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Mimicry refinement: Phenotypic variations tracking the local optimum

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Summary

1. Müllerian mimicry between chemically defended preys is a textbook example of natural selection favouring phenotypic convergence onto a shared warning signal. Studies of mimicry have concentrated on deciphering the ecological and genetic underpinnings of dramatic switches in mimicry association, producing a well-known

mosaic distribution of mimicry patterns across geography. However, little is known about the accuracy of resemblance between natural co-mimics when the local phenotypic optimum varies.

2. In this study, using analyses of wing shape, pattern and hue, we quantify multimodal phenotypic similarity between butterfly co-mimics sharing the so-called postman pattern in different localities with varying species composition.
3. We show that subtle but consistent variation between populations of the localised species, *Heliconius timareta thelxinoe*, enhance resemblance to the abundant co-mimics which drive the mimicry in each locality.
4. Those results suggest that rarer co-mimics track the changes in the phenotypic optimum caused by gradual changes in the composition of the mimicry community, providing insights into the process by which intra-specific diversity of mimetic pattern may arise. Furthermore, our results suggest a multimodal evolution of similarity, with coordinated convergence in different features of the phenotype such as wing outline, pattern and hue.
5. Finally, multilocus genotyping allows estimating local hybridization rates between *H. timareta* and co-mimic *H. melpomene* in different populations, raising the hypothesis that mimicry refinement between closely-related co-mimics may be enhanced by adaptive introgression at loci modifying the accuracy of resemblance.

Introduction

Chemically-defended animal species often show striking convergence in their colour patterns with other prey coexisting in the same habitat. This convergence may be explained, since the work of Müller (1879), by natural selection favouring superficial resemblance, and operated by visual predators, a phenomenon called Müllerian mimicry. Theory proposes that predators learn upon experience the association of prey distastefulness and prey visual appearance, generally distinctive warning patterns. Mimicking a locally abundant warning signal, well known by local predators, constitutes a benefit to a defended prey species by decreasing predation risk. Mimicry benefits associated with a given warning signal depend on the relative numbers of prey sampled vs. available to learning predators, and are usually driven by the most toxic or the most abundant prey species (Mallet & Joron 1999).

Müller's general principle has been largely supported by theoretical models and empirical experiments (Turner 1977; Sheppard *et al.* 1985; Turner 1987; Ruxton, Sherratt & Speed 2004). Field transplant experiments have confirmed selection favouring local patterns (Mallet & Barton 1989; Kapan 2001; Chouteau & Angers 2011; Merrill *et al.* 2012) and the strong frequency-dependent selection acting on warning signals in diverse communities (Chouteau, Arias & Joron 2016). Natural selection for local mimicry explains local polymorphism of distinct colour patterns (Kapan 2001; Joron & Iwasa 2005), as well as the maintenance of geographical races with sharply distinct patterns, for instance the so-called postman vs. rayed patterns of *Heliconius erato* and *H. melpomene* (Mallet & Barton 1989). Most of those studies investigated the mimicry benefits associated with alternative warning strategies using completely distinct patterns, corresponding to mimetic optima and describing an adaptive landscape with adaptive peaks separated by valleys of low fitness (Leimar & Mallet 2012). However, for a given morph, variations may be found between individuals, between sexes and

between localities. Fewer studies have addressed the significance of mimicry variation around a given adaptive peak, or the underpinnings of precise resemblance within a given mimicry ring. Mimetic communities often involve assemblages of species which differ between localities, and species indeed vary in the level of mimicry precision to others (Penney *et al.* 2012), but it is unclear what determines the level of mimicry accuracy in those communities or to which extent the mimicry optimum may vary through space or time.

The ability of predators to generalize the signals of defended prey is an important determinant of selection on resemblance in a mimicry system (Rowe, Lindstrom & Lyytinen 2004; Ihalainen *et al.* 2012). Sharing key components of a warning signal with co-mimics can sometimes enhance protection and may allow crossing a valley of low fitness (Beatty, Beirinckx & Sherratt 2004; Balogh & Leimar 2010). For instance, jacamars trained to avoid butterflies with an orange patch were less likely to attack butterflies with a similar pattern painted red than those painted black (Langham 2004), suggesting that a red patch may be sufficient to reduce predation regardless of the differences in hue. Nevertheless, in that example red butterflies still received higher predation than orange controls (Langham 2004), suggesting that small deviations of colour hue are, to a certain extent, perceived by predators and translate into fitness differences. Increased predation against imperfect mimics has also been shown in lab experiments (Ihalainen *et al.* 2008), meaning that even if coarse resemblance is attained, selection may still favour the improvement of mimicry. Those findings support the classical scenario for the evolution of mimicry, first through a major phenotypic change allowing coarse resemblance for certain key warning feature, followed by the gradual improvement of mimicry under selection by narrowly generalizing predators (Sheppard *et al.* 1985; Turner 1987; Franks & Sherratt 2007; Balogh & Leimar 2010; Leimar & Mallet 2012).

96

97 The strength of selection for resemblance is affected by the complexity and diversity of the
98 prey community. For instance, discrimination against imperfect mimics is less accurate when
99 the community of prey is complex, i.e. composed of several distinct warning signals
100 (Ihalainen *et al.* 2012). However, whether variations of pattern within a mimicry ring itself
101 affect the intensity of selection for resemblance has rarely been tested, since experimental
102 predators usually are only trained on a single prey type. Quantifying variations in resemblance
103 of wild individuals within and between species of a given mimicry ring allows investigating if
104 and how the accuracy of resemblance evolves.

105

106 Phenotypic similarity is influenced not only by natural selection favouring accurate mimicry
107 but also by the genetic architecture underlying variation in phenotype. For instance,
108 phenotypic variation remaining within the generalization range of predators might be little
109 influenced by mimicry selection and more by genetic correlations or environmental trade-offs.
110 Drift, mutations, environmental plasticity or hybridization are different sources of variation
111 which can affect the accuracy of similarity and dissimilarity of phenotypes within and
112 between species of the mimicry ring. In addition, specific genetic architectures can favour
113 convergence and a good level of resemblance. In *Heliconius* butterflies, variations in mimetic
114 colour patterns are largely controlled by a few Mendelian loci of large effect, often coined the
115 “colour pattern toolbox”, an architecture which may facilitate secondary convergence in wing
116 patterns (Reed *et al.* 2011). The most striking example of mimicry achieved through a shared
117 architecture is when alleles at colour-patterning loci are shared among co-mimics via adaptive
118 introgression. This was documented, for instance, in the pair of species *H. timareta* and *H.*
119 *melpomene* (Heliconius Genome Consortium 2012; Pardo-Diaz *et al.* 2012). In this case,
120 colour pattern resemblance reflects the shared origin of adaptive alleles in both species, but

selection for mimicry may also play a role, first by facilitating the invasion of introgressed alleles in the receiving population, and second by favouring further refinement of resemblance in the new genome. Describing variations in resemblance between species is therefore required to disentangle the relative importance of shared genetics and mimicry selection in the evolution of accurate resemblance.

In this study, we investigate selection for mimicry perfection by quantifying phenotypic similarity among multiple species forming the so-called “postman” mimicry ring in Northern Peru.

The “postman” wing pattern is a very strong warning signal working as a major (and possibly ancient) mimicry attractor in this region (Hines *et al.* 2011). However, subtle geographic variation in colour pattern was reported for one of the co-mimics (*Heliconius timareta thelxinoe*), between localities separated by about 175 km (Mérot *et al.* 2013). The two localities display some differences in the assemblage of species participating in the postman mimicry. In the Alto Mayo, *H. timareta thelxinoe* co-occurs mostly with *H. telesiphe* while, in the Cordillera Escalera, the ‘postman’ community is dominated by *H. erato favorinus* and *H. melpomene amaryllis* (Fig.1). Theoretical simulations suggest that the most abundant species of a mimicry ring generally drives the evolution of phenotypic resemblance in other species (Turner 1977; Mallet 1999; Franks & Sherratt 2007; Ruxton *et al.* 2008). We therefore hypothesise that the subtle variation in colour pattern found in certain species participating in the mimicry ring might be the footprint of selection for different mimetic optima, reflecting spatial changes in the phenotypic composition of the different communities.

To test whether the local mimetic community may influence the strength and the nature of selection for mimicry, we investigate whether geographic variations for various modalities of the warning signals (colour pattern, reflectance of the colour patch, wing shape) within participating species appear to track variations in composition of the mimetic community. We use Colour Pattern Modelling (Le Poul *et al.* 2014), geometric morphometrics, and spectral colour measurements to quantify phenotypic similarity between co-mimics, and analyse it in the light of neutral molecular variation, hybridization rates, and species composition in the distinct communities.

Methods

Species studied, specimen collection and density.

The four species of the “postman” mimicry ring (Fig.1, *H. melpomene amaryllis* Feder & Feder, *H. timareta thelxinoe* Lamas & Mérot, *H. erato favorinus* Hopffer and *H. telesiphe* Doubleday, further abbreviated with their species name only) were sampled in two tropical montane areas separated by 175km, the Escalera and the Alto Mayo (San Martín, Peru). Sampling localities were chosen along an altitudinal continuum, which ranges from 400m to 1300m in the Escalera (“E”, 06°27’28”S; 76°17’53”W) and from 1100m to 1800m in the Alto Mayo (“A”, 05°39’58”S; 77°44’35”W).

To estimate the relative frequencies of each species, we used collection data corrected by the number of collecting days. On collecting days, all butterflies from the four species encountered were caught with entomological nets. A subset of this sample was used for genetic and phenotypic analysis (Table.S1&S2). We considered two populations of *H. melpomene* in the Escalera (“Low E”, below 1000m; and “Escalera”, above 1000m, sympatric with *H. timareta*). We also included an additional population of *H. melpomene* from

Moyobamba (06°05'13"S; 76°59'36"W, Peru) to investigate geographic variation in *H. melpomene* between area of sympatry and allopatry with *H. timareta*.

Phenotypic description and analyses

Data acquisition

Images of ventral (v) and dorsal (d) forewings (FW) and hindwings (HW) were captured in normalized light conditions (CIE Standard Illuminant D50) using a Nikon D90 digital camera with a Nikon micro 105/2.8GEDVR lens.

Measurements of wing reflectance were done with a spectrometer (AvaSpec-3648, Avantes) and a deuterium-halogen light source (DH-200, Avantes) connected to a 1.5mm diameter sensor (FCR-7UV200-2-1.5x100, Avantes) inserted in a miniature black chamber (an opaque black plastic tube surrounding the reflectance probe to exclude ambient light from the measurement). Reflectance spectra were taken at 90° incidence relative to a 99% reflectance standard (300-700nm spectralon) and to dark current. Spectra were recorded with the software Avasoft 7.0 using an average of 5 measures with an integration time of 23 ms. On all wing surface (FWv, FWd, HWv, HWd), we recorded reflectance of colour patches and black area at the same location for each specimen.

Wing colour pattern

Colour pattern was analysed using Colour Pattern Modelling (Le Poul *et al.* 2014) which allows quantifying colour pattern variation and similarity across the entire wing. Detailed methods are given in supplementary material. Briefly, wing outline was extracted individually from the background. Within this area, the RGB colours are categorized into three colour classes (black, red or yellow). We called “yellow” the bar on all species hindwing so that pattern itself would be comparable, despite some hue variation between species and between

individuals of different ages or wear. All individual wings were aligned by rotation, translation, scaling and normalization based on an iterative process. Variations in patch boundaries can then be fully described and compared between individuals.

Each wing surface (FWd, FWv, HWd, HWv), was characterized by a set of pixels with homologous position across specimens. Each pixel was associated with three presence/absence binary values for black, red and yellow, which allows colours to be treated separately. Variations in patch boundaries were then analysed for each surface separately with a principal component analysis applied to the set of pixels. The resulting components describe a morphological space used for subsequent analyses after the dimensionality reduction proposed by Baylac and Friess (2005).

Small colour elements located in the basal part of the wing were scored following Mérot *et al.* (2013) with an index describing variation at two qualitative characters: the red line on the ventral forewing (0=absent to 5=a well-marked line, Fig.S1a) and the extension and the number of basal red spots on the ventral hindwing (0=no dots to 5=large spots, Fig.S1b).

Wing outline

Wing outline, extracted and aligned through the first step CPM procedure, was further analysed with elliptical Fourier analysis using custom scripts developed in Matlab (Jones *et al.* 2013), following the directions of (Neto & Samal 2006). A PCA was applied to the first twenty Fourier harmonics and allowed describing a morphological space for wing outline.

Wing venation: analysis by geometric morphometrics

Wing venation was described using 15 (FW) and 14 (HW) landmarks, placed at vein intersections and vein termini on the ventral side, as described in Mérot *et al.* (2013). Standard tests of repeatability were done by taking the landmarks five times per wing on subsamples of five butterflies from a single species, population and sex. Landmark coordinates were digitalized using TpsDig2 (Rohlf 2010) and superimposed using a general Procrustes analysis (Bookstein 1991; Zelditch *et al.* 2004). For each set of landmarks, superposition includes all samples in a multidimensional Procrustes space whose tangent space is a Euclidian morphological space for wing venation. A principal component analysis was applied on this wing venation data followed by the dimensionality reduction proposed by Baylac and Friess (2005). Wing size was measured using log-transformed centroid size (Bookstein 1991).

Colour spectra and visual models

Colour spectra were analysed using Avicol V.6 (Gomez 2006). Colour spectra obtained between 300 and 700 nm were smoothed using a local Fourier correction at 650 nm (Fig.S5&S7). A mean colour spectrum was calculated for each colour patch of each individual by averaging measurements on the left and the right wing. Each kind of colour patch was further analysed separately.

Analyses of spectra were carried out using models of animal vision, which take into account the observer's vision and the illuminating light. Each photoreceptor is characterized by a sensitivity function which determines the wavelength of reflected light perceived by the eye. Analyses in the main text are with a tetrachromatic V-type bird visual system (Peafowl, *Pavo cristatus*, (Hart 2002)) and a light environment corresponding to large sunny gaps in a tropical

forest (Théry, Pincebourde & Feer 2008). Analysis with other visual system and other incident lights gave consistent results and are presented in supplementary materials (Fig.S9). A physiological model of Endler and Mielke (2005) was applied to visualize colour distribution in an unconstrained space, a tetrahedron whose vertices corresponds to the four photoreceptors (Fig.S6). Within this colour space, the relative location of each individual's patch colour can be compared and the overlap between two clouds of points (Table.S6) can be calculated. Relative excitation of each photoreceptor were treated as multivariate data and analysed with PCA analyses.

Statistical analysis

Within each species, differences in colour pattern, colour spectra, wing outline and venation between geographic populations were tested by a one-way MANOVA on each subset of PCs with geographic origin as a factor. Then, within each species and for each trait, we tested discrimination between groups defined by geographical populations with a linear discriminant analysis. We compared the cross-validation values to discrimination between simulated populations of similar size following the methods described in Evin *et al.* (2013).

Phenotypic similarity between each species and each population of *H. timareta* was quantified with several methods within each morphological space. First, to measure the magnitude of phenotypic similarity between individuals, Euclidian distances in the morphological space were computed between all pairs of specimens. For colour spectra, we used perceptual chromatic distances between all pairs of specimen, expressed in JNDs (just noticeable differences) in a perception model of Vorobyev and Osorio (1998). This model takes into account the noise due to errors in photoreceptor response and estimates more accurately whether the discriminability between colours could really be perceived by predators.

