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9 Abstract

Low induction number EMI instruments are able to simultaneously measure a soil's 10 apparent magnetic susceptibility and electrical conductivity. This family of dual measurement 11 instruments is highly useful for the analysis of soils and archaeological sites. However, the 12 electromagnetic properties of soils are found to vary over considerably different ranges: 13 whereas their electrical conductivity varies from ≤ 0.1 to ≥ 100 mSm⁻¹, their relative magnetic 14 permeability remains within a very small range, between 1.0001 and 1.01 SI. Consequently, 15 although apparent conductivity measurements need to be inverted using non-linear processes, 16 the variations of the apparent magnetic susceptibility can be approximated through the use of 17 linear processes, as in the case of the magnetic prospection technique. 18

Our proposed 3D inversion algorithm starts from apparent susceptibility data sets, acquired using different instruments over a given area. A reference vertical profile is defined by considering the mode of the vertical distributions of both the electrical resistivity and of the magnetic susceptibility. At each point of the mapped area, the reference vertical profile response is subtracted to obtain the apparent susceptibility variation dataset. A 2D horizontal Fourier transform is applied to these variation datasets and to the dipole (impulse) response of each instrument, a (vertical) 1D inversion is performed at each point in the spectral domain, and finally the resulting dataset is inverse transformed to restore the apparent 3Dsusceptibility variations.

It has been shown that when applied to synthetic results, this method is able to correct 28 the apparent deformations of a buried object resulting from the geometry of the instrument, 29 and to restore reliable quantitative susceptibility contrasts. It also allows the thin layer 30 solution, similar to that used in magnetic prospection, to be implemented. When applied to 31 field data it initially delivers a level of contrast comparable to that obtained with a non-linear 32 3D inversion. Over four different sites, this method is able to produce, following an 33 acceptably short computation time, realistic values for the lateral and vertical variations in 34 35 susceptibility, which are significantly different to those given by a point-by-point 1D inversion. 36

37

38 Key-words: Magnetic susceptibility of soils, frequency domain EMI, 3D inversion of in39 phase susceptibility measurements

40

41 Introduction

Soil is produced by various complex processes, to which human activities can make a 42 significant contribution. A complete, continuous and non-invasive description of a soil's 43 structure is thus of primary importance in terms of improving our knowledge of ancient 44 societies, and ensuring more relevant management of the current environment. Geophysical 45 surveys have thus been recognized as an indispensable tool for subsurface environmental 46 studies (Butler 2005, Viscarra-Rossel et al. 2010). In addition to its electrical resistivity, the 47 soil's magnetic properties have sufficient variability, and are sufficiently related to past and 48 present active pedological processes (namely redox) (Evans and Heller 2003, Liu et al. 2012), 49 to motivate their utilization in ground prospection campaigns. Magnetic prospection has been 50

the most commonly used technique in archeological applications (Aspinall et al. 2008), in 51 52 which spatial variations of the Earth's magnetic field, and thus all variations in the ground's total magnetization, are measured. However, this technique fails to describe the vertical 53 layering of a terrain, and is thus less useful for pedological applications in which it is 54 important to identify the magnetic properties of each horizon; moreover, its ability to detect 55 lens-like features is very poor (Scollar et al. 1990). These limitations confirm the potential 56 usefulness of small, frequency-domain electromagnetic (also referred to as Slingram, loop-57 loop, or dipole-dipole) instruments, which can simultaneously measure the ground's apparent 58 electrical conductivity and magnetic susceptibility (Parchas and Tabbagh 1978), and can now 59 60 be fitted with a multi-receiver capability (Saey et al. 2012, Bonsall et al. 2013).

The present paper focuses on the interpretation of measurements of the 61 ground's in-phase magnetic susceptibility. Other measurements, such as that of the ground's 62 63 magnetic viscosity (Thiesson et al. 2007), or measurements combining both EMI and the magnetic technique, are reported to be highly advantageous in certain contexts (Benech et al. 64 2002, Pétronille et al. 2010). The aim of the present study is to assess the performance of a 65 fast 3D linear interpretation algorithm, which is easy to implement on a laptop computer. 66 Through the use of the Moment Method (MoM), fast 3D inversion processes have already 67 been proposed for DC resistivity prospection (Brinon et al. 2012), and for the simultaneous 68 interpretation of electrical conductivity and magnetic susceptibility EMI data (Benech et al. 69 2016), whilst this processes is limited to reduced areas in the vicinity of targeted features. In 70 the following, an inversion technique is proposed for the processing of magnetic susceptibility 71 72 variation data derived from the MoM. Since the relative magnetic permeability of the soil varies only slightly (between 1.0001 and 1.01), it has been verified (Tabbagh 1985) that the 73 74 Born approximation can be applied to the analysis of such data, thus paving the way for the use of linear inversion techniques: this is a sound approximation, and is systematically used in 75

magnetic prospection when the so-called demagnetizing field is neglected (Grant and West 1965, Scollar et al. 1990). On the other hand, it cannot be applied in the case of DC resistivity (Dabas et al. 1994, Buvat *et al.* 2013) or conductivity electromagnetic (EM) methods because the soil's electrical conductivity varies over a wide range, between ≤ 0.1 and ≥ 100 mS/m. The implementation of a linear method has the advantage of being more efficient computationally, thus allowing the entire surveyed surface to be processed in one go.

