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# Low Power Load Interface For Vibrational Energy MEMS harvesters

M. Bedier

Universite Pairs-Sorbonne, UPMC Paris 6, LIP6 Paris, France Mohammed.bedier@lip6.fr

*Abstract*— Electrostatic vibrational energy harvesting is an appealing source power for self powered wireless sensors. With many pervious successful implementation of energy harvesters, a power efficient load interface is needed. This article describes multiple energy-shot load interface for vibrational energy MEMS harvester with a low power decision mechanism.

Keywords— Energy harvesting; MEMS; Electrostatic converters; Ambient vibration

#### I. INTRODUCTION

The harvesting of ambient energy has gained increased interest with the emerge of IoT revolution specially with the need of self power sensors and energy aware electronics design. Electrostatic energy harvesting is among the promising techniques to extract the ambient energy and use it instead of traditional battery cells. The energy is harnessed by taking advantage of the vibrational force and allowing it to act against an electrostatic force by the mean of a conditioning circuit (CC). The Miniaturized Vibrational electrostatic energy harvesters (e-VEH) are implemented using a variable capacitor MEMS free to move with the mechanical vibration, thus disturbing the charges in the CC which results in an accumulated energy on a reservoir capacitor ( $C_{res}$ ).

A completed energy harvesting system is composed of a CC, load interface (LI) and output voltage regulator. The CC extracts the energy from ambient vibration, while the output voltage regulator guaranties a constant voltage supplied to the load. Due to the nature of e-VEH, the harvested energy on  $C_{res}$  can exhibit a high voltage as well as large - yet slow - variations. Thus, a load interface (LI) is needed as an intermediate stage between the CC and the voltage regulator. The e-VEH and CC have been studied extensively, such as in [1]-[4]. However, a LI that efficiently transfers the harvested energy to a temporary low voltage load buffer  $C_{buffer}$ , were merrily addressed. This work presents a low power LI with a multiple energy-shot scheme.

#### II. LOAD INTERFACE ENERGY MANAGEMENT

#### A. Energy harvester system discreption

The energy is harvested by a conditioning circuit (CC) as shown in Figure 1. The CC shown is one of various circuits implementing rectangular QV cycles and is chosen for demonstration purpose. It is a charge pump CC based on [4] with a flyback architecture. The LI maintains the CC at the maximum energy extraction interval, and stores the harvested energy to be later regulated for the load.

Dimitri Galayko Universite Paris-Sorbonne, UPMC Paris 6, LIP6 Paris, France Dimitri.galayko@lip6.fr

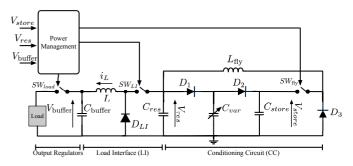


Fig. 1. E-VEH energy harvesting system with LI and voltage regulator.

The LI is a switched inductor capacitive architecture. It is composed of an inductor (L), freewheeling diode (D<sub>L1</sub>), buffer capacitor (C<sub>buffer</sub>) and a high side high voltage switch (SW<sub>L1</sub>). The C<sub>buffer</sub> is a temporary low voltage storage capacitor. The switches SW<sub>L1</sub> and SW<sub>load</sub> are used to activated/deactivate the LI and load regulator. The switching decision are made by a power management system.

#### B. Multiple shot energy transfer

For maximum harvested energy rate, the reservoir voltage  $V_{res}$  is contained with in an optimum interval [5][6]. During the harvesting operation, if  $V_{res}$  exists its optimum interval, it is forced back by activating the LI thus transferring a part of its energy into  $C_{buffer}$ . Nevertheless,  $V_{res}$  is guarantied not to fall below the optimum interval, as the LI is then deactivated, allowing  $V_{res}$  to recover back using the continuous generation of energy by the CC. The optimum interval is defined as  $V_{resL} < V_{res} < V_{resH}$ , where  $V_{resH}$  and  $V_{resL}$  are the high and low optimum energy harvesting interval thresholds. Assuming a lossless energy transfer, the energy to be removed from  $C_{res}$  to drop its voltage from  $V_{resH}$  to  $V_{resL}$  is,

$$\Delta W = \frac{1}{2} C_{res} (V_{resH}^2 - V_{resL}^2) \tag{1}$$

This energy is transferred through the inductor (L) with a current  $(i_L)$  defined as,

$$i_L(t) = \sqrt{\frac{c_{eq}}{L}} \left( V_{\text{buffer}_0} - V_{res_0} \right) \sin(\omega t), \ 0 < t < t_{on}(2)$$

Where,  $t_{on}$  is the ON time of the switch SW<sub>LI</sub> required to transfer  $\Delta W$ ,  $\omega = \sqrt{1/LC_{eq}}$  and  $C_{eq}$  is the equivalent capacitance of C<sub>buffer</sub> and C<sub>res</sub>.