Perceptual and Euclidian distances between a mimic and each population of *H. timareta* (Alto Mayo vs. Escalera) were analysed with a mixed model with geographic population as factor and identity of the compared specimen as random factors. Second, to compute an indicator of similarity between groups, Mahalanobis distances were calculated between the three species and the two populations of *H. timareta*. Contrary to Euclidian distances, this measure applies in a transformed space and is scaled by intra-group variation. Third, to confirm our similarity estimates, we calculated an index of cross-classification by performing a linear discriminant analysis on a subset of two groups (for example, *H. melpomene*/*H. timareta* (A); *H. melpomene*/*H. timareta* (E)). Since the latter two analyses are sensitive to unbalanced sample sizes (Kovarovic 2011), we performed them on subsets of similar sizes, by randomly drawing 30 specimens from each group, repeating the procedure 1000 times and averaging over the repetitions.

All analyses were performed in R 3.0.3. (R Core Team 2014) using the packages *ade4* , *nlme* , *Mass* and *Rmorph* (Baylac 2012).

Multilocus microsatellite analysis

The multilocus microsatellite genotype, performed on *H. melpomene* and *H. timareta*, is based on 11 loci, and is an extension of the genotyping performed in Mérot et al (2013) with the addition of 31 *H. melpomene amaryllis* and 69 *H. timareta thelxinoe*. Detailed methods can be found in supplementary materials; genetic diversity and statistics in Table.S3. F-statistics were calculated using GENETIX 4.05 (Belkhir *et al.* 1996-2004). We used STRUCTURE (Pritchard, Stevens & Donnelly 2000), a multilocus Bayesian clustering method, to determine population structure, to confirm the assignment of individuals to species, and to detect admixed genotypes. STRUCTURE was run with 500,000 updates of the Markov chain after

an initial burn-in of 50,000 updates, to achieve chain convergence for a set of models with different numbers of clusters ($K=1-6$). Since *H. melpomene* and *H. timareta* can hybridize and disperse, we used the ‘admixture model’ and ‘correlated allele frequencies’. The most likely K was chosen using the maximum likelihood value in STRUCTURE and the ΔK -method (Evanno, Regnaut & Goudet 2005) and then evaluated following recommendations from STRUCTURE documentation. Over the entire set of specimens included, the likelihood reaches a maximum plateau between $K=2$ and $K=3$. When $K=2$, the two clusters correspond to the two species (identified phenotypically), so $K=2$ bears a clear biological meaning and was retained. $K=3$ further splits *H. timareta* into two clusters with no obvious association with biological variables (such as geographic populations), nor with any identifiable experimental bias. Further STRUCTURE analyses run on each species separately support the absence of intraspecific clustering. Posterior probabilities of being member of a cluster were estimated and allowed detecting potential hybrids. Hybrid detection was also run separately with NewHybrids 1.0 (Anderson & Thompson 2002). Relying on the results from simulated hybrids (Mérot et al. 2013) and hybrids from controlled crosses (Mérot et al. 2015), individuals were considered as “pure” if the posterior probability was above 0.9 in STRUCTURE and above 0.7 in NewHybrids.

Results

Geographical variation within species

Populations of *H. timareta* from the Escalera and the Alto Mayo exhibit significant differences in colour spectra, pattern, wing outline and venation (Table.1). This result was consistent whether males and females were treated together or separately. A linear discriminant analysis on *H. timareta* allows discriminating the two populations, with a low level of misclassifications, better than the range of mis-classification obtained from randomly

simulated population (Table.1). Centroid sizes did not exhibit significant differences between the two populations of *H. timareta* (ANOVA FW $p=0.12$, HW $p=0.77$).

Within *H. melpomene* and within *H. erato*, neither colour spectra, wing outline nor size displayed any significant geographical phenotypic variations (Table.S4&S5). For pattern and venation, slightly significant differences were observed between populations of *H. melpomene* and *H. erato*. However, discrimination between geographic populations reaches 41-71% of misclassifications, which is within the misclassification range from randomly simulated populations of similar sample size.

Relative frequency of postman co-mimics

The Escalera and the Alto Mayo areas display differences in their geography and topography, their community composition and the altitudinal ranges of local species (Fig.1C). The Escalera is a relatively thin, mid-elevation Eastern cordillera jutting from adjacent Amazonian lowlands. On its slopes below 1000m, *H. erato* and *H. melpomene* are the only species with a postman pattern and are generally very abundant, at our collection places and elsewhere in the foothills (>200 specimen of each species in 65 days, approximately 1:1 ratio, Table.S2). In the highest areas, between 1000 and 1300m, *H. erato* becomes less abundant while *H. melpomene* co-occurs with *H. timareta*. The Escalera is the southernmost tip of the known distribution of *H. timareta* and the latter can be as abundant as *H. melpomene*, but only locally, as observed at our collection places (1:1 ratio, Table.S2). At a finer scale, *H. timareta* gradually increases in frequency relative to *H. melpomene* (Fig.1C). Despite intensive collection (83 days, Table.S2), only two specimens of *H. telesiphe* were found in the Escalera, and only at the highest collection station (1300m).

The Alto Mayo represents a wider, higher and more continuous area of montane forest surrounded by Andean areas. There, *H. melpomene* and *H. timareta* display less overlap since the transition is more abrupt and occurs at higher elevation (1300m, Fig.1C). *H. timareta* was never found below 1200m and was locally abundant at one collection station (1400-1600m). Over 1300m, *H. telesiphe* is an abundant species in the Alto Mayo and the commonest postman-patterned species. *H. erato* was not found in our standardized collection stations of the Alto Mayo although it is occasional up to 1200m, and thus parapatric with *H. timareta*.

Variation in wing phenotype in the postman mimetic community

Wing colour pattern

For forewing colour pattern, the first axis of the PCA (Fig.2a) displays variation from the large rounded red patch of *H. erato* and *H. melpomene*, to the dislocated, slender patches *H. telesiphe*. *H. timareta* is intermediate on this axis with the Escalera population closer to *H. melpomene* and *H. erato*. *H. telesiphe* is sitting in a quite distant position overall, because it exhibits a small additional subapical red patch on the forewing, missing in all other species. Nevertheless, the Alto Mayo population of *H. timareta* is the closest population to *H. telesiphe* in the colour pattern space because of its somewhat dislocated, zigzagging red patch shape, reminiscent of the main red patch of *H. telesiphe*.

On the hindwing, all four species display a yellow/white pattern barring both sides of the hindwing longitudinally. The first PC shows variation in the width of the bar. *H. melpomene* and *H. erato* have a rather wide and long yellow bar while *H. telesiphe* has a thinner and shorter bar (Fig.2b). Again, *H. timareta* appears in intermediate position along this direction of variation, with the Escalera population having a wide yellow bar like *H. melpomene*, while Alto Mayo populations show a thinner bar like *H. telesiphe*. The second PC shows a

continuous gradient from a long and pointed bar seen in *H. erato* to the thin bar characteristic of *H. timareta* from the Alto Mayo, straight and wide in the proximal part and curved posteriorly in the distal part. *H. melpomene* and *H. timareta* from the Escalera sit in an intermediate position.

Results were consistent on the ventral colour pattern (Fig.S2) and whether males and females were treated together or separately (Fig.S3).

Small elements of pattern (Fig.S1)

All specimens of *H. telesiphe* exhibit bright and large red spots on the ventral hindwing and a well-marked red line on the ventral forewing (index=5). By contrast, *H. erato* nearly never displays red dots or lines except in a few specimens (4-18%, depending on population) that possess small faded spots or a slight line (index=0-1). Along this gradient between *H. erato* and *H. telesiphe*, most *H. melpomene* samples are closer to the *H. erato* phenotype, with no red line (89-100% depending on the population) and small faded spots (89-96%). Then, 45 to 47% of *H. timareta* samples from the Escalera exhibit small red spots (index=2-3) and no or a tiny red line (index=0-3), making them closer to the *H. erato* and *H. melpomene* phenotypes. On the contrary, a well-marked red line and large red dots (index=4-5) are observed in more than 93% of *H. timareta* samples from the Alto Mayo (vs. only 53-55% from the Escalera population).

Wing venation and outline

For forewing shape, results were congruent whether described by venation or by wing outline. For both venation and outline, the first PCs display continuous variations from the rather rounded forewings (Fig.3ac) of *H. melpomene*, shared by *H. timareta* from the Escalera,

towards the thinner and more elongated wings of *H. telesiphe*. By contrast, *H. timareta* from the Alto Mayo display resemblance to *H. telesiphe* through its more elongated wing shape. In the venation analysis, which takes into account the discal cell and the distal veins, the second PC recapitulates phylogenetic relationships, separating *H. erato* and *H. telesiphe* from *H. melpomene* and *H. timareta*.

For the hindwing shape, the first PCs of both the venation and outline analysis are mostly associated with sexual dimorphism (presence/absence of male androconia), but the second PCs display the same variation as the forewing, from the rounded wings of *H. melpomene* to the thin, elongated wings of *H. telesiphe* (Fig.3bd). Both *H. timareta* populations are in intermediate position.

Colour spectra

For both forewing and hindwing, the reflectance of colour patches also follows a continuum between the four species from *H. erato* and *H. melpomene* to *H. telesiphe* (Fig.4). The two populations of *H. timareta* occupy different positions along this continuum in the colour space. On the one hand, the Escalera population displays similar colours to *H. melpomene* and *H. erato* (red-orange and bright yellow), with which it overlaps in the three-dimensional colour space (Fig.S6, Table.S6). On the other hand, the position of *H. timareta* from the Alto Mayo comes closer to *H. telesiphe* for the red forewing patches (with a deeper red) and, to a lesser extent, for the whitish hindwing patch.

It is notable that colours are generally lighter on the ventral side than on the dorsal side and exhibit more intra- and inter-specific variability. On the ventral side, both red and yellow patches of *H. timareta* and *H. telesiphe* reflect more short-wavelengths and UV than *H. erato*

and *H. melpomene*. The higher variability in colour on the ventral side is also shown by the analyses of perceptual distances, since discrimination was higher for the ventral side than for the dorsal side. On the ventral side, visual contrast within species was smaller than between species, for both red and yellow and reaches 2 to 6 JND (Fig.5ij). On the dorsal side, within species and between species visual distances spanned a similar range (2 JND, Fig.5gh), except between *H. telesiphe* and all others for the white dorsal hindwing patch.

Similarities in wing phenotype in the postman mimetic community

For forewing and hindwing colour patterns, forewing shape and hue of all patches, resemblance indicators suggest that the Escalera population of *H. timareta* is more similar to the most abundant local co-mimics of the Escalera (*H. erato*, *H. melpomene*) than the Alto Mayo population is. Euclidian and perceptual distances as well as Mahalanobis distances between *H. timareta* and *H. erato* or *H. melpomene* are smaller for the Escalera population than for the Alto Mayo population (Table.S7, Fig.5). The reverse was found for distances with *H. telesiphe*, suggesting that the Alto Mayo population of *H. timareta* is more similar to *H. telesiphe* than the Escalera population is. Those results are supported by the differences in cross-classification rates from the discriminant analysis (Table.S8). Results were consistent for males and females taken independently and together.

For hindwing shape, similarity estimates do not show any consistent trend differentiating the two geographic populations of *H. timareta*.

Genetic divergence and population structure

No genetic differentiation was found between the two geographic populations of *H. timareta*. The F_{ST} value over all loci was estimated at 0.025 and the two populations do not split into

different genetic clusters. For *H. melpomene*, no genetic differentiation was found either, F_{ST} reaches only 0.009 between the four populations and they do not display any genetic clustering.

Genetic differentiation between *H. melpomene* and *H. timareta* was significant in the two geographic areas and of similar magnitude (A: $F_{ST}=0.148$; E: $F_{ST}=0.157$).

Hybrid detection

The level of admixture follows the expected trend, with slightly higher rates in the Escalera, where *H. timareta* and *H. melpomene* populations show more altitudinal overlap and are the most phenotypically similar. However, this difference was not significant, possibly due to our limited samples sizes (test of equal proportions: $p=0.67$).

Bayesian clustering analyses with STRUCTURE detected 4.2% of admixed individuals in the Escalera (Fig.S11, 2 back-crosses to *melpomene*, 2 back-crosses to *timareta* and 3 F1 hybrids out of 167 specimens), and 3.2% in the Alto Mayo (1 back-cross to *melpomene*, 1 F1 or back-cross to *timareta* out of 63 specimens). Surprisingly, given that *H. timareta* does not occur below 1000m, one admixed specimen was detected in the low Escalera population at about 700m of elevation. Assignment tests with New Hybrids1.0 found the same admixed individuals except in one case, but also pointed out six more putative back-crosses, raising the proportion of admixed individuals to 8.7% in the Escalera and 6.3% in the Alto Mayo.

Discussion

Tracking variations in the local prey environment

Our results show that despite an absence of genetic differentiation at neutral markers, geographic populations in one of the species, *H. timareta*, display subtle but consistent variations in wing phenotype, associated with enhanced similarity to locally abundant co-mimics. Our results therefore denote a geographic shift in mimicry association consistent with quantitative changes in the composition of the mimicry community.

Geographic mosaics of co-varying warning pattern are commonly observed in animal clades involved in mimicry associations, from butterflies to frogs (Thompson 2005; Twomey *et al.* 2013). An iconic case is the faithful co-variation of *Heliconius melpomene* and *H. erato* throughout their shared range, the two butterflies switching in concert from red postman pattern (in certain Andean valleys, south-eastern Brazil, and Caribbean area) to orange-rayed Amazonian patterns (Sheppard *et al.* 1985; Reed *et al.* 2011). Our results suggest that co-mimetic species not only exhibit adaptive shifts of colour pattern but can also track one another geographically for more subtle variations within a type of pattern. Quantitative variations in pattern and hue appear adaptive and match local specificities of the surrounding communities of co-mimetic prey. Such partial phenotypic divergence represents an intermediate situation between undifferentiated populations and colour pattern races participating in disjoint mimicry assemblages, opening a window on the process by which diversity within species may evolve. This also brings support to the hypothesis that the variation in abundance of certain key species can influence the local mimicry optimum in a way that translates into changes in the selected phenotypes of other species, a process which was proposed to contribute to mimicry diversification in the face of selection for resemblance (Turner & Mallet 1996).

488

489 Geographic variations were not found, at our scale, within *H. melpomene amaryllis* nor *H.*
490 *erato favorinus*, two species which are generally abundant and widespread compared to *H.*
491 *timareta*. This observation fits the prediction that the commoner species should be less
492 influenced by selection for perfect resemblance in a Müllerian association (Ruxton, Sherratt &
493 Speed 2004; Ruxton *et al.* 2008). However, in other cases where *H. melpomene* is not the
494 dominant species, such as in the Amazon lowlands, subtle geographic variations are reported
495 where they match the local butterfly communities. For instance, among the orange-rayed
496 Amazonian forms, local populations from the Marañon valley exhibit a partial lack of orange
497 rays, which presumably enhance their resemblance to the commonest local species, *H. himera*
498 (J. Mallet, pers. com.). Similarly, the two parapatric races named *H. melpomene aglaope* and
499 *H. m. malleti* represent a geographic continuum of populations whose wing pattern varies
500 quantitatively in the width and shape of the yellow forewing patch, matching similar
501 variations in the patterns of local *H. erato* populations and likely other co-mimetic species.
502 Together with those examples, our results suggest that coordinated quantitative co-variations
503 of the elements of the warning signal are adaptive and, despite receiving little quantitative
504 attention, reflect the tracking of a geographically changing optimum defined by a community
505 of multiple mimetic species.