Our proposed interpretation process is divided into two phases. In the first of these, the 82 usual 1D non-linear inversion scheme is applied, point by point, to determine the vertical 83 distributions of both electrical conductivity and magnetic susceptibility (Zhang and 84 Oldenburg 1999). These vertical distributions are often sufficient to allow the terrain's 85 structure to be characterized. If marked lateral changes require a 3D inversion the statistical 86 mode of these distributions as a function of depth is taken to be the reference vertical profile. 87 88 Then, during the second phase, the interpreter determines the lateral variations in susceptibility with respect to this profile. Since the response of a contrasting magnetic body 89 can be assumed to be linear, this process involves successively applying a 2D (horizontal 90 91 plane) Fourier transform, non-linearly inverting the resulting spectrum of the 1D vertical distribution of magnetic susceptibility contrasting with respect to the reference profile, and 92 finally computing the lateral susceptibility contrast variations by means of an inverse Fourier 93 transform. The full process is illustrated in Figure 1. 94

95

96 **Reminder of the 1D inversion process**

97 The EMI instruments under consideration have a transmitting coil and at least one 98 receiving coil at a metric separation expressed by *L*. The coils are located at a height *d*, above 99 ground level. The coil orientations can be adjusted, and various possible configurations have 100 been defined (Frischknecht et al. 1991) with respect to the plane of the coils. The most

commonly used configurations are HCP (horizontal coplanar), VCP (vertical coplanar), 101 PARA (parallel – inclined at 55° from the horizontal plane), and PERP (perpendicular). The 102 application of the instrument's primary field over a layered ground generates complex 103 secondary fields, H_s , which are expressed by Hankel Transform integrals. The full 104 development of these expressions, and the definition of the subsequent approximations are 105 described by Thiesson et al. (2014). The method used to compute these transforms (i.e. the 106 forward problem) is well known, and is similar to that used for vertical electrical sounding 107 (Ghosh 1971). The calculation results can be expressed in terms of apparent properties, this 108 allows an initial approximate evaluation to be made of the soil's properties, thus simplifying 109 comparisons between different instruments. The apparent magnetic susceptibility, κ_a , is the 110 susceptibility of a homogeneous terrain that would produce the same results with the same 111 instrumental geometry (L, coil orientation, height above the surface). 112

113 The inverse problem is usually solved by starting from an *a priori* guess at the values of the unknown parameters, which are iteratively modified until a good fit between the 114 computed results and the apparent experimental properties is reached. The number of 115 116 parameters is limited by the number of different geometrical configurations which can be adopted by the instrument (coil orientations and L distances), since at the studied frequencies 117 (VLF and LF) and depth ranges, the investigation depth is governed by the instrument 118 geometry. Although a single parameter inversion can sometimes be useful (Guerin et al. 119 1996), several instruments (or a multi-coil configuration in the same apparatus) clearly 120 provide a more detailed description of the terrain's structure. 121

It is important to note that with EMI data inversion, the vertical conductivity profile must first be determined (using the quadrature out of phase component of the responses), prior to inversion of the magnetic susceptibility profile because: (1) the conductivity distribution modifies the total magnetic field distribution in the ground, whereas the terrain's vertical susceptibility distribution has a negligible influence on the total magnetic field
distribution (Tabbagh 1985) and (2) when high, the conductivity may generate an in-phase
response (Thiesson et al. 2014) that must be subtracted from the total in-phase response.

129 At the end of the 1D inversion step, the statistical mode of each model parameter is 130 adopted, in order to define the reference vertical profile. A susceptibility response $\kappa_{a0}(d)$ is 131 associated with this profile, and is subtracted from the experimental response at each point (*x*, 132 *y*) of the surveyed area, and for each receiver (at elevation *d*), thereby defining a contrasting 133 magnetic susceptibility response $\delta \kappa_a(x, y, d)$.