The technology of which the switch is implemented sets an upper limit on the inductor current ( $I_{Lmax}$ ). Nevertheless, high

inductor current may result in large I<sup>2</sup>R losses as well as device stress. To transfer  $\Delta W$  without exceeding I<sub>Lmax</sub>, the energy is transferred in a multiple of shots instead of a single shot as shown in Figure 2. Each shot is of a fixed duration (t<sub>shot</sub>) with two phases of operation. In the first phase a part of energy ( $\delta W_n$ ) is removed from C<sub>res</sub> during t<sub>I</sub>, while the second phase allows  $W_n$  to accumulate on C<sub>buffe</sub> for t<sub>II</sub>. This process is repeated *n* times until  $\Delta W$  is extracted from C<sub>res</sub>. The next section describes transistor level implementation of the load interface.

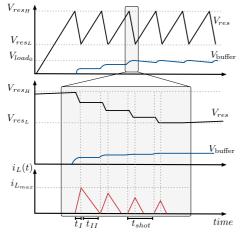


Fig. 2. Evolution of V<sub>res</sub>, V<sub>buffer</sub> and i<sub>L</sub> in mulitple shot energy transfer.

#### III. LOAD INTERFACE CONTROLLER

The load interface controller is implemented using a 0.35µm technology by AMSH35. First,  $V_{res}$  is sampled by a voltage divider using one of two sampling frequencies corresponding to two modes (idle and switching). The idle mode is activated when  $C_{res}$  accumulates energy from the harvester, while the switching mode is when  $C_{res}$  transfers  $\Delta W$  to  $C_{buffer}$ . Second, the sampled scaled version of  $V_{res}$  is introduced to an RS-trigger based hysteresis comparator with its hysteresis gap fitted to the optimum interval of  $V_{res}$ . The comparator output controls SW<sub>LI</sub> state, the clock selection and multiple energy shot pulse generations. Figure 3 shows the schematic of the LI controller.

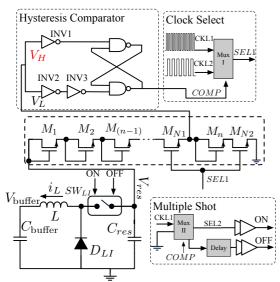


Fig. 3. Schematic of Load Interface Controller.

#### IV. SIMULATION AND RESULTS

The load interface and its controller is simulated with the design parameters of L = 15mH,  $C_{res} = 1\mu$ ,  $C_{buffer} = 20\mu$ F, and optimum interval of  $7V < V_{res} < 6V$ . The maximum allowed inductor current  $I_{Lmax} = 15$ mA defines  $t_I = 25\mu$ s and  $t_{II} = 375\mu$ s. The simulation shown in Figure 4 shows the energy transfer process. The power consumption is mainly by the hysteresis comparator, which has maximum instantaneous power consumption of 13.67n Watt. The energy consumed by the comparator in 10ms duration is 126.52p Joules.

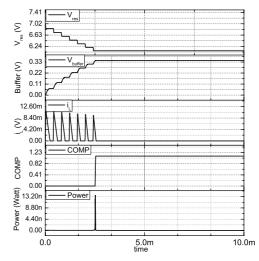


Fig. 4. Load interface controller simulation showing instantnous power consumption of the hysteresis compartor.

#### V. CONCLUSION

A load interface is presented for vibrational energy harvesters with a multiple energy shot interface. The comparator energy consumption of the load interface is substantial decreased by using an RS-trigger based comparator. Further optimization of other supporting blocks, such as the multiplexers and clocks, can help decrease the power consumption. The ongoing work is toward fully integrating the harvester with the load interface and achieve autonomous operation.

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