506

507 *The multimodality of traits involved in mimicry*

508 Resemblance between populations of *H. timareta* and the local co-mimetic species appear
509 congruent over the different traits measured in our study: colour pattern, hue and wing shape,
510 suggesting a multimodal and coordinated evolution of resemblance. This is consistent with
511 recent studies showing that, although colour might have a greater influence on predator

512 decision, pattern features also play a significant role in signalling (Finkbeiner, Briscoe &
513 Reed 2014).

514
515 Whether wing shape is also under selection for mimicry is unclear. Wing venation itself
516 cannot presumably be seen by predators but it may be indirectly under selection since wing
517 motion and wing outline are associated with mimicry (Srygley 1994; Jones *et al.* 2013). Long
518 and narrow forewings (high aspect ratio) are generally associated with fast and extended flight
519 while broader wings may be better suited for slow and more fluttery flights (Betts & Wootton
520 1988), and *H. telesiphe* displays a notably faster and more elusive flight than *H. erato* and *H.*
521 *melpomene* (pers. obs.). Flight behaviours may be perceived by bird predators as informative
522 characters for prey identification and may participate in the definition of the local mimicry
523 optimum (Srygley & Ellington 1999), so the similarity in shape of *H. timareta* to *H. telesiphe*
524 in the Alto Mayo and to *H. melpomene* in the Escalera may represent an adaptive response to
525 selection on flight patterns.

526
527 A striking result from the spectral analysis is that, although both wing sides show a signal of
528 local mimicry adaptation, hue on the dorsal side is less variable (within and between species)
529 than on the ventral side. In butterflies, ventral and dorsal patterns can be genetically correlated
530 as shown by experimental evolution lines of *Bicyclus anynana* (Beldade, Koops & Brakefield.
531 2002) but also strikingly different, as in *Morpho* for instance, which exhibit a bright blue
532 dorsal side and a camouflaged ventral side. Pattern differences between the ventral and dorsal
533 sides then generally result from different selective pressures. Here, the lower variance
534 measured on dorsal hue presumably reflects the fact that dorsal patterns in *Heliconius* are
535 more frequently visible to predators in full light during sunny hours, when the butterflies are
536 flying or basking with wings spread out, translating into stronger natural selection on hue

resemblance. By contrast, ventral patterns are exhibited when resting in the shadow or roosting at night or at dusk or dawn (Mallet 1986; Finkbeiner, Briscoe & Reed 2012), in a light environment where colour differences are less noticeable than in sunlight (Théry, Pincebourde & Feer 2008). Inter-specific differences in ventral hue, especially in UV reflectance, might also be associated with intra-specific social and sexual communication (Silberglied & Taylor 1978).

The evolution of accurate mimicry

Most variations in resemblance quantified between co-mimics here are quite subtle. All populations belong to the general “postman” wing pattern but the precision of mimicry is enhanced between taxa from the same locality, as expected if predators select for mimicry refinement. A long-standing debate is whether evolution takes place by small gradual or large changes (Punnett 1915; Fisher 1927; Nicholson 1927; Fisher 1930). Mimicry evolution is classically suggested to occur first via a large phenotypic change which allows coarse resemblance, then by a phase of more subtle refinement (Sheppard *et al.* 1985; Turner 1987; Franks & Sherratt 2007; Balogh & Leimar 2010; Leimar & Mallet 2012). Introgression of alleles of the *optix* locus from *H. melpomene*, controlling the presence of the red forewing patch, is thought to have been a major step allowing *H. timareta* to join the postman mimicry ring (Heliconius Genome Consortium 2012; Pardo-Diaz *et al.* 2012). Our results describe the second phase of mimicry evolution in which small variations in shape, colour and pattern improve the match to the local optimum. Those mimicry improvements may have evolved through the selection of allelic variants at *optix* and other unlinked loci modifying wing morphology and pattern. In *H. melpomene*, the dislocated *vs.* rounded shape variation of the red forewing patch is associated with a quantitative trait locus (QTL) unlinked to *optix* (Baxter, Johnston & Jiggins 2008). Differential selection towards different mimetic optima

determined by changes in the local species communities would then be predicted to affect such “secondary” mimicry-refining loci which act epistatically with the major mimicry switches already identified.

A role for gene flow?

The process of gradual evolution is particularly efficient in populations with a rich supply of genetic variation for traits contributing to the warning signal (Ruxton *et al.* 2008). Apart from mutation and intra-specific migration, gene flow from closely-related species through hybridization may be an important source of variation (Grant & Grant 1994). Hybridization with local species may bring new, locally adapted alleles and our data show that a certain percentage of F1 hybrids and admixed individuals between *H. melpomene* and *H. timareta* are found in natural populations. Genome-wide signatures of past and ongoing gene flow are documented between *H. melpomene* and *H. timareta*, and introgressed alleles of the red-patterning gene *optix* from *H. melpomene* determine the general postman wing pattern in *H. timareta* of Northern Peru (Heliconius Genome Consortium 2012; Pardo-Diaz *et al.* 2012; Martin *et al.* 2013). The occurrence and timing of the introgression need to be clarified more finely to assess its role in the differentiation we report between the two locations. For instance, one hypothesis is that resemblance may have had more time to evolve in one population if the postman pattern is older there. Similarly, recurrent interspecific gene flow for adaptive alleles at *optix* and other loci readily favoured by selection may participate in the refinement of mimicry in places where *H. melpomene* determines the position of the optimum and overlaps with *H. timareta*.

One intriguing result here is that traits which might not be readily perceived by predators (small red spots, costal line, forewing venation) also display a higher similarity between *H.*

timareta and *H. melpomene* in the Escalera than in the Alto Mayo. If those traits are indeed subject to weaker selection by predators (cf. the stronger resemblance on dorsal phenotypic traits), their similarity might reflect local gene flow between hybridizing *H. melpomene* and *H. timareta*. Our genetic analysis does not support higher gene flow in the Escalera than in the Alto Mayo, but the resolution is limited by the small number of markers. We suggest it would be worth exploring the contribution to resemblance of inter-specific gene flow in this and similar systems.

Conclusion

Here we showed that subtle variations in wing pattern across short geographic distances allow populations of co-mimics to track gradual changes in the mimicry optimum, which suggest that predators do not generalise widely and that selection is operating to maximise mimicry efficiency even between relatively similar warning signals. This demonstrates that fitness peaks in the morphological (signalling) space are sharp and that the quantitative movements of the position of the optimum are of strong adaptive significance for certain species of the community. Effectively, this amounts to *H. timareta* switching mimetic association and to our knowledge, this is the first quantification of such a mimicry switch in a community context. All traits quantified here display coordinated variations, suggesting multimodal and gradual evolution of multiple traits improving the level of resemblance and describing the second phase of colonisation of a new fitness peak. Our study also raises the possibility that the observed geographic pattern of adaptation and the accuracy of mimicry might partly be enhanced by interspecific gene flow providing adaptive alleles readily favoured by selection.

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Data accessibility

Data available from the Dryad Digital Repository: <http://dx.doi.org/10.5061/dryad.h4j6c>

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Figure legends

Figure.1 Distribution and phenotype of the four species belonging to the postman mimicry ring in Northern Peru.

(a) Overview of the phylogenetic relationship between the four co-mimics (left: dorsal side, right: ventral side). Note that this phylogeny is simplified to present the four taxa of interest and the postman pattern is not shared through common ancestry. (b) Map of the study area with an example of phenotypic variation observed in *H. timareta* (T) between the two regions (Escalera and Alto Mayo). (c) Abundance of each species at different localities (AV=Aguas Verdes; Se=Serranoyacu; Af=Afluente; V=Venceremos; Sh=Shilcayo; RV=Rancho Vista; U=Urahuasha; T=Túnel; An=Antena, Table.S1) sorted by elevation, corrected by sampling effort.

Figure.2 Variation in colour pattern between and within species of the postman mimicry ring.

PCA based on colour pattern of the dorsal side and visualisation of the variations in the morphospace. (a-b:FW, c-d:HW). Open dots are females and solid dots are males.

Figure.3 Variation in wing shape between and within species of the postman mimicry ring.

PCA based on wing venation (a:FW, b:HW) and wing outline (c:FW, d:HW). Variation in shape along the axis is represented with the red solid lines at the positive part of the axis and blue dotted lines at the negative value of the axis. Open dots are females and solid dots are males.

Figure.4 Colour variation between and within species of the postman mimicry ring.

PCA based on the excitation of the four photoreceptors in the physiological model of Endler & Mielke. The spot on each wing corresponds to the area where the reflectance measurement was taken (a:FWd, b:HWd, c:FWv, d:HWv).

Figure.5 Pairwise phenotypic distances between groups (co-mimetic species and geographic populations of *H. timareta*)

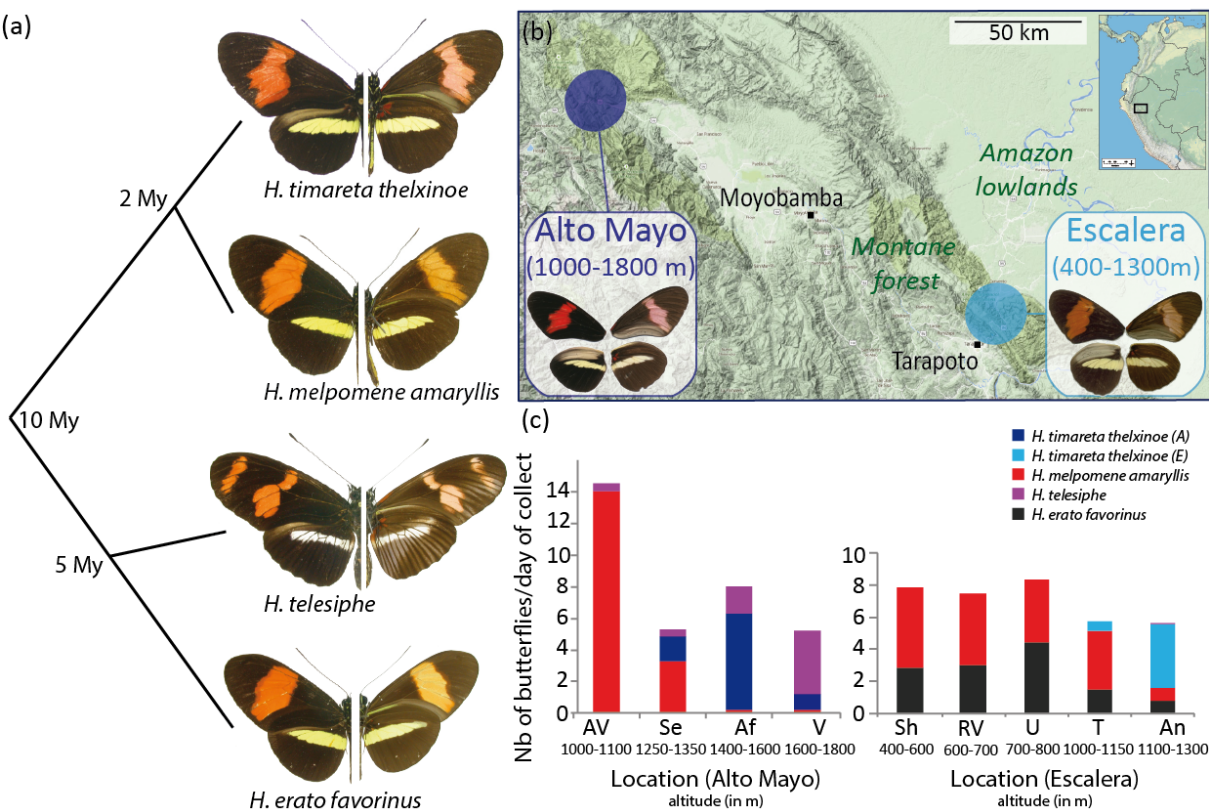
Euclidian distances in each PCA morphospace (**a-f**). Perceptual distances in the physiological model of Vorobyev & Osario (**g-j**). Coloured boxes describe phenotypic distances between a given co-mimic (E= *H. erato*, M= *H. melpomene*, Te= *H. telesiphe*) and each population of *H. timareta* (dark blue: Alto Mayo *T(A)* - light blue: Escalera *T(E)*). Statistical differences between pairwise distances to a given mimic were tested using a mixed model with the geographic population as factor (A vs. E) and identity of the compared specimen as random factors (***: $P \leq 0.001$, **: $P \leq 0.01$, *: $P \leq 0.05$, ns: $P \geq 0.05$). White boxes provide distances between the remaining groups.

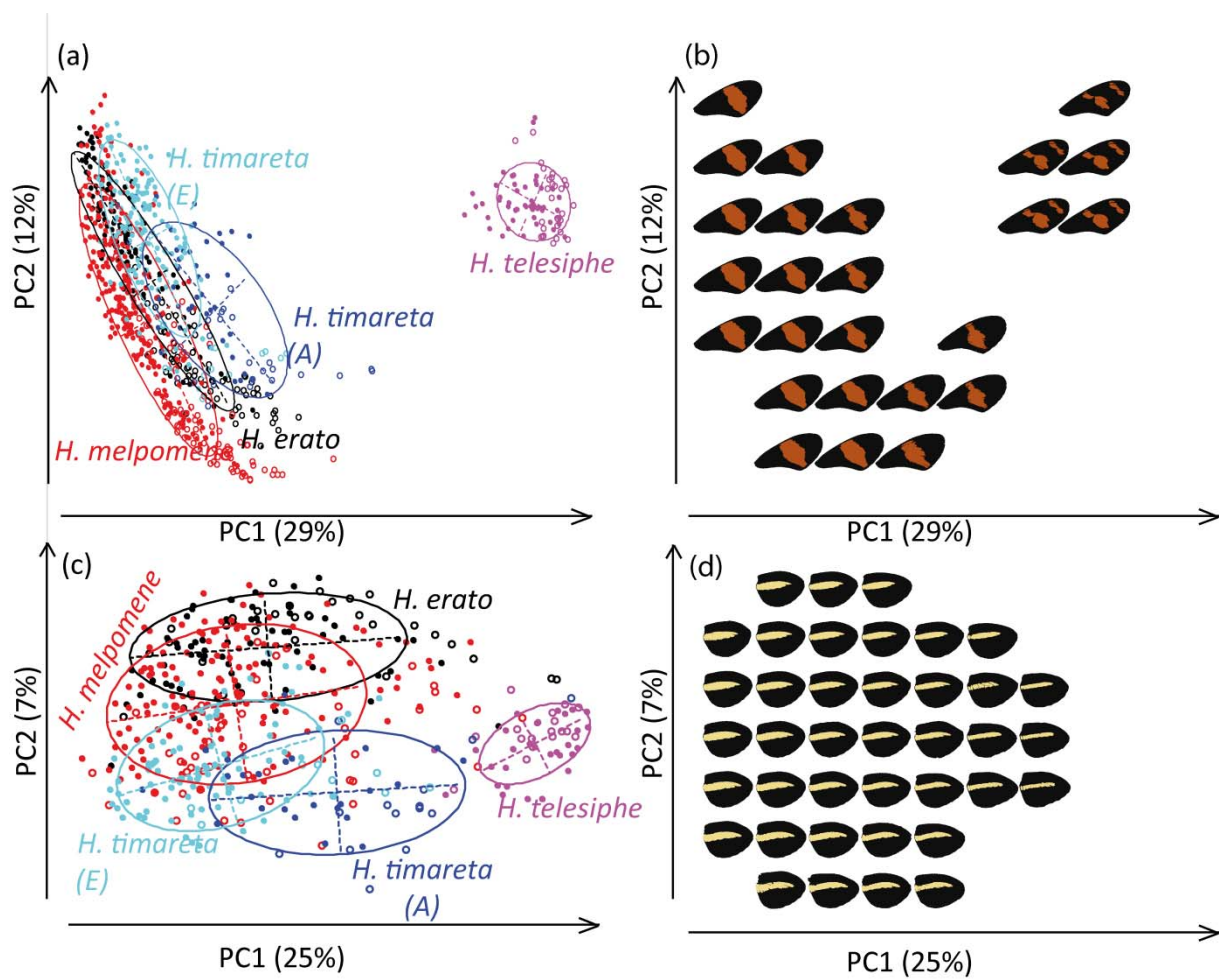
830 **Table.1 MANOVA on phenotypic variation and mis-classification rate from the linear discrimi-**
831 **nant analysis between geographical populations of *H. timareta* (E vs. A)**