134

135 **2D** (x,y) inversion using a Fourier transform

136 *Principle*

137 Given $\delta \kappa(x',y',z')$, the contrasting magnetic susceptibility distribution inside the 138 ground, and since the problem to be solved is linear, the response $\delta \kappa_a(x, y, d)$ that is added to 139 the response of the reference profile can be expressed as a convolution product:

140
$$\delta \kappa_a(x, y, d) = \iiint_{\infty} \delta \kappa(x', y', z') IR(x - x', y - y', d - z') dx' dy' dz'$$
(1),

where *IR* is the 'impulse response', the 3D Green function corresponding to the dipole source response to the instrumental configuration under consideration (analytical expressions corresponding to these functions are presented in more detail in (Tabbagh 1985)). If the ground is discretized in the form of *N* successive layers having thicknesses e_i centered at z_i , and a magnetic susceptibility contrast $\delta \kappa(x', y', z_i)$, equation (1) can be approximated by:

146
$$\delta \kappa_a(x, y, d) = \sum_{i=1}^N e_i \iint_{\infty} \delta \kappa(x', y', z_i) IR(x - x', y - y', d - z_i) dx' dy'$$
(2).

147 By applying a 2D Fourier transform to Eq. (2) one has:

148
$$\delta\hat{\kappa}_{a}(u,v,d) = \sum_{i=1}^{N} e_{i}\delta\hat{\kappa}(u,v,z_{i})R\hat{I}(u,v,d-z_{i})$$
(3),

where a 'circumflex accent' indicates Fourier transformed functions, and (u, v) are the spatial 149 150 frequencies corresponding to (x, y). Consequently, at each point (u, y) the expression for Eq. (3) corresponding to each level z_i can be thought of as a single component of an N-151 equation linear system. If the number of different geometric coil configurations K is smaller 152 than N, the system has no solution, however when K = N it can be solved directly. When 153 K > N the system can be solved using the least squares method. Knowing $\delta \kappa(u, v, z_i)$, it is 154 straightforward to derive the solution for the problem of 3D susceptibility contrast via the 155 inverse transformation of $\delta \hat{\kappa}(x, y, z_i)$. 156

157

158 The thin layer solution

Although commercial multi-configuration instruments are now commonly available 159 and used in field surveys, a considerable volume of data has been acquired over the last forty 160 years using just one type of configuration. It is thus important to reconsider and enhance the 161 interpretation of this data. When a single configuration is used, only one layer can be 162 163 considered and the resulting thin-layer interpretation is similar to that obtained with potential methods (Grant and West 1965). In the case of magnetic prospection, this is a valuable 164 solution (Desvignes et al. 1999) since it allows: (i) the general pattern of the source body to be 165 restored by correcting for the influence of the Earth's magnetic inclination on the shape of the 166 anomaly; (ii) the maximum source depth to be assessed, and (iii) the magnetization contrast to 167 be determined. Similar issues arise when interpreting EMI apparent magnetic susceptibility 168 data: deformations introduced by the coil configuration, poor accuracy of depth assessments, 169 170 and the contrast of any source body. This similarity has made it possible to use 171 transformations between apparent susceptibility measurements and induced magnetization anomalies of the Earth's magnetic field, and has opened up significant perspectives for the 172 simultaneous interpretation of both types of data (Benech et al. 2002). In the present study, 173

our analysis is limited to that of EMI measurements, for which the determination of the depth of the thin layer raises a specific issue: a relationship clearly does exist between the coil separation and the depth at which a susceptibility variation can be detected, if the sensitivity at a depth is too low, then the inversion near that depth will be poor.

We thus consider a series of synthetic cases, in which a 2m x 2m slab with a thickness 178 of 0.2 m and susceptibility contrast equal to 200 10^{-5} SI is displaced along the vertical axis. 179 The apparent susceptibility maps are inverted for each different position (change in depth) of 180 the slab, and the quality of the inversion is assessed by comparing the susceptibility contrast 181 produced by the inversion with the original value. Table 1(a) presents the results obtained for 182 the different depths of the slab and coil separations using VCP configuration. Table 1(b) 183 provides the results with the PERP configuration, Table 1(c) the results with the HCP 184 configuration, Table 1(d) the results with the PARA configuration. Four main conclusions can 185 186 be drawn for these comparisons:

187 (1) With the VCP configuration, the slab is correctly restored, even for a coil 188 separation of L=2m and shallow slab depths, as well as for smaller coil separations and 189 greater depths.

(2) With the PERP configuration, the results are comparable to those for the VCP
configuration, and (with the exception of shallow slabs with VCP) the inverted values are
generally 10% to 20% higher than the original values. For shallower slabs the outcome can
probably be explained by the more complex lateral variations of the PERP dipole impulse
response, and thus more problematic inversion of PERP data.

