (dashed line), energy release rate $G(a) / G_{Ic}$ (dotted line) (dimensionless data).

The limit of the abrupt failure is between $t_{ox} = 300$ h and $t_{ox} = 350$ h. This does not mean that multi-cracking occurs above this limit, but that the new crack is arrested until the applied load increases ($a_a = 0.56$ mm, $a_A = 0.66$ mm for $t_{ox} = 350$ h, Figure 22) leading further either to an abrupt failure or to multi-cracking.





Figure 22. The CC at failure for $t_{ox} = 350$ h and d = 12 mm: tensile stress $\sigma(a) / \sigma_c$ (solid line), incremental energy release rate $G^{inc}(a) / G_{Ic}$ (dashed line), energy release rate $G(a) / G_{Ic}$ (dotted line) (dimensionless data). The initiation length a_0 and the two bounds a_a and a_A of the arrest length are distinct.

It must be noted that it is ambiguous to plot such curves (Figures 14, 20 and 21) for larger cracks because the kinematic model of bending illustrated in Figure 12 is less and less adequate for longer cracks.

7. A full FE simulation of the 4-point bending test

Predicting the nucleation of the first crack, leading to an abrupt failure or not, can also be done by performing an exact simulation of the 4-point bending test (Figure 3) and applying the CC to the entire structure as done for instance in (Leguillon et al., 2015b). A summary of the results is proposed in the following Table 5.

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Table 5. Summary of strain ε and tensile stresses σ^{C} and σ on the surface in tension during the 4-point bending loading, at onset of the first crack for different oxidation time t_{ox} , as predicted by the CC using the periodic pattern (Per.) and a full FE simulation of the 4-point bending test (FE). Comparison with data and experimental measures (Pecora et al., 2016).

$t_{\rm ox}$ (h)	0	200	400	600
\mathcal{E} (%) per.	2.5	1.5	0.8	0.6
ε (%) f 4-p	2.5	1.3	0.9	0.8
$\sigma^{ ext{ch}}$ (MPa)	0	5.0	10.1	20.1
σ (MPa) Per.	100.6	70.7	50.5	50.7
σ (MPa) FE	100.3	72.7	56.2	62.9
σ^{exp} (MPa)	153 # 189 ± 6	50 ± 4	35 ± 3	41 ± 7

Experimental values are obtained from the measured load at failure using an improved beam model (Pecora, 2014; Pecora et al., 2016). In the first row $t_{ox} = 0$ h, σ^{exp} in bold corresponds to the flexural strength found in the manufacturer data sheet, the experimental measure is beside. If we take into account the experimental dispersion, the last σ^{exp} data (3rd and 4th rows) seems to converge to the same value.

To complete this analysis, it would be difficult to envisage the successive divisions leading to a significant numbers of new micro-cracks whose growth must be analyzed separately. However this could still be addressed, at a considerable numerical effort, as shown in (Li and Leguillon, 2016).

8. Conclusion

It is difficult to get values of the mechanical parameters: Young's modulus, Poisson's ratio, toughness and tensile strength, in the oxidized layer of a polymer sheet. Reliable values of the Young modulus can be obtained from indentation tests in the thickness for different ageing conditions. Poisson's ratio does not pose a major problem, its influence is small and it can be considered as constant through the thickness for any ageing condition. Unfortunately, it is also necessary to have accurate values of the toughness and the tensile strength to predict the onset of cracks on the surface and their growth in the layer using the CC (note that the same problem arises using CZM). Some flexural strength, or at least the state of stress prevailing on

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the surface at the instant of crack nucleation, can be derived from an improved beam theory, for different ageing conditions. But this does not provide much information on how this parameter varies in the thickness of the oxide layer. In addition, there is absolutely no information on the way the toughness changes, both through the thickness and for different oxidation time. The only available qualitative remark is that the oxide is more brittle.

Despite these partial data, we attempted to develop a model for predicting the formation of crack patterns on the surface of oxidized polymer specimens subjected to a 4-point bending loading. It is based on the Finite fracture Mechanics concept and the CC. In agreement with the experiments, this model has allowed predicting that the samples break abruptly for low oxidation times (i.e. $t_{ox} \leq 350$ h). For longer oxidation time, multi-cracking appears on the surface of the specimen and the model describing the number of cracks as a function of the applied load is quite encouraging. This is especially true, considering the wide scattering existing first when determining experimentally the onset of the first micro-crack, and then when counting the number of these small cracks.

There is an approximate agreement between the measured strains and stresses and the calculated ones. Indeed, the trends are the same and the orders of magnitude are well met but it is difficult to go into more details. Once again, the uncertainties on the data can be invoked. Moreover, the theoretical model based on computations performed on a simple RC is well suited to the simulation of multi-cracking but remains an approximate model with its own weaknesses. In particular, the quality seems to degrade for high oxidation times, i.e. for thick oxide layers and strongly changed Young's modulus. This is due to the fact that in the RC model cross sections are supposed to keep straight (the only assumption that agrees with the periodicity hypothesis) which is not entirely accurate, warping may be due to the varying value of the Young modulus in the oxide layer and to the presence of cracks that disturb the horizontal symmetry. Indeed such periodic conditions agree with an infinitely long structure made of an indefinite repetition of the RC.

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