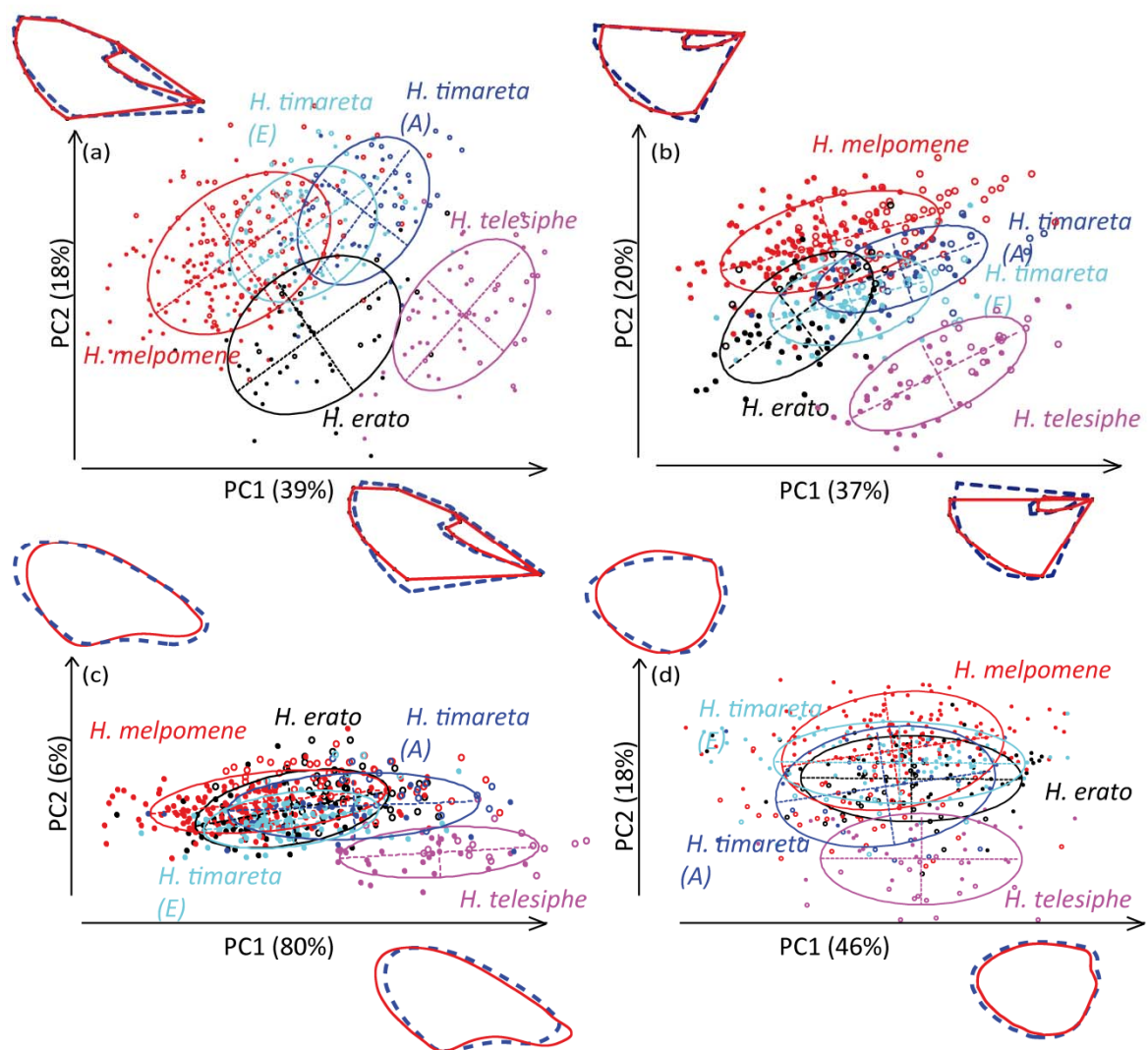
		dF	F	Pillai	P	mis-classification (LDA)
Colour spectra	dorsal red FW	1,132	13.5	0.24	<0.001	28%
	ventral red FW	1,133	8.9	0.17	<0.001	39%
	dorsal yellow HW	1,134	8.7	0.17	<0.001	29%
	ventral yellow HW	1,135	7.9	0.15	<0.001	34%
Colour pattern	dorsal red patch FW	1,136	16.5	0.66	<0.001	13%
	dorsal yellow bar HW	1,137	18.9	0.70	<0.001	11%
Wing venation	FW	1,138	7.1	0.68	<0.001	30%
	HW	1,139	7.0	0.69	<0.001	27%
Wing outline	FW	1,133	5.7	0.29	<0.001	23%
	HW	1,120	5.3	0.30	<0.001	21%

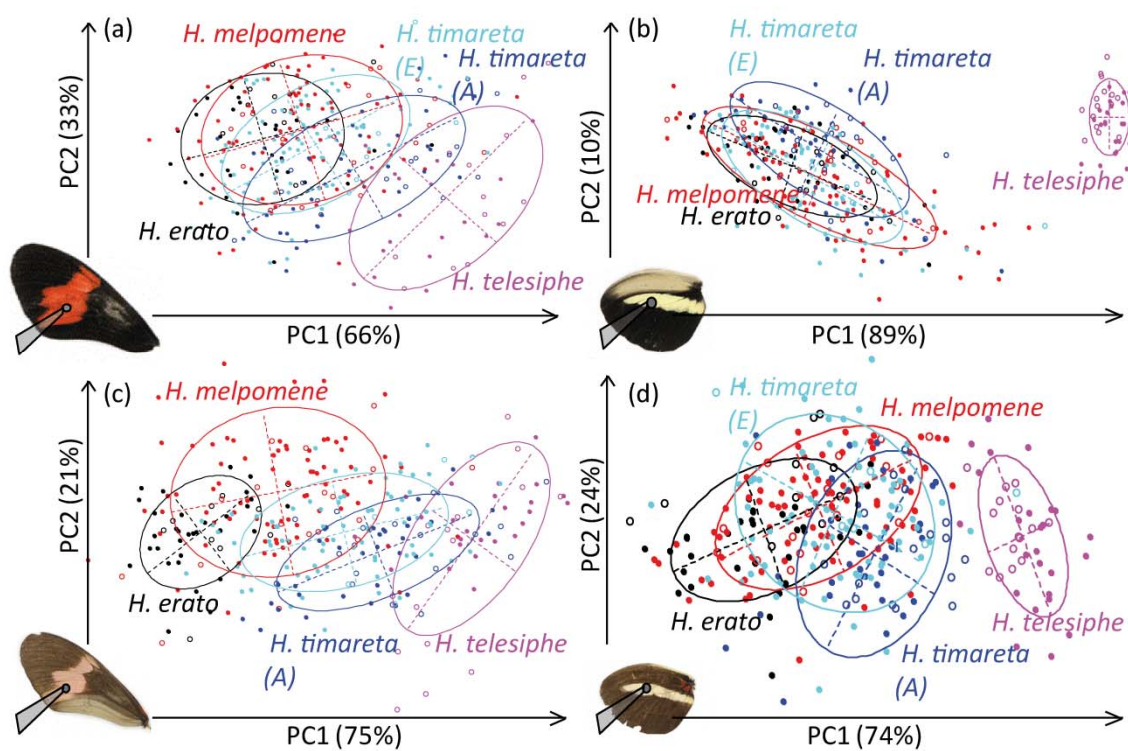
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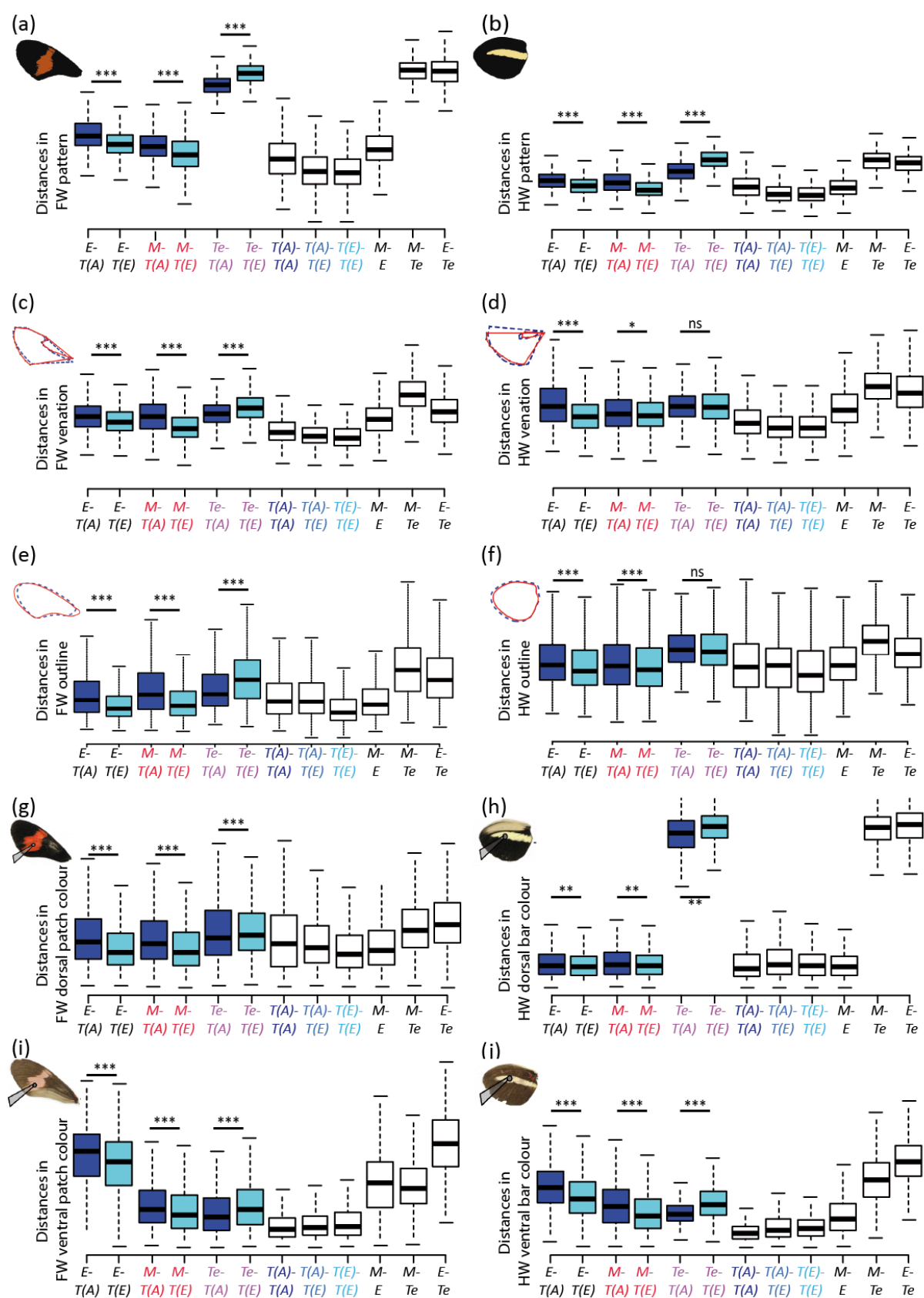
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Mimicry refinement: Phenotypic variation tracking the local optimum

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Supplementary materials

Multilocus microsatellite analysis (Mérot et al, 2013)

Multilocus genotypes were derived by examining variation at eleven microsatellite loci developed for *Heliconius*, using primers and PCR conditions adapted from (Flanagan *et al.*, 2002) and (Mavarez & Gonzalez, 2006). A preliminary set of specimens of 59 *H. m. amaryllis* and 28 *H. t. thelxinoe* was analysed using GeneMapper with the Genescan Rox-500 size standard for allele size determination (Applied Biosystems). A secondary set of specimens of 68 *H. m. amaryllis* and 128 *H. t. thelxinoe*, including one putative hybrid and four reference individuals per species from the first set, was analysed using GeneMarker 2.2.0 with the Genescan-500Liz size standard. Linkage disequilibrium and departure from Hardy-Weinberg within each population within each species were tested using exact tests implemented in GENEPOP 4.1.4 (Rousset, 2008). We used FSTAT 2.9.3 (Goudet, 2001) to survey within-species genetic diversity in terms of expected heterozygosity (H_E), observed heterozygosity (H_O) and allelic richness (A), estimated on the smallest sample size per locus per population ($N=22$). Allelic frequency and F -statistics (Weir & Cockerham, 1984) were calculated using GENETIX 4.05 (Belkhir *et al.*, 1996-2004).

Colour pattern modelling (Le Poul et al, 2014)

Normalized photographs. First, for each specimen, both sides of each forewing and hindwing were photographed in normalized light conditions (CIE Standard Illuminant D50), with a high colour rendering light source (Philips Master TL-D 90 Graphica pro). A scale indicator was included in each picture, and the white balance was normalized. A Nikon D90 digital camera with a Nikon micro 105/2.8G ED VR lens was used to capture high resolution images with accurate colour rendering.

Wing extraction. The first step of CPM relies in identifying and extracting outline of wings on pictures. Wings were automatically detected in the images using their colour difference with the homogenous white background, and were then precisely extracted using the marker-based watershed transformation (Meyer & Beucher, 1990) along the image colour gradient (Meyer, 1992). This segmentation method finds the maximum intensity of the colour transition between the marked wings and the marked background, which was then considered to be the wing outline.

Colour number reduction and colour attribution. Then, the pattern was modelled by considering explicitly the mosaic distribution of colour across the wings, which allows describing efficiently the variation in patches boundaries. A set of discrete colours characteristic to each wing was first identified using an algorithm based on colour histograms (Cheng & Sun, 2000; Kurugollu *et al.*, 2001). After simplifying the spatial structures of wing images (Nikolaev & Nicolayev, 2004), pixels were then attributed to each colour (black, red and yellow) using a simple threshold.

Colours classes were extracted from the histogram by the following procedure. First, to smooth the colour distribution on the histogram and simplify colour histogram processing, the image was projected from the 3-dimensional RGB colour space to a 2-dimensional (2D) colour space, where

dimension 1 corresponds to luminance (the Y component in the Ycrbr colour space), and dimension 2 to the major colour variation axis using all wing images. This projection preserved about 97% of colour variance in the images. A 2D-histogram, representing the distribution of pixel colour, was computed in the same 2D-projected colour space for all wings. Each separate colour on the wing was defined as a local maximum on the 2D-histogram. These local maxima are always numerous because of the complexity of the natural image. To prevent over-segmentation, minor peaks were automatically removed by consideration of their proximity to and separation from neighbouring peaks. We performed a watershed transformation on the additive inverse of the 2D-histogram to partition the colour space among the major peaks (Shafarenko *et al*, 1998). At the end of this process, each wing could be associated with a set of characteristic colour partitioning the colour space and accounting for the colour variation actually present on the wing RGB image.