195 (3) With the HCP and PARA configurations the sign of the contrast is correctly 196 restored (the apparent susceptibility anomaly is negative for greater d/L ratios with HCP) but 197 not its magnitude (most often significantly amplified) (4) This preceding example, established using synthetic data, shows that good depthsof investigation can be reached, even for the case of smaller values of *L*.

However, even for one thin layer, the simultaneous use of several configurations leadsto slightly better results than the use of a single configuration.

202

203 Multi-layer inversion

At each point of the spectral domain, the solution $\delta \kappa(u, v, z_i)$ is represented by an N 204 component vector $\delta \vec{\kappa} = (\kappa_1, ..., \kappa_N)$, the solution for the linear equation system. While in 205 practice limited to few components, the solution for the N linear equations system is 206 207 confronted by an instability arising from the fact that an abnormal value in one layer can be compensated by another abnormal value, of the opposite sign, in another layer. The solution 208 can be stabilized by adding an external constraint, for example by minimizing the norm of the 209 solution vector. Although it is also possible to use this constraint to introduce the depth 210 sensitivity dependence associated with each coil configuration, this sensitivity tends to be of 211 212 the 'all or nothing' type, as shown in Table 1. Following several tests, two options were found to be potentially useful: either minimizing the square of the norm of the $\delta \vec{\kappa}$ vector (constraint 213 214 I):

215
$$Q = \sum_{1}^{N} \hat{\kappa}_{i}^{2}$$
, (4),

or minimizing the sum of the squares of the differences between consecutive components(constraint II):

218
$$Q = \sum_{2}^{N} (\widehat{\kappa}_{i} - \widehat{\kappa}_{i-1})^{2}$$
(5).

219 Thus, for *K* different instruments the minimized quantity is:

220
$$\sum_{j=1}^{K} \left(\delta \hat{\kappa}_{a, \exp, j} - \delta \hat{\kappa}_{a, theo, j}\right)^2 + \lambda Q \qquad (6),$$

where λ is chosen by the interpreter: for the second option the value $\lambda = 1$ would be set, whereas with the first option it is more convenient to use the trace of the Jacobian matrix: $\lambda = trace/2$. With constraint II the stabilization is stronger, the vertical variation of the magnetic susceptibility contrast minimum.

The application of this inversion procedure using synthetic data computed for PERP, VCP and PARA configurations and inter-coil distances varying between 0.7 and 1.5 m is presented in Table 2 for the case of constraint II and for λ =1. The body is 2m x 2m x 0.6m sized, it presents a 200 10⁻⁵ SI susceptibility contrast, it is centered at z=0.5 m and divided in 5 layers (0.12m thick). Equivalently good results were obtained with reduced number of layers equal to: 3 (0.2 m thickness) or 4 (0.15 m thickness).

231

232 Tests with multi-body synthetic data

We consider a rectangular 25 m x 17 m area, meshed onto a regular 0.5m x 0.5m grid, 233 containing four different magnetic bodies (Fig. 2) imbedded in a terrain with a homogeneous 234 resistivity equal to 70 Ω m, and susceptibility equal to 30 10⁻⁵ SI. The first body (A) is an L-235 shaped ditch with a 1m x 0.4 m cross section, centered at a depth of 0.4 m, the two 236 perpendicular branches of which are 8 m in length and have a susceptibility contrast of 237 $120 \ 10^{-5}$ SI. The second body (B) is a medium-sized square body with dimensions $2m \ x \ 2m \ x$ 238 0.75 m, centered at a depth of 0.6 m and having a susceptibility contrast equal to $100 \ 10^{-5}$ SI. 239 The third body (C) is a small superficial feature with dimensions 0.4m x 0.4m x 0.2 m, 240 centered at a depth of 0.3 m depth and having a susceptibility contrast equal to $100 \ 10^{-5}$ SI. 241 The fourth body (D) is a slim feature with dimensions 0.4m x 0.4m x 1.6 m, centered at a 242 depth of 1 m and having a susceptibility contrast equal to $100 \ 10^{-5}$ SI. The apparent magnetic 243 susceptibility maps computed using MoM are shown in Fig. 3, for the seven different 244 apparatus geometries described in Table 3. For all configurations, the transmitter-receiver 245

246 line lies parallel to the x axis. The four features, with their different geometries, can be 247 recognized in each map. These are characterized by ringing, especially in the case of the 248 longest coil separations. It should be noted that the shortest apparatus provides the best 249 description of the four magnetic bodies, in terms of the shape and the magnitude of the 250 associated anomalies.