In order to preserve the patch structure of colour patterns, we also performed a routine to merge neighbouring pixels of homogeneously-coloured regions in the images (Nikolaev & Nicolayev, 2004). The scale indicator within each image was first used to rescale images to an output length of around 512 pixels, leading to a mean spatial resolution of 10.9px/mm. Each reduced image was then transformed into a mosaic of homogeneously-coloured spatial zones. A watershed transformation of the image colour gradient was used to carry out the mosaicking (Meyer, 1992). Each homogeneously-coloured region was then attributed a colour according to the classification given by the segmented histogram.

Finally, the attribution to the different colours (black, red, and yellow) was done automatically using a threshold on RGB values, followed by manual checking to correct errors, which were mostly due to minor damage to parts of the wings, resulting in the final segmented image.

Alignment. For the wing images to be efficiently comparable pixel by pixel, a proper homology of pixel positions was needed. This match was obtained by transforming each set of processed images into a common coordinate system which maximizes similarity between each wing pattern and wing outline to a wing model (*i.e.* the ‘mean’ of all individuals), treating each wing surface separately. Similarity was measured by the Mattes implementation of mutual information metric (Thévenaz & Unser, 2000; Mattes *et al*, 2001; Mattes *et al*, 2003), which is minimal when colour patches and outlines are aligned in an optimal compromise. The one+one evolutionary optimizer (Styner & Gerig, 1997; Styner *et al*, 2000), implemented within the ITK free image processing library in C++ (Yoo *et al*, 2002; Ibáñez, 2003; Martin & Hoffman, 2003), was used to find the scale, rotation and translation parameter set that minimized this mutual information value. This procedure created an initial registration set based on wing shape, which allowed generation of the wing pattern model. Each wing was then recursively aligned to the model, until the variance of the metric stabilized (variance varying less 1% (Rohlf & Slice, 1990)). At the completion of this process, all wings could be considered to be positioned in the same physical space, with pixel locations and colour values among wings being comparable among all individuals.

Table S2. Number of specimen used in each analysis

	<i>Density estimates</i>	<i>Density</i> (butterflies/day of collection)	<i>Scored for genotype</i> (microsatellites)	<i>Band/ spots</i>	<i>Venation</i>	<i>Scored for phenotype</i>						
						<i>Outline (FW)</i>	<i>Outline (HW)</i>	<i>Pattern (FW v)</i>	<i>Pattern (FW d)</i>	<i>Pattern (HW v)</i>	<i>Pattern (HW d)</i>	<i>Reflectance</i>
Alto Mayo	180 (25 days)		59	200	151	118	105	121	124	109	112	118
<i>H. timareta</i>	83	3.3	38	71	54	42	31	42	44	34	36	43
<i>H. melpomene</i>	54	2.2	20	60	39	27	25	28	28	25	25	31
<i>H. erato</i>	0	0.0		5	5	5	5	5	5	5	5	5
<i>H. telesiphe</i>	43	1.7		63	53	44	44	46	47	45	46	39
<i>H. melpomene</i> <i>x H. timareta</i> ?			1									
Escalera	473 (83 days)		172	324	148	187	172	195	195	190	191	98
<i>H. timareta</i>	203	2.4	115	167	70	91	89	97	97	98	97	73
<i>H. melpomene</i>	175	2.1	54	118	67	61	55	64	63	62	63	16
<i>H. erato</i>	93	1.1		34	10	33	26	32	33	28	29	8
<i>H. telesiphe</i>	2	0.0		2	1	2	2	2	2	2	2	1
<i>H. melpomene</i> <i>x H. timareta</i> ?			3									
Escalera_low	517 (65 days)		32	163	78	128	119	132	132	121	124	44
<i>H. melpomene</i>	293	4.5	32	103	55	77	72	81	80	73	73	22
<i>H. erato</i>	224	3.4		60	23	51	47	51	52	48	51	22
Moyobamba			11	54	37	47	44	50	48	45	45	22
<i>H. melpomene</i>			11	35	25	30	29	32	30	30	30	16
<i>H. erato</i>				19	12	17	15	18	18	15	15	6
Raised												
<i>H. melpomene</i> <i>x H. timareta</i>			11	11								9
Total			285	752	414	480	440	498	499	465	472	291

Table S3: Genetic polymorphism of the studied sample.

Allelic richness (A) is estimated for the smallest population (N=22). H_O represents the observed heterozygosity and H_E , the expected heterozygosity. Significant deviations from Hardy-Weinberg expectations are indicated by asterisks ($P < 0.05$ *; $P < 0.01$ **). Loci come from Flanagan et al (2002)[1], and Mavarez et al (2006)[2].

Locus	Primer sequence (5'-3')	GenBank accession no.	No. of sample	No. of alleles	<i>H. timareta thelxinoe</i> (Alto Mayo)					<i>H. timareta thelxinoe</i> (Escalera)						
					Allelic Richness	Size range (bp)	H_O	HW DEFICIT	H_E	No. of sample	No. of alleles	Allelic Richness	Size range (bp)	H_O	HW DEFICIT	H_E
Hel2 (1)	TCAAAATGTTGCAGACCGAG TGCACTTCATTGTAAGCGGT	AF481467	40	4	3.6	186-202	0.20	**	0.52	113	5	4.3	196-202	0.50	**	0.58
Hel4 (1)	CGTTGCCGCTTATACTTTCC GGAACGGAGTGCCCTAAAAC	AF481469	40	7	6	268-282	0.34	**	0.62	109	10	6.8	262-302	0.37	**	0.77
Hel5 (1)	TGCTGTCCATACCCAACTCA CGAACTCACAACCATCAGTCA	AF81470	40	3	2.6	314-330	0.24		0.32	115	5	2.9	314-330	0.21	**	0.22
Hm02 (2)	TATTTGCACGATGGAAACCC GCGAGGTGGAGACAAAAGAC	DQ020073	40	6	5.5	180-200	0.54	**	0.75	112	11	7.2	180-200	0.71	**	0.72
Hm03 (2)	GACGTCACAGCGGGGAAC AGAGGGGAACGGAGTGTCTAT	DQ020074	40	9	7.5	292-352	0.49	*	0.65	110	10	6.8	312-348	0.59	*	0.72
Hm04 (2)	CCTGGCTTATCTACGACGACA ATGCAGCTTACTCGCTGGTT	DQ020075	40	10	8	410-458	0.66	**	0.79	111	7	5	406-452	0.49		0.60
Hm05 (2)	GCGGTAAGGTAAAACCGTGA CAGAAGAAAATGGTTGGATGG	DQ020076	40	8	7.2	284-302	0.76		0.71	112	12	8.3	274-300	0.71	**	0.82
Hm06 (2)	AAATAGTGTGCGGCGGAATA TGGAGTAGAAATGCGGGTTTA	DQ020077	40	4	4	240-246	0.49	**	0.73	111	5	4.9	238-246	0.59	**	0.74
Hm13 (2)	TCTAGTTTTCGGCTTATCG AAGGCTAAATGATGCCTAAAG	DQ020083	40	6	5.9	168-188	0.78		0.82	112	9	6.5	168-190	0.65	**	0.77
Hm19 (2)	CGCTAATTCAAAGGAAAGAGGA AGTGCTGTCATGGCTAACGA	DQ020088	40	5	4	182-216	0.22		0.25	110	9	5	182-216	0.14	**	0.32
Hm22 (2)	CCTCGTCCAACTCCAAAAC AACAATGTCACAACCATCGC	DQ020092	40	3	2.8	252-256	0.51		0.53	113	6	3.5	252-264	0.54		0.53

Locus	Primer sequence (5'-3')	GenBank accession no.	<i>H. melpomene amaryllis</i> (Alto Mayo)							<i>H. melpomene amaryllis</i> (Escalera)						
			No. of sample	No. of alleles	Allelic Richness	Size range (bp)	Ho	HW DEFICIT	He	No. of sample	No. of alleles	Allelic Richness	Size range (bp)	Ho	HW DEFICIT	He
Hel2 (1)	TCAAAATGTTGCAGACCGAG TGCACTTCATTGTAAGGCGT	AF481467	22	5	5	184-192	0.55	**	0.65	53	6	5	184-192	0.54	*	0.63
Hel4 (1)	CGTTGCCGCTTATACTTTCC GGAACGGAGTGCCCTAAAC	AF481469	22	12	12	236-312	0.46	**	0.88	50	22	14.7	236-322	0.29	**	0.90
Hel5 (1)	TGCTGTCCATACCCAACCTCA CGAACTCACAACCATCAGTCA	AF81470	22	11	11	310-358	0.82		0.85	53	21	14.9	296-358	0.77	*	0.90
Hm02 (2)	TATTTGCACGATGGAAACCC GCGAGGTGGAGACAAAAGAC	DQ020073	22	7	7	184-200	0.46	**	0.64	53	10	7.3	170-198	0.64	**	0.69
Hm03 (2)	GACGTCACAGCGGGGAAC AGAGGGGAACGGAGTGTCAT	DQ020074	22	7	7	314-352	0.46		0.55	53	111	8.2	302-348	0.56		0.67
Hm04 (2)	CCTGGCTTATCTACGACGACA ATGCAGCTTACTCGCTGGTT	DQ020075	22	11	11	402-444	0.64	*	0.78	53	14	10.9	396-428	0.71	**	0.80
Hm05 (2)	GCGGTAAGGTAAAACCGTGA CAGAAGAAAATGGTTGGATGG	DQ020076	22	13	13	274-320	0.77		0.85	52	14	11.5	274-306	0.75	*	0.87
Hm06 (2)	AAATAGTGTGCGGCGGAATA TGGAGTAGAAATGCGGGTTTA	DQ020077	22	4	4	240-246	0.77		0.76	53	6	5.5	238-248	0.64		0.73
Hm13 (2)	TCTACTAGTTTTCGGCTTATCG AAGGCTAAATGATGCCTAAAG	DQ020083	22	12	12	144-186	0.73	*	0.88	53	13	10.2	170-198	0.56	**	0.76
Hm19 (2)	CGCTAATTCAAAGGAAAGAGGA AGTGCTGTCATGGCTAACGA	DQ020088	22	13	13	154-208	0.64	**	0.85	53	20	14.8	150-210	0.52	**	0.88
Hm22 (2)	CCTCGTCCAAACTCCAAAAC AACAATGTCACAACCATCGC	DQ020092	22	13	13	246-279	0.68	**	0.91	52	15	11.8	246-280	0.67	**	0.85

Geographic variation in *H. melpomene* and *H. erato*

Table S4. MANOVA on phenotypic variation and mis-classification rate from the linear discriminant analysis between four geographical populations of *H. melpomene* (“Low Escalera”, “High Escalera”, “Alto Mayo”, “Moyobamba”)

		dF	F	Pillai	P	mis-classification (CVA)
Colour spectra	dorsal red FW	3,95	2.2	0.20	0.02	65%
	ventral red FW	3,95	1.9	0.17	0.055	64%
	dorsal yellow HW	3,95	0.6	0.06	0.77	70%
	ventral yellow HW	3,95	1.4	0.13	0.19	71%
Colour pattern	dorsal red patch FW	3,194	1.7	0.36	0.004	58%
	dorsal yellow bar HW	3,198	2.6	0.52	<0.001	52%
Wing venation	FW	3,178	1.8	0.43	0.001	60%
	HW	3,178	2.7	0.59	<0.001	53%
Wing outline	FW	3,193	1.2	0.16	0.27	59%
	HW	3,177	1.8	0.26	0.009	59%

Table S5. MANOVA on phenotypic variation and mis-classification rate from the linear discriminant analysis between three geographical populations of *H. erato* (“Low Escalera”, “High Escalera”, “Moyobamba”)

		dF	F	Pillai	P	mis-classification (CVA)
Colour spectra	dorsal red FW	2,34	1.2	0.20	0.33	43%
	ventral red FW	2,34	1.2	0.20	0.32	43%
	dorsal yellow HW	2,34	0.5	0.09	0.80	41%
	ventral yellow HW	2,34	0.3	0.06	0.91	41%
Colour pattern	dorsal red patch FW	2,98	1.3	0.38	0.14	52%
	dorsal yellow bar HW	2,96	1.1	0.33	0.36	54%
Wing venation	FW	2,34	1.4	0.98	0.18	57%
	HW	2,34	1.7	1.09	0.06	60%
Wing outline	FW	2,99	1.0	0.17	0.52	48%
	HW	2,87	1.1	0.22	0.36	46%

Colour pattern analyses

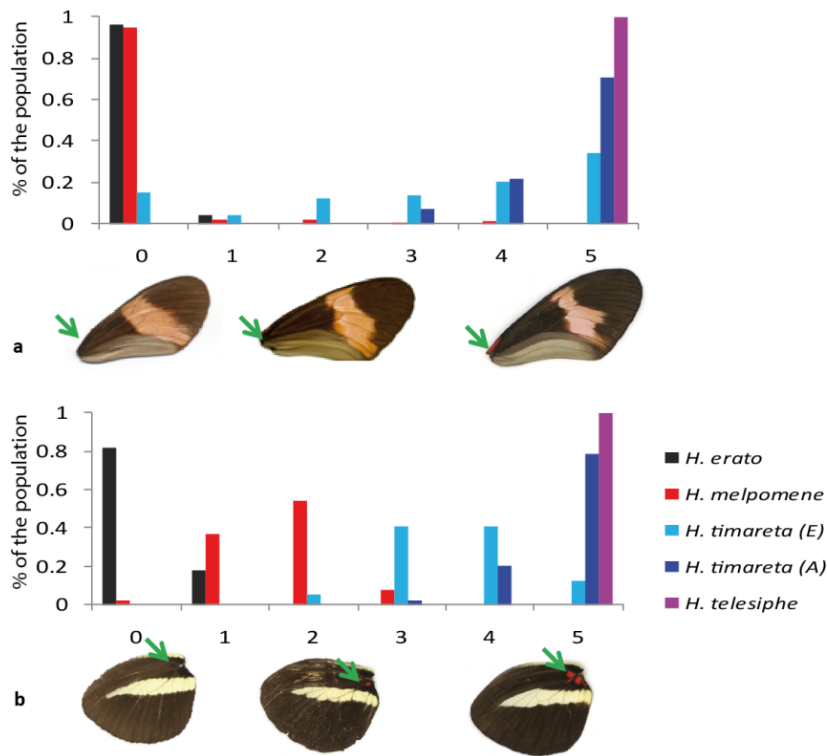


Figure S1: Distribution of the indices scoring the small ventral elements of pattern between and within species of the postman mimicry ring. (a) Presence and size of a red line at the base of the costal vein of the ventral forewing. The index ranges from 0 (absence of red line) to 5 (large and well-marked red line). (b) Presence and size of red dots at the base of the ventral hindwing. The index ranges from 0 (no dot) to 5 (presence of four large smudgy spots). 1 to 4 correspond to a gradation between one or two minute dots and more numerous or larger spots.