The seven datasets were inverted together, whilst considering three layers with 251 different values of magnetic susceptibility, the first centered at $z_1=0.3$ m with a thickness 252 $e_1=0.2$ m, the second centered at $z_2=0.5$ m with a thickness $e_2=0.2$ m, and the third centered at 253 $z_3=0.8$ m with a thickness $e_3=0.4$ m. When 1D inversion is applied (Fig. 4), although the four 254 255 features are correctly identified, this inversion fails to correct for their deformed shapes and for the apparent anisotropy, produced by the different coil orientations. This issue is 256 particularly pronounced for small features, whose precise locations are difficult to restore. In 257 258 addition, ringing with sign changes cannot be eliminated, and is even amplified in the third layer in which there should be no variations corresponding to the superficial features (A) and 259 (C). These spurious variations are a consequence of the instrument's low sensitivity to 3D 260 changes at the depth of these features. 261

The results produced by 3D linear inversion are presented in Fig. 5, showing that the body's shapes are faithfully restored, and the susceptibility values are in good agreement with the original values for the first two layers. However, in the case of feature (A) the third layer is again characterized by greater amplitude variations, resulting from the fact that the instruments' sensitivities are too low to constrain the solution.

267

268 Interpretation of field data

In order to assess the potential of this approach for data inversion under field conditions, we analyzed the data acquired using various instrument geometries, at four different archaeological sites characterized by different climatic conditions and soil environments. In all cases we started from the apparent susceptibility data sets which have been obtained after checking the instrument calibration (Thiesson et al. 2014) and transforming the in-phase secondary field measurements. Where the electrical conductivity is high (Medamud case), the apparent electrical conductivity was first determined using the quadrature response and then used to calculate the in-phase response which was algebraically subtracted from the total in-phase response.

278

279 Neolithic enclosure at Balloy (Seine et Marne, France)

The eastern section of this middle-neolithic 'Passy' type of funeral enclosure (Mordant 280 1997) has been the object of multi-method tests. This enclosure was detected using both 281 electrical (1 m square array) and SH3 prospection (see appendix 1 for the characteristics of 282 the latter device), but was not detected by magnetic prospection using a fluxgate gradiometer 283 with 1 nTm⁻¹ sensitivity (Hesse 1987). This failure was explained by the use of a 3D non-284 285 linear inversion (Bénech et al. 2016), applied to a selected zone (indicated by a rectangular outline in Fig. 6), showing that the SH3 measurements had revealed a 1.4m x 0.4 m cross-286 sectional feature, surrounded by gravel, with magnetic susceptibilities of respectively 51 x 10⁻ 287 5 and 20 x 10⁻⁵ SI. Using these parameters, the induced magnetization anomaly determined for 288 a fluxgate vertical gradiometer is less than 0.5 nTm⁻¹, and even with the addition of viscous 289 magnetic remanent magnetization the anomaly cannot clearly overpass 1nTm⁻¹. 290

In the present study we consider just one layer (since only one instrumental dataset was recorded), of 0.4m thickness and centred at a depth of 0.45m. For the same selected zone, the following results are obtained:

(1) as could be expected, the 1D inversion produces the same image as that generatedusing the apparent susceptibility measurements (Fig. 6b),

(2) the susceptibility variations are in agreement with the 3D non-linear inversion, with a magnetic susceptibility of 40 10^{-5} SI for the ditch filling, in contrast with a value of 10 x 10^{-5} SI for the immediately surrounding gravel. This calculation was made for the totality of the 26m x 26 m surface shown in Fig. 6, and required just 7s of computing time, whilst using the same laptop computer (4 Go RAM, 2.5 GHz) the non-linear inversion over the 2.5m x 5m area required 267s of computing time.

302

303 Neolithic settlement of Perdika 2 (Central Greece)

This neolithic settlement, in this region referred to as a *magoula*, is located on the 304 eastern Thessalian plain of Greece and was surveyed using different methods in the frame of 305 the IGEAN project (Innovative Geophysical Approach for the study of Early Agriculture 306 villages of Neolithic Thessaly) (Simon et al., 2015). The magnetic survey revealed a complex 307 308 system of enclosures (Fig. 7). In order to acquire a better description of what is thought to be an enclosure entrance, a 40m x 40m area was prospected using the CMD instrument (see 309 310 Appendix I for its characteristics). The ditches are more clearly discernible by their magnetic 311 susceptibility contrast than by their electrical conductivity. The resistivity variations are relatively small, lying within a moderate range of values: a 150 Ω m layer of topsoil, and 312 subsoil variations ranging between 30 and 100 Ω m. As the magnetic susceptibility data 313 acquired with the shorter coil separation (L=0.32m) was too noisy for suitable interpretation. 314 we made use of four data sets for the inversion (Fig. 8): HCP with 0.71 m and 1.18 m 315 separations, and VCP with 0.71 m and 1.18 m separations. The topsoil layer was assumed to 316 be homogeneous. In order to assess the vertical extent of the archaeological features, we 317 chose to divide the subsoil into two contiguous layers of 0.5 m thickness, with the first lying 318 319 between 0.2 and 0.7 m, and the second between 0.7 and 1.2 m. The images produced by point-by-point 1D inversion and by 3D linear inversion of the data are presented in Figs. 9a 320