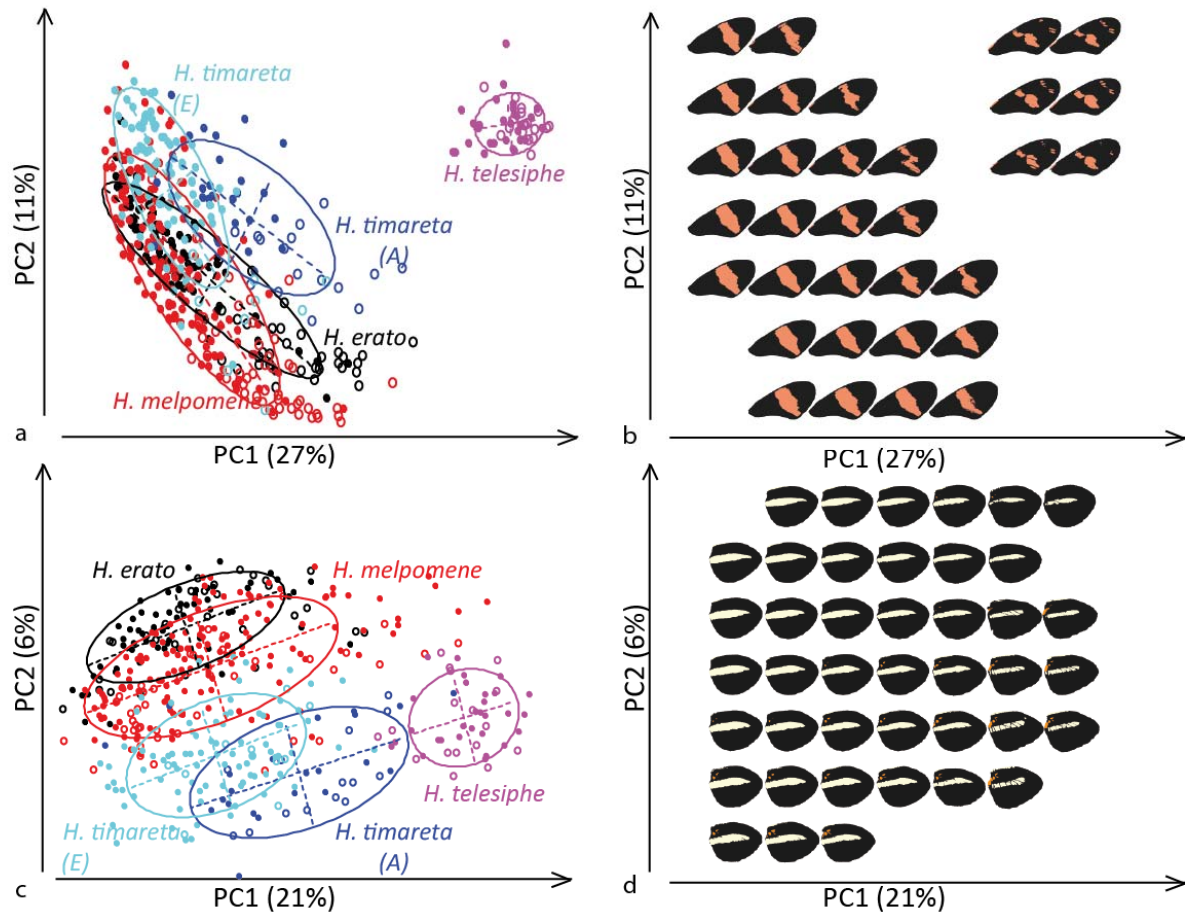


Figure S2: Colour pattern variation between and within species of the postman mimicry ring. Principal component analysis based on colour pattern and visualisation of variation in the morphospace (ventral FW (a-b), ventral HW (c-d))

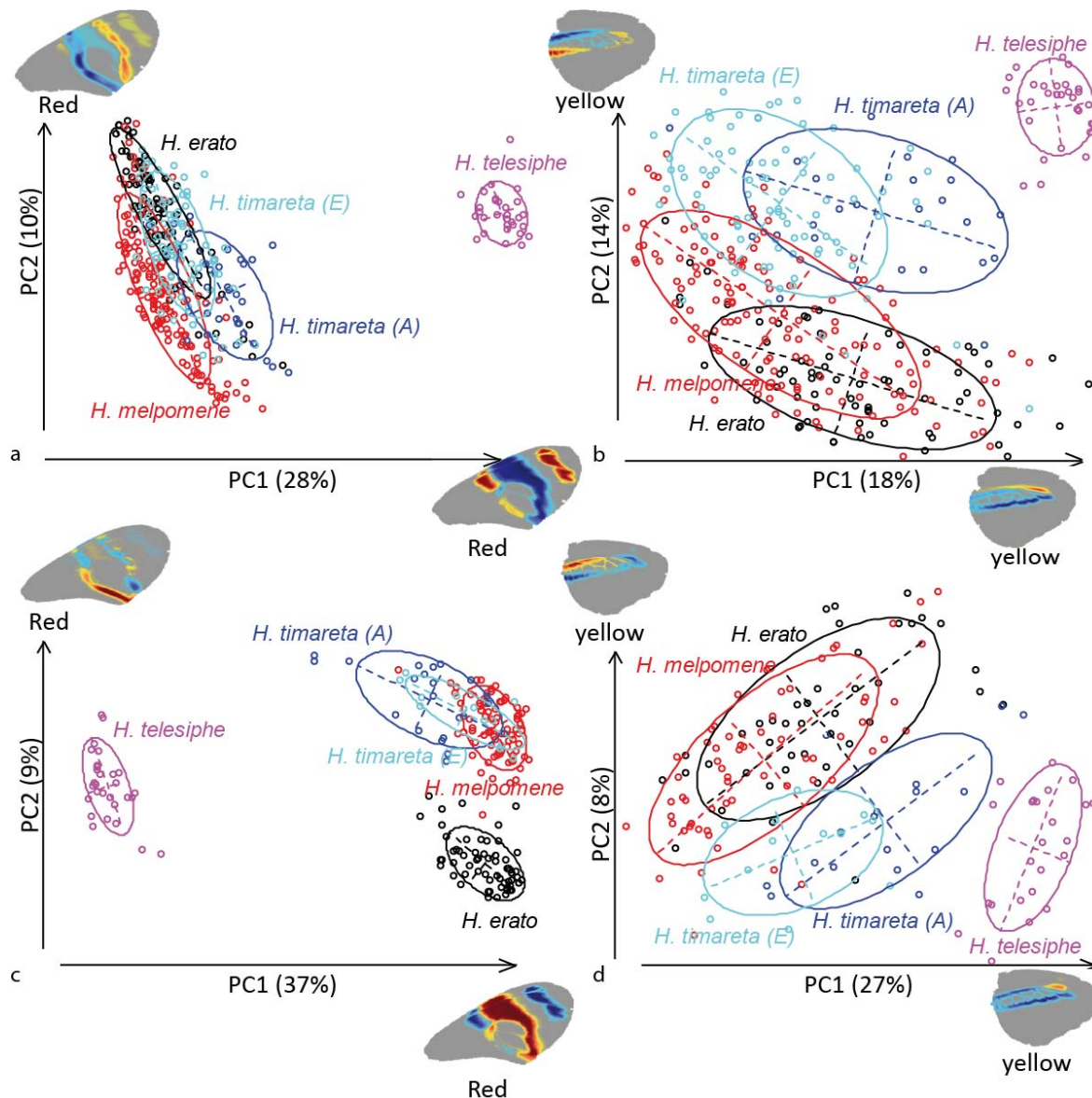


Figure S3: Wing colour pattern PCA within each sex.

Wing sketches show the pixels involved in the variation of colour pattern associated with each axis. A positive contribution (red) for one colour indicates that an increase in the score is associated with the appearance (presence) of this colour on the phenotype. On the contrary, a negative contribution (blue) is associated with a disappearance of this colour. (a) Red colour on male FW, (b) yellow colour on male HW, (c) red colour on female FW, (d) yellow colour on female HW.

Wing venation

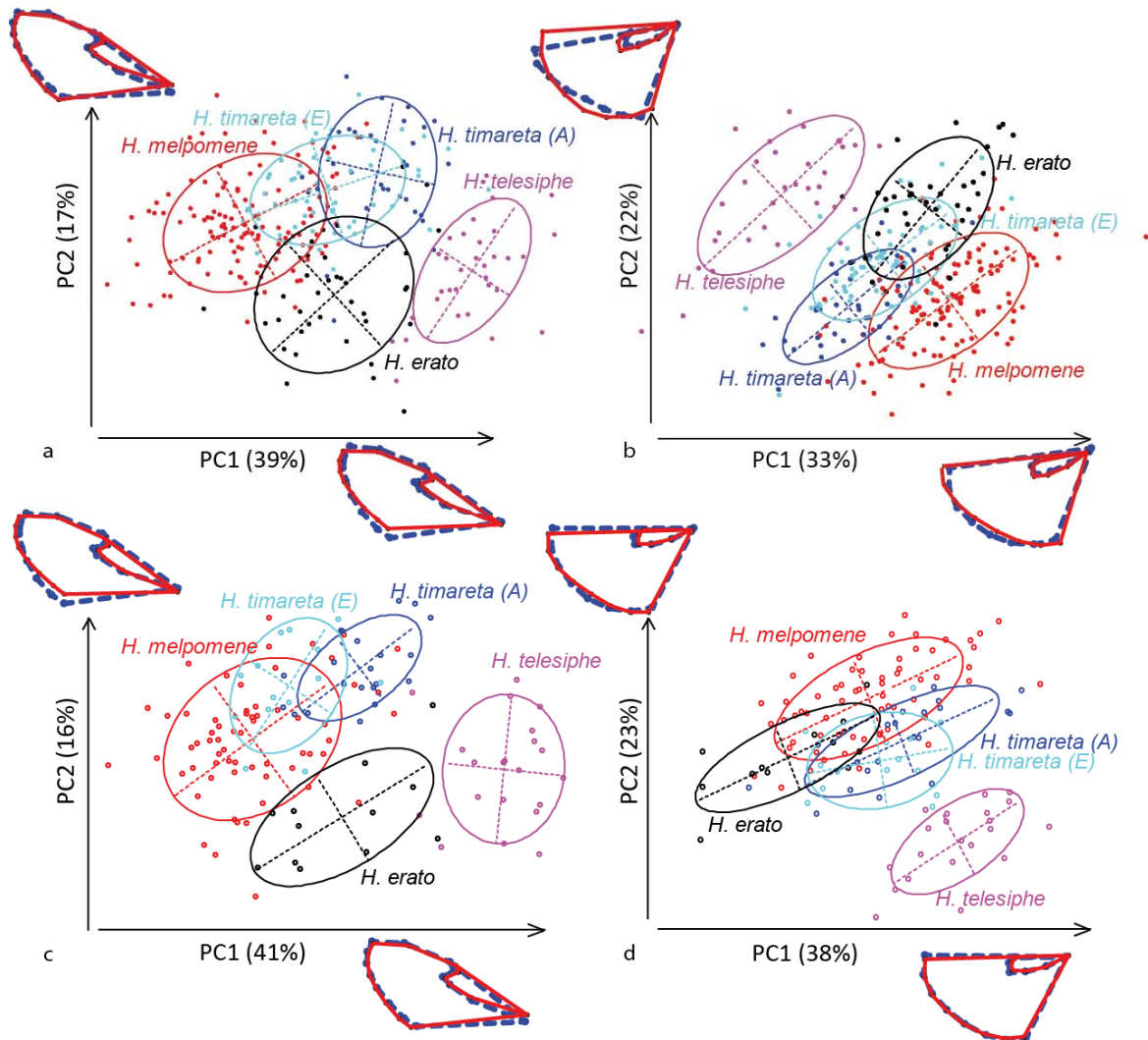


Figure S4: PCA on wing venation for each sex.

(a) FW for males, (b) HW for males, (c) FW for females, (d) HW for females.

Colour analyses

The best-documented predators of *Heliconius* include jacamars (Chai & Srygley 1990; Langham 2006), which belong to the order Galbuliformes. Within this order, only *Nystalus maculatus* visual system has been studied and would have a tetrachromatic violet-type visual system according to opsin sequence similarity (Odeen & Hastad 2003). However, the guild of bird predators on those butterflies may include other birds, which possibly differ in the spectral sensitivities of their short-wavelength-sensitive cone visual pigments. Therefore, we included two tetrachromatic visual systems in our analysis: a bird with a V-type visual system (Peafowl, *Pavo cristatus*, (Hart 2002)), a bird with a UV-type visual system (Blue tit, *Parus caeruleus*, (Hart *et al.* 2000)). Because the results were not qualitatively different when analysed with different visual systems, we chose to present the results in the V-type vision model. Results in the UV-type visual system displayed consistent results with the V-type

system (Fig. S9). All models were run considering two kinds of incident light: a light environment corresponding to large sunny gaps in a tropical forest, and a light environment corresponding to small light gaps. Those light spectra were measured by M. Théry in primary forest in French Guiana (Théry, Pincebourde & Feer 2008). Results were consistent with both types of light so we only present models with large gap incident light here, which corresponds better to the natural habitat of the species considered here.

Surrounding colours can affect perception and it is usually important to take background colour into account. Here, all patches are large making the colour well-visible. The patches are surrounded by the black part of the wing, for which we analyzed reflectance. Colour contrasts calculated with the model of Vorobyev and Osorio (1998) indicate that differences between and within species were not perceptible for observers (below the usual value of 1 JND), with mean values around 0.5 JND in the large gap conditions and 0.2 JND in the small gap conditions (Fig. S8). Therefore, we focused on the comparison of actual patches' colour between species and populations.

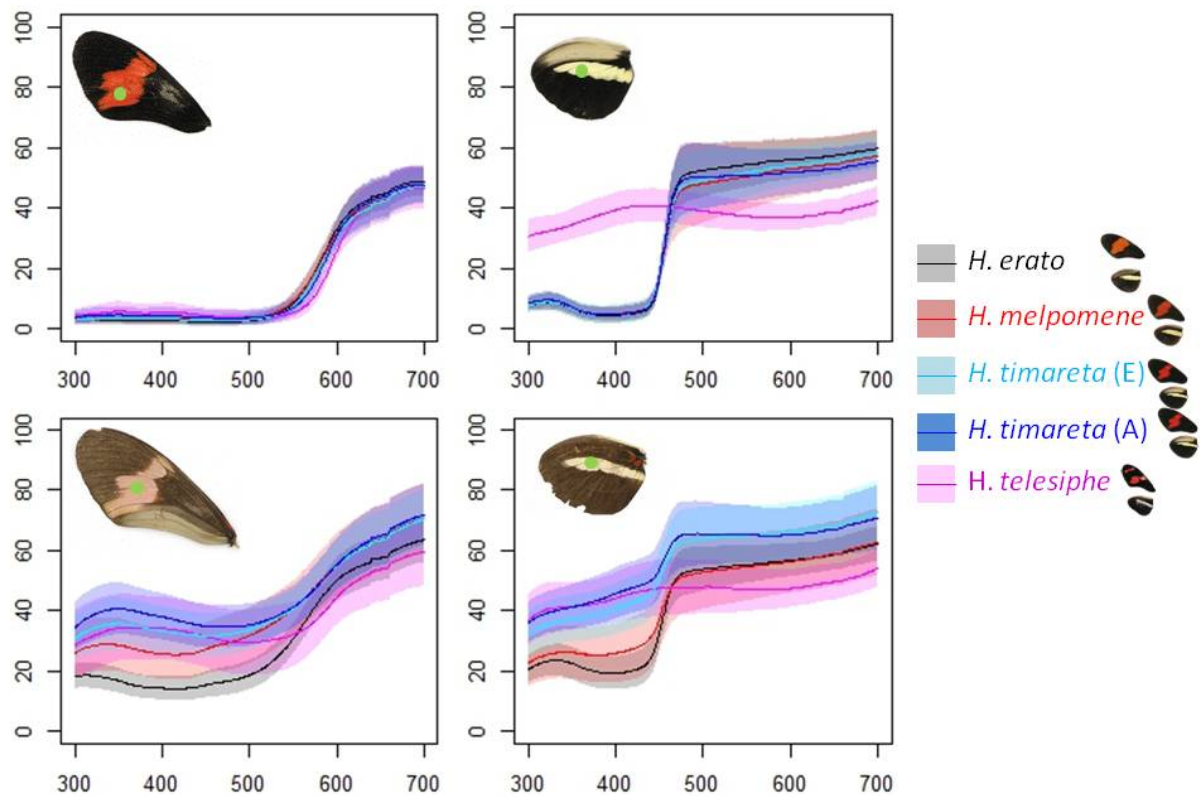


Figure S5: Mean raw spectra of colour patches for each taxon. The x-axis represents the wavelength from 300 to 700 nm and the y-axis the reflectance in percentage of the white control. The shadows represent standard deviation.