and 9b, respectively. In the 1D inversion, the second layer reveals some features that are different to those found in the first layer, which is characterised by strong susceptibility variations. Also performed using constraint I, see equation (4), the 3D linear inversion shows that the ditches are shallow, and that different features appear at greater depths, but with smaller variations in susceptibility.

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- 327

7 Middle Kingdom Kôm of Medamud (Egypt)

The site of Medamud is located 4 km to the north of Karnak, and was occupied for a 328 long period of time, from the Middle Kingdom of Egypt until the Roman era (Relats-329 330 Montserrat 2016(a)). The geophysical survey initiated by the IFAO tended to characterize a Middle Kingdom pottery workshop area. The survey was carried out with the CMD (see 331 Appendix I) instrument in a VCP configuration, in order to simultaneously describe the soil's 332 333 electrical conductivity and magnetic susceptibility. In the area under consideration the finegrained, thick archaeological layer present just below the surface has a very low resistivity, 334 centred on 16 Ω m, for which a correction is required to eliminate the in-phase component of 335 the conductivity response 336

In the present study we consider a 44m x 60m zone from this site. Fig. 10 shows three 337 apparent susceptibility maps, produced using inter-coil distances of 0.32, 0.71 and 1.18 m, 338 respectively. Fig. 11 shows the results of the inversions when two layers are considered, with 339 the first situated between 0.05 and 0.35 cm, and the second between 0.35 and 0.65 m: Fig. 11a 340 and Fig. 11b show the results of the 1D and 3D inversions (both using constraint I), 341 respectively. Both inversions show that the magnetic features have a significant vertical 342 extent (which probably exceeds the range of the instrument), and that their susceptibilities are 343 high. However, comparisons between these different results underscore the fact that when 1D 344 inversion is used, the second layer has higher values, in the range $[350 - 1250] 10^{-5}$ SI, 345

whereas the first layer remains close to a modal value of 200 10^{-5} SI, which is the same as that found for both layers with the 3D inversion. Again in this case, the second layer of the 3D inversion is characterised by a narrower range of variations ([180 – 225] 10^{-5} SI) than the first layer ([130 – 330] 10^{-5} SI).

These maps clearly show the presence of a mud brick wall which corresponds to lower 350 apparent susceptibilities. By comparing these results with measurements (MS2D Bartington 351 Ltd) taken over another feature we obtain values in the range $[60 - 90] 10^{-5}$ SI for the mud 352 bricks and a modal value of 178 10⁻⁵ SI for the surrounding magnetic soil (Relats-Montserrat 353 et al. 2016(b)). When applying a full 3D inversion to the rectangular 12m x 3 m area (marked 354 in Figure 11b) we obtain, by considering a wall of 0.6m thickness and 4m width, a 355 susceptibility contrast of -92 10⁻⁵ SI with the surrounding soil. These results are in fair 356 agreement with the results mapped in Figure 10b and with the 3D linear inversion using one 357 layer of 0.6m thickness which gives a $-100 \ 10^{-5}$ SI susceptibility contrast. 358

359

360 Destroyed medieval city of Thérouanne (Pas-de-Calais, France)

Thérouanne was originally a Gallic, then an important Gallo-roman city, and during 361 medieval times was one of the main centres of the Picardie region in France. In 1553 it was 362 besieged and totally levelled by Charles Quint. This location was settled again as a small 363 village, only at the end of the XIXth century. The aim of the survey was to identify the 364 remains of the ancient medieval city, through a series of EMI and electrical prospection 365 campaigns. The test area considered here covers a surface area of 180m x 40m, and was 366 surveyed using the DualEM instrument (see Appendix I) in both HCP and VCP base 367 configurations. From this archaeological survey, we produced six different apparent magnetic 368 susceptibility maps, derived from the instrument's in-phase recordings made with the HCP 369 1m, HCP 2m, PERP 1.1m, PERP 2.1m, VCP 1m and VCP 2m configurations. In the present 370

analysis, the longest inter-coil separations of 4 m and 4.1m were not used, and the HCP 1m
and PERP 2m channels produced corrupted data. Thus, only four independent magnetic
susceptibility maps could be used, as shown in Fig. 12.