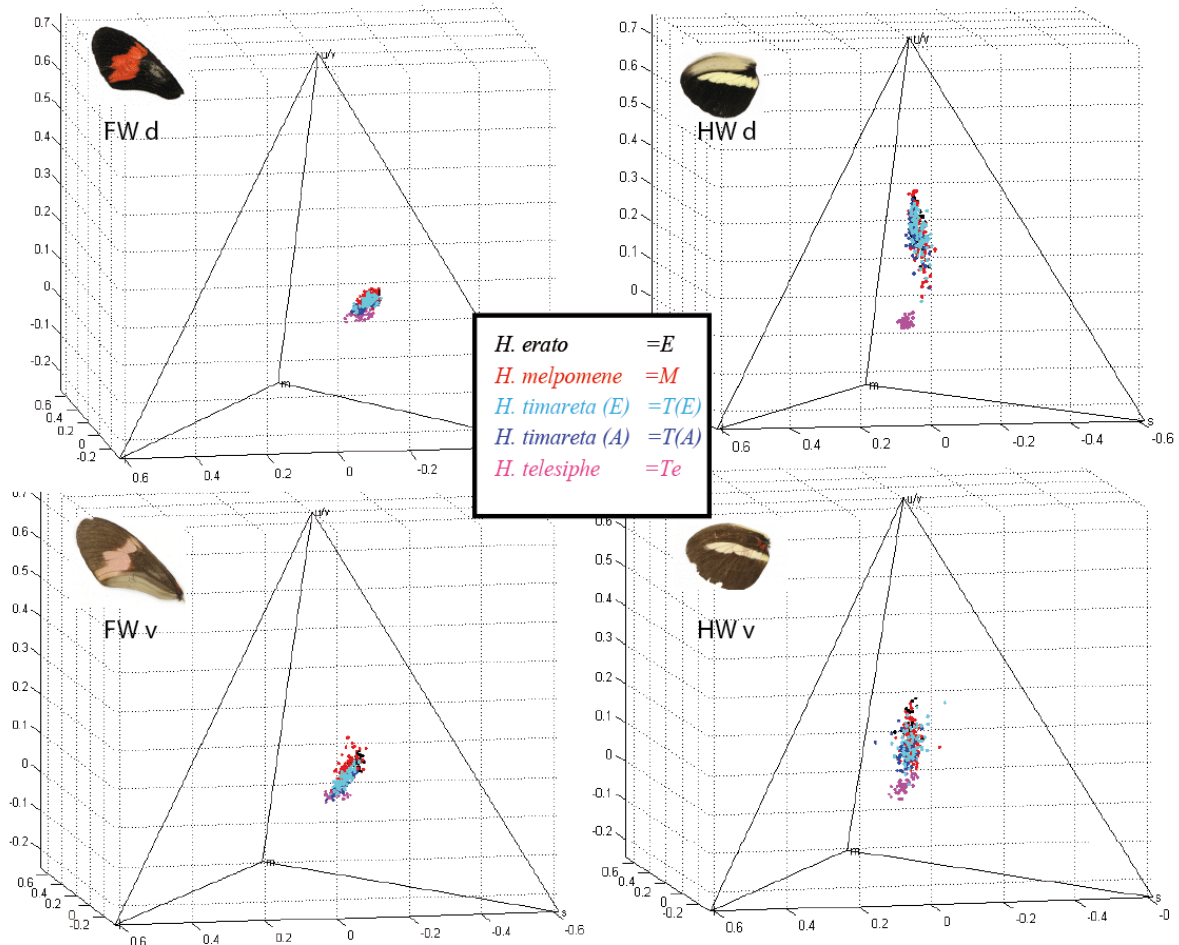


Figure S6: Location of wing colours in the tetrahedral chromatic visual space.

Based on a model Endler and Mielke (2005) with a bird V-type visual system (Peafowl) and a large gap light.

Table S6. Percentage of overlap in the tetrahedral colour space between spectral variation of each species and each population of *H. timareta*.

The last column gives the overlap between the two populations of *H. timareta*. This is based on a physiological model Endler and Mielke (2005) with a bird V-type system (Peafowl) and a large gap light.

	<i>H. erato</i>		<i>H. melpomene</i>		<i>H. telesiphe</i>		<i>H. timareta</i>
	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	A vs. E
	A	E	A	E	A	E	
Red FW d	0.22	0.36	0.43	0.58	0.09	0.05	0.58
Red FW v	0.00	0.08	0.08	0.22	0.20	0.11	0.39
Yellow HW d	0.31	0.32	0.25	0.29	0.00	0.00	0.42
Yellow HW v	0.09	0.12	0.26	0.43	0.00	0.00	0.34

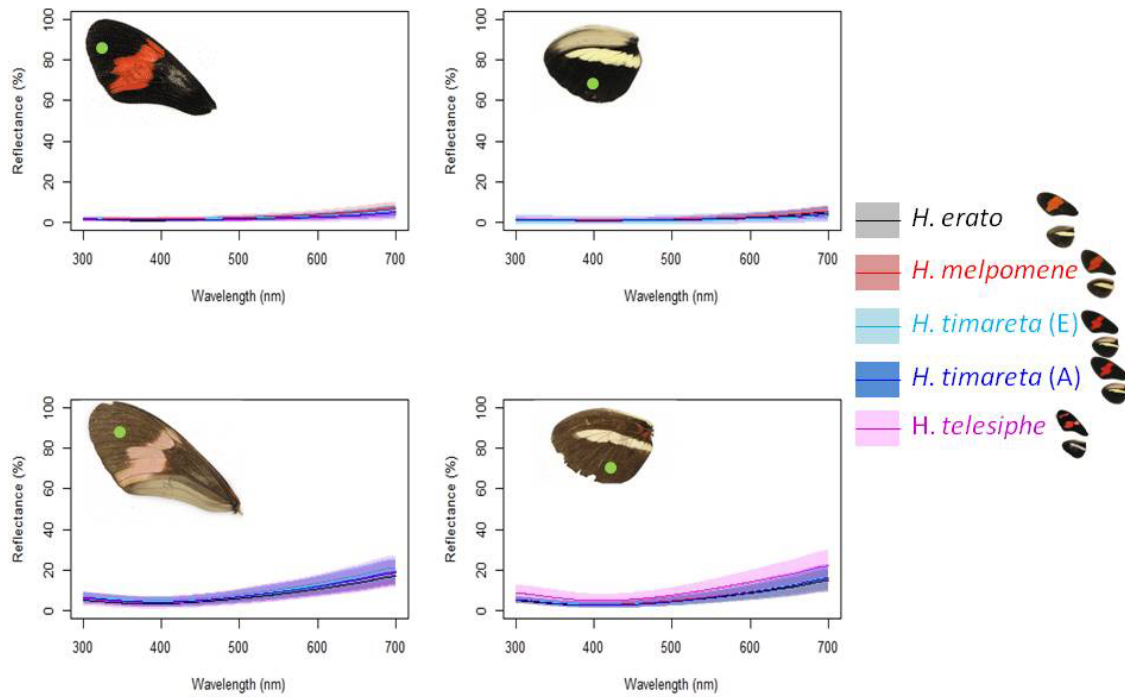


Figure S7: Mean raw spectra of the black area for each taxon. The x-axis represents the wavelength from 300 to 700 nm and the y-axis the reflectance in percentage of the white control. The shadows represent standard deviation.

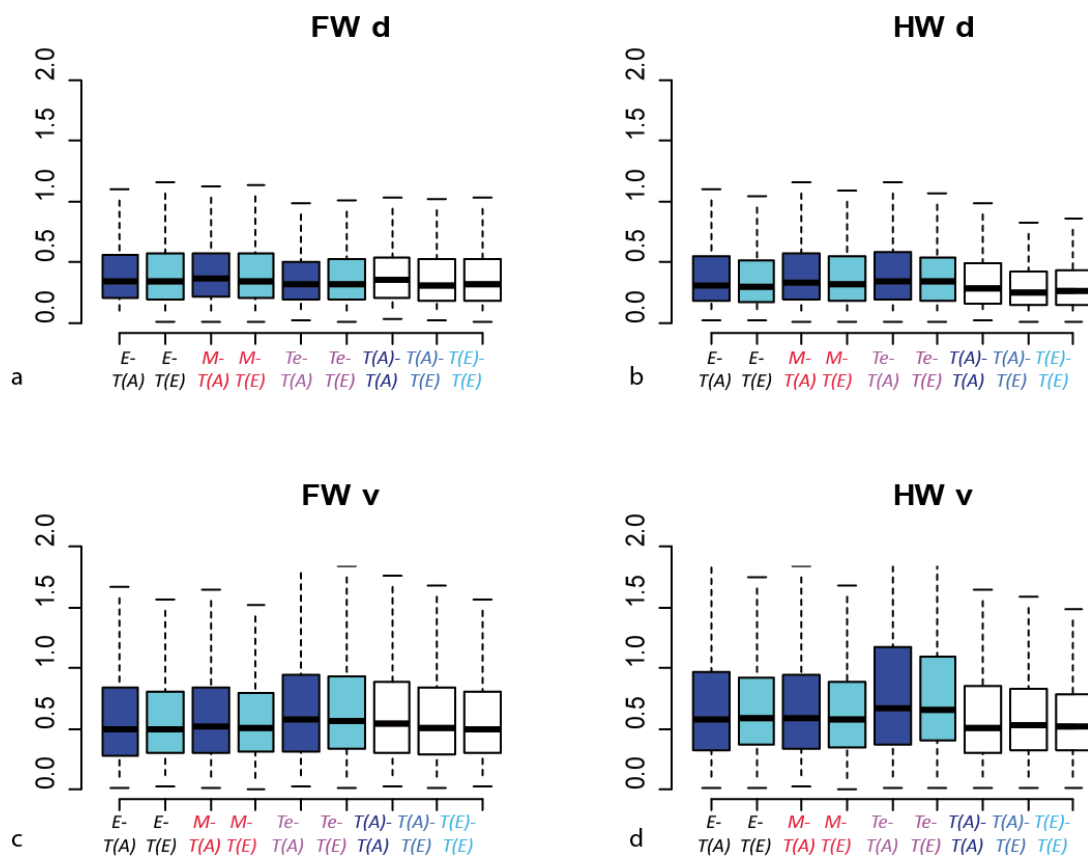


Figure S8: Controlling perceptual distances in the black.

Colour perceptual distances for the black part of each wing in the model of Vorobyev & Osorio (1998) expressed in unit of just noticeable differences (JND). Bird V-type system (Peafowl) and a large gap light. Contrast between species blackness is below 1 JND.

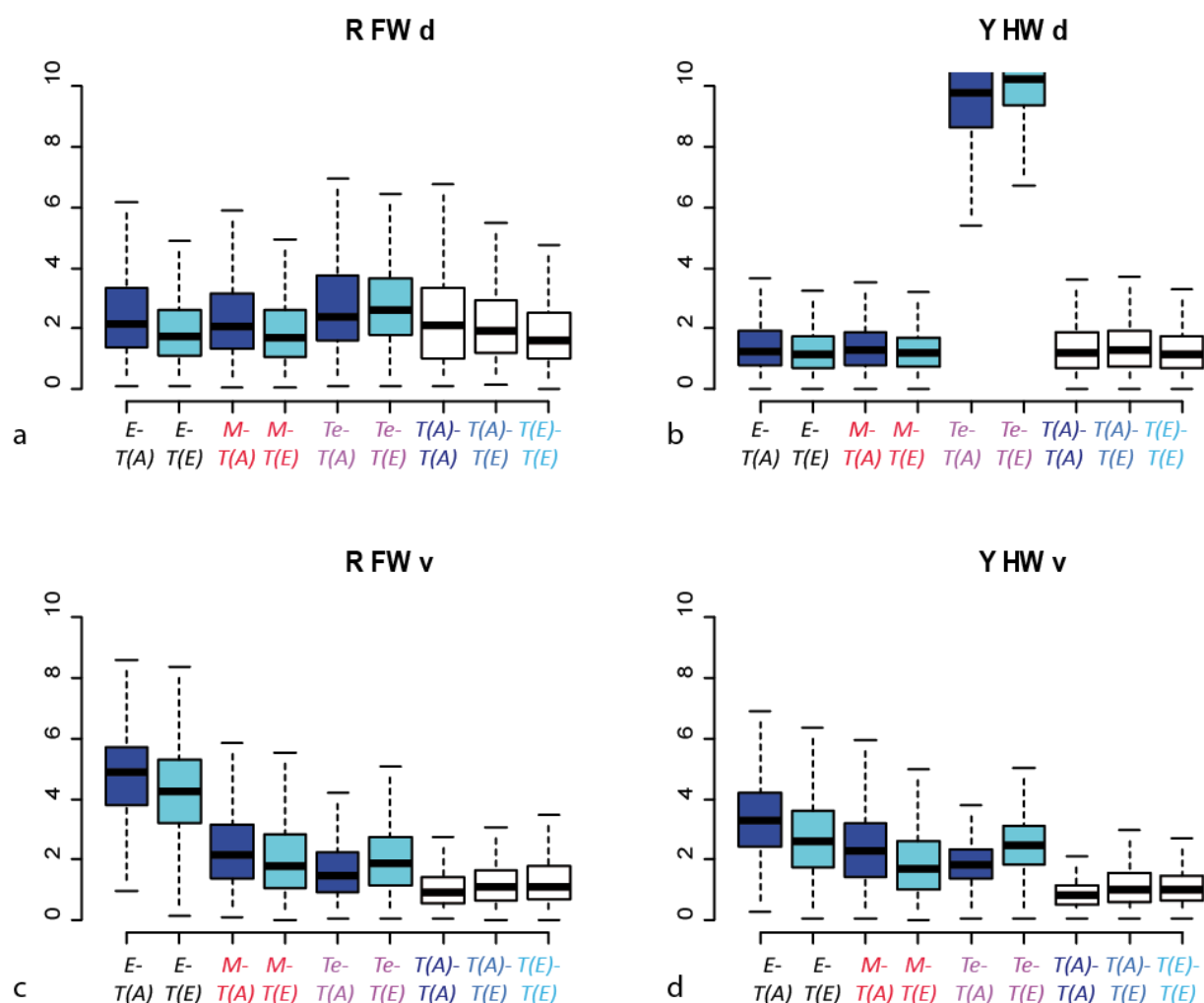


Figure S9: Investigating other vision system (UV-type).