374 The electrical resistivity maps of the terrain reveal a 70 Ω m topsoil layer, followed by a conductive subsoil layer with a resistivity between 10 and 60 Ω m, suggesting a significant 375 clay content (the salt spread under the order of Charles Quint was probably leached out well 376 before the time of the prospection campaign). The apparent magnetic susceptibility is 377 generally high, and higher for the PERP 1m and HCP 2m measurements than for both VCP 378 configurations (different susceptibility scales are used in Fig. 12). The change in sign of the 379 380 susceptibility response for the HCP 2m measurement, at approximately 0.75m, suggests that most of the observed features have shallow locations. Three layers were considered for the 381 inversions: the first between 0.25 and 0.75 m; the second between 0.75 and 1.25 m; and the 382 383 third between 1.25 and 2.25 m. The results of the 1D point-by-point inversion are presented in Fig. 13, and those of the 3D linear inversion are shown in Fig. 14. Constraint I was applied for 384 both inversions. Although the mean values of susceptibility decrease slightly with depth in the 385 386 1D inversion, the lateral variations have the same aspect and reproduce those of the four apparent susceptibility maps. A large, 40 m diameter semi-circular feature, centred 18m to the 387 north of the image centre, can be seen in all three layers, thus suggesting that it has a 388 substantial vertical extent. In the 3D inversion, the first layer is clearly more magnetic than 389 the remaining two layers (the scales are different in Fig. 14), and the large semi-circular 390 feature is less noticeable in the deepest layer. 391

392

393 Conclusion

The new linear inversion technique presented here has been tested on synthetic and field data. When compared with the original model, or with the complete 3D MoM inversion

technique, it provides reliable results for the shape of the sought features, as well as the 396 397 magnitude of the contrasts. It is shown to be highly efficient for the correction of anomalous deformations, caused by the instrument's geometry, of a feature's geometrical outlines. By 398 using the instrument's dipole impulse response in the analysis, this technique takes the 399 influence of the real instrumental geometry into account, including that of the coil 400 orientations. Its results are thus significantly different to those obtained with 1D point-to-401 point inversions, in terms of susceptibility variations as a function of depth, making it possible 402 to improve the identification of the vertical boundaries of a given feature. 403

It should be underlined, however, that this technique is limited by the number of different available instrument geometries: in practice the magnetic susceptibility contrasts of only a rather small number of layers at a limited number of depths can be inversed. It is very valuable to have even this limited information on depth and susceptibility and where necessary the prospector has the possibility to increase the number of instruments geometries by considering measurements acquired at several altitudes with the same device.

Compared to 3D complete MoM inversion, the rapidity of this technique not only leads to a significant gain in time, but also provides the interpreter with the ability to test several stabilization process options, such as the choice of the number of layers or layer thicknesses. This also makes it possible to assess the probable vertical extent of the different features, through the use of a vertically translated thin layer.

415

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495 Appendix I Characteristics of the devices used for field studies

496

497 SH3: this apparatus is a laboratory prototype designed in 1977 (Parchas and Tabbagh 1978). 498 It has a PARA coil orientation (the two coils have parallel axes aligned at 35° from the 499 vertical, such that their direct coupling is null in free space), a 1.5 m coil separation, a coil 500 center height of d=0.2 m, and is operated at 8.04 kHz.

501

502 **CMD**: this apparatus is a multi-receiver EMI (Gf Instruments, Ltd, Brno) comprising one 503 transmitter coil and three receiver coils, located at distances of 0.32, 0.71 and 1.18 m from the 504 transmitter. All the coils are coplanar, allowing the instrument to be used in either HCP or 505 VCP configurations. The instrument's operating frequency is 30 kHz, and it can be used in a 506 continuous recording mode by a mobile operator in the field, with an above-ground clearance 507 of d=0.12 m.

508

DualEM 421S: this apparatus is a multi-receiver EMI (DualEM Ltd, Milton) operated at 509 9 kHz. It associates one horizontal transmitter loop with three pairs of receivers. In each pair, 510 the first receiver is horizontal, allowing HCP measurements to be made. By rotating the entire 511 apparatus, VCP configuration measurements can also be made. The second receiver of each 512 pair is oriented in a radial direction from the transmitter, allowing PERP configuration 513 measurements to be used. The receivers of the first pair are located at respectively 1m and 514 1.1m from the transmitter, those of the second pair at 2m and 2.1 m, and those of the third 515 pair at 4m and 4.1m. However, in the archaeological surveys presented here, data from the 516 third pair were not considered. Data from the VCP 1m, VCP 2m, HCP 1m, HCP 2m, PERP 517 1.1m and PERP 2.1m are used in the present study. 518

520 Figure captions

521 Figure 1: Flowchart demonstrating the full process with both a 1D non-linear inversion and a

522 3D linear inversion over the variations.