Colour perceptual distances in the model of Vorobyev & Osorio (1998) with a bird UV-type visual system (Blue tit) and a large gap light for the red patches (R) and the yellow patches (Y)

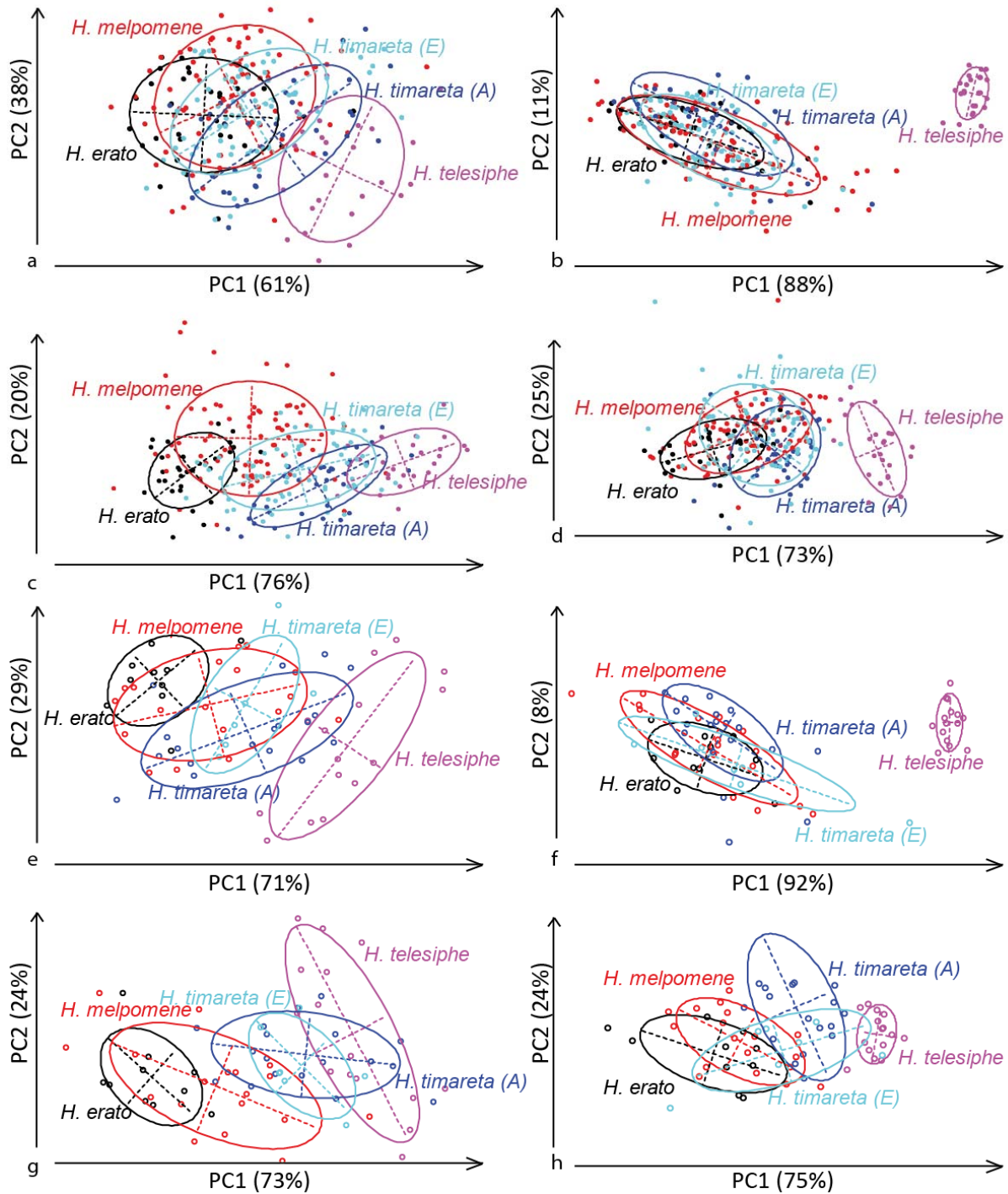


Figure S10: Principal component analyses based on the excitation of the four photoreceptors in the physiological model of Endler & Mielke for each colour patch

Bird V-type visual system and large gap light. (a) red patch on male dorsal FW, (b) yellow patch on male dorsal HW, (c) red patch on male ventral FW, (d) yellow patch on male ventral HW, (e) red patch on female dorsal FW, (f) yellow patch on female dorsal HW, (g) red patch on female ventral FW, (h) yellow patch on female ventral HW.

Distances and cross-validation

Table S7. Mahalanobis distances for each component of the phenotype between populations of *H. timareta* and their co-mimics (mean of the bootstrap \pm sd)

		<i>H. erato favorinus</i>		<i>H. melpomene amaryllis</i>		<i>H. telesiphe</i>	
		<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>
		A	E	A	E	A	E
Colour spectra	Red FW d	4.0 \pm 1.0	1.2 \pm 0.5	2.3 \pm 0.9	0.4 \pm 0.3	4.3 \pm 1.1	9.1 \pm 1.9
	Red FW v	12.4 \pm 2.1	7.5 \pm 1.8	6.7 \pm 1.7	3.1 \pm 1.2	2.9 \pm 0.9	5.9 \pm 1.6
	Yellow HW d	1.4 \pm 0.6	0.3 \pm 0.2	1.1 \pm 0.6	0.3 \pm 0.3	53.3 \pm 8.3	66.5 \pm 10.1
	Yellow HW v	4.5 \pm 1.2	2.0 \pm 0.8	2.0 \pm 0.8	0.4 \pm 0.3	7.2 \pm 1.2	12.0 \pm 2.2
Colour pattern	Red patch FW d	82.6 \pm 11.8	64.4 \pm 11.1	34.3 \pm 4.0	17.4 \pm 2.9	561.7 \pm 62.4	579.4 \pm 62.4
	Yellow bar HW d	25.2 \pm 4.1	18.7 \pm 3.7	17.5 \pm 3.2	11.7 \pm 2.8	59.4 \pm 7.6	78.7 \pm 9.2
Wing venation	FW venation	22.6 \pm 2.7	21.4 \pm 2.5	15.1 \pm 2.3	10.3 \pm 1.9	37.2 \pm 4.4	42.0 \pm 4.8
	HW venation	25.9 \pm 2.9	24.6 \pm 2.8	12.5 \pm 2.0	12.1 \pm 1.9	34.4 \pm 3.7	35.8 \pm 4.1
Wing Outline	FW outline	18.9 \pm 4.6	16.5 \pm 3.9	13.4 \pm 3.9	12.1 \pm 3.5	32.9 \pm 7.4	36.8 \pm 8.2
	HW outline	17.3 \pm 4.6	12.2 \pm 3.5	6.9 \pm 2.2	6.8 \pm 2.4	42.8 \pm 8.0	38.5 \pm 7.5

		<i>H. timareta</i> A	<i>H. erato</i>	<i>H. telesiphe</i>	<i>H. telesiphe</i>
		<i>H. timareta</i> E	<i>H. melpomene</i>	<i>H. melpomene</i>	<i>H. erato</i>
Colour spectra	Red FW d	1.2 \pm 0.5	0.7 \pm 0.4	11.9 \pm 2.8	15.9 \pm 2.9
	Red FW v	0.9 \pm 0.5	3.3 \pm 1.3	15.5 \pm 3.2	26.1 \pm 4.0
	Yellow HW d	1.3 \pm 0.7	0.5 \pm 0.4	64.1 \pm 10.1	69.9 \pm 10.3
	Yellow HW v	1.3 \pm 0.7	1.3 \pm 0.7	14.1 \pm 2.7	22.0 \pm 3.2
Colour pattern	Red patch FW d	9.6 \pm 1.7	43.3 \pm 9.9	597.4 \pm 61.4	617.3 \pm 62.6
	Yellow bar HW d	5.0 \pm 1.1	8.7 \pm 2.1	84.7 \pm 10.6	88.1 \pm 10.9
Wing venation	FW shape	3.1 \pm 0.7	16.6 \pm 2.3	52.9 \pm 6.5	33.2 \pm 4.4
	HW shape	2.8 \pm 0.7	17.2 \pm 2.5	50.5 \pm 5.8	39.5 \pm 3.9
Wing outline	FW outline	4.7 \pm 1.7	10.3 \pm 3.2	48.4 \pm 10.6	34.1 \pm 7.2
	HW outline	3.7 \pm 1.2	14.3 \pm 3.7	64.1 \pm 11.6	44.7 \pm 9.2

Table S8. Percentage of cross-validation in the linear discriminant analysis for each component of the phenotype between each population of *H. timareta* and their co-mimics

(1 = complete discrimination between the two groups compared, 100% of the individuals can be re-identified); mean of the bootstrap + sd

		<i>H. erato</i>		<i>H. melpomene</i>		<i>H. telesiphe</i>	
		<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>	<i>H. timareta</i>
		<i>A</i>	<i>E</i>	<i>A</i>	<i>E</i>	<i>A</i>	<i>E</i>
Colour spectra	Red FW d	0.82 ± 0.04	0.69 ± 0.05	0.73 ± 0.05	0.55 ± 0.08	0.83 ± 0.03	0.92 ± 0.03
	Red FW v	0.99 ± 0.01	0.92 ± 0.03	0.90 ± 0.03	0.74 ± 0.05	0.78 ± 0.04	0.87 ± 0.03
	Yellow HW d	0.69 ± 0.04	0.54 ± 0.07	0.66 ± 0.05	0.50 ± 0.08	1.00 ± 0.00	0.99 ± 0.01
	Yellow HW v	0.85 ± 0.03	0.69 ± 0.05	0.75 ± 0.05	0.52 ± 0.09	0.98 ± 0.01	0.98 ± 0.01
Colour pattern	Red patch FW d	1.00 ± 0.00	0.99 ± 0.01	0.97 ± 0.02	0.92 ± 0.04	1.00 ± 0.00	1.00 ± 0.00
	Red patch FW v	1.00 ± 0.01	0.99 ± 0.01	0.97 ± 0.02	0.90 ± 0.04	1.00 ± 0.00	1.00 ± 0.00
	Yellow bar HW d	0.94 ± 0.03	0.94 ± 0.03	0.89 ± 0.04	0.85 ± 0.05	0.98 ± 0.01	1.00 ± 0.01
	Yellow bar HW v	0.99 ± 0.01	0.98 ± 0.02	0.96 ± 0.02	0.95 ± 0.03	0.99 ± 0.01	1.00 ± 0.01
Wing venation	FW shape	0.99 ± 0.01	0.69 ± 0.06	0.91 ± 0.04	0.85 ± 0.05	0.93 ± 0.03	0.99 ± 0.01
	HW shape	1.00 ± 0.01	0.67 ± 0.06	0.89 ± 0.04	0.90 ± 0.04	0.90 ± 0.04	1.00 ± 0.01
	FW outline	0.93 ± 0.03	0.92 ± 0.04	0.84 ± 0.05	0.85 ± 0.05	0.99 ± 0.01	0.99 ± 0.01
	HW outline	0.89 ± 0.04	0.86 ± 0.05	0.74 ± 0.05	0.76 ± 0.06	0.98 ± 0.01	0.98 ± 0.02
			<i>H. timareta A</i>	<i>H. erato</i>	<i>H. telesiphe</i>	<i>H. telesiphe</i>	
			<i>H. timareta E</i>	<i>H. melpomene</i>	<i>H. melpomene</i>	<i>H. erato</i>	
Colour spectra	Red FW d		0.70 ± 0.05	0.61 ± 0.06	0.92 ± 0.03	0.98 ± 0.01	
	Red FW v		0.64 ± 0.05	0.80 ± 0.05	0.97 ± 0.02	1.00 ± 0.00	
	Yellow HW d		0.66 ± 0.05	0.58 ± 0.06	1.00 ± 0.00	1.00 ± 0.00	
	Yellow HW v		0.65 ± 0.05	0.63 ± 0.06	0.98 ± 0.01	1.00 ± 0.00	
Colour pattern	Red patch FW d		0.84 ± 0.05	0.98 ± 0.02	1.00 ± 0.00	1.00 ± 0.00	
	Red patch FW v		0.85 ± 0.05	0.97 ± 0.02	1.00 ± 0.00	1.00 ± 0.00	
	Yellow bar HW d		0.75 ± 0.05	0.81 ± 0.05	1.00 ± 0.00	0.99 ± 0.01	
	Yellow bar HW v		0.79 ± 0.05	0.91 ± 0.04	1.00 ± 0.00	1.00 ± 0.00	
Wing venation	FW shape		0.69 ± 0.06	0.85 ± 0.05	1.00 ± 0.01	0.93 ± 0.03	
	HW shape		0.67 ± 0.06	0.90 ± 0.04	1.00 ± 0.01	0.90 ± 0.04	
Wing outline	FW outline		0.68 ± 0.06	0.84 ± 0.05	0.99 ± 0.01	0.98 ± 0.02	
	HW outline		0.66 ± 0.06	0.89 ± 0.04	1.00 ± 0.01	0.98 ± 0.02	

Hybrid detection and population structure

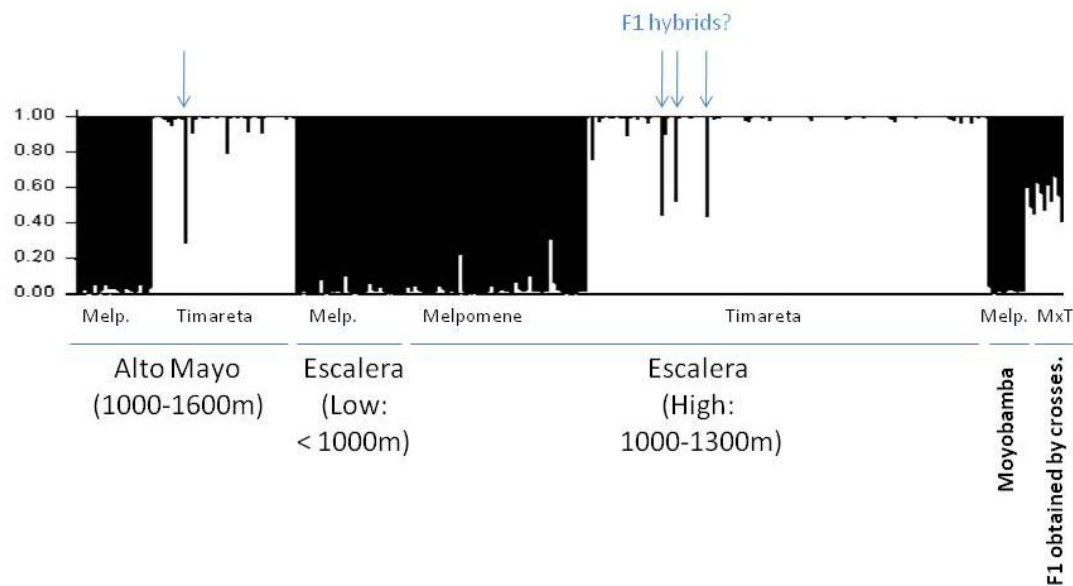


Figure S11. Multilocus Bayesian clustering and assignment analysis with STRUCTURE 2.3.1.

Each individual is represented by a column and the colour represents the relative genome contribution of each cluster. The blue arrows point to the specimens identified as F1 hybrids with other assignment analyses (NewHybrids).

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