523 Figure 2: Description of the different bodies used to generate synthetic data

524 Figure 3: Apparent magnetic susceptibility maps calculated using the method of moments and

525 the characteristics of the seven devices under consideration.

526 Figure 4: Results of the 1D inversion when three layers are considered: the first is centered at

527 $z_1=0.3$ m and has a thickness $e_1=0.2$ m, the second is centered at $z_2=0.5$ m and has a thickness

528 $e_2=0.2$ m, and the third is centered at $z_3=0.8$ m and has a thickness $e_3=0.4$ m.

529 Figure 5: Results of the 3D linear inversion when three layers are considered (using the same

geometries as in Fig. 3), and the norm of the κ vector is minimized using $\lambda = trace/2$

531 Figure 6: Balloy neolithic enclosure: (a) SH3 apparent magnetic susceptibility, the relatively

high level is explained by the high susceptibility of the upper layer of soil (approx. 100×10^{-5}

533 SI), and the inverted magnetic susceptibility of a layer situated between the depths of 0.25 m

and 0.65 m, derived from the 1D inversion (b) and from the 3D linear inversion (c). The

rectangles indicate the contour of the targeted area used for 3D non-linear inversion.

536 Figure 7: Perdika2 (Central Thessaly, Greece) magnetic map: pseudo-gradient of the vertical

537 component of the Earth's magnetic field. The area surveyed using the CMD is colored orange.

Figure 8: Perdika2 site, apparent magnetic susceptibility maps measured using the CMDinstrument.

Figure 9: Perdika2 site, (a) inverted magnetic susceptibility of the 0.2 - 0.7 m and 0.7 - 1.2 m layers using the 1D inversion, (b) inverted magnetic susceptibility of the 0.2 - 0.7 m and 0.7 - 1.2 m 1.2 m layers using the 3D linear inversion.

- Figure 10: Medamud site (Egypt), three apparent magnetic susceptibility maps measured
 using the CMD instrument over the 44m x 60 m survey area.
- Figure 11: Medamud site, (a) inverted magnetic susceptibility of the 0.05 0.35 m and 0.35 0.35 m
- 546 0.65 m layers using the 1D inversion, (b) inverted magnetic susceptibility of the 0.05 0.35 m
- and 0.35 0.65 m layers using the 3D linear inversion. The white rectangles indicate the
- 548 contour of the targeted area used for 3D non-linear inversion.
- Figure 12: Thérouanne (Pas-de-Calais, France) site, four apparent magnetic susceptibilitymaps.
- 551 Figure 13: Thérouanne site, inverted magnetic susceptibility of the 0.25 0.75 m, 0.75 –
- 552 1.25 m, and 1.25 2.25 m layers using the 1D inversion.
- 553 Figure 14: Thérouanne site, inverted magnetic susceptibility of the 0.25 0.75 m, 0.75 0.75 m,
- 1.25 m, and 1.25 2.25 m layers using the 3D linear inversion.
- 555

557 **Table captions**

Table 1: Inverted susceptibility contrast (in 10^{-5} SI) as a function of the slab's depth of the slab, z, and the separation between transmitting and receiving coils, *L* (the original value being 200 10^{-5} SI), (a) VCP configuration, (b) PERP configuration (the symbol X means that the shape of the slab is not correctly restored and unidentifiable), (c) HCP configuration and (d) PARA configuration

563

Table 2: Inverted susceptibility contrast when a $2m \ge 2m \ge 0.6$ m body, of $200 \ 10^{-5}$ Si susceptibility contrast is divided into 5 thin layers of 0.12m thickness, determined using respectively five, six and seven different instrumental configurations (constraint II is used in the inversion).

Table 3: Characteristics of seven instrumental configurations used to interpret inversionprocesses with synthetic data.

	L=0.5 m	L=0.7 m	L=1 m	L=1.5 m	L=2 m
z=0.3 m	195	187	153	169	153
z=0.5 m	227	224	209	226	200
z=0.7 m	245	235	221	236	234
z=1 m	242	241	239	241	229
z=1.5 m	250	226	219	249	205

571 Table 1(a)

572

	L=0.5 m	L=0.7 m	L=1 m	L=1.5 m	L=2 m
z=0.3 m	206	258	183	Х	Х
z=0.5 m	235	244	217	259	219
z=0.7 m	242	240	233	253	228
z=1 m	252	245	252	248I	230
z=1.5 m	Х	Х	Х	249	193

573 Table 1(b)

574

	L=0.5 m	L=0.7 m	L=1 m	L=1.5 m	L=2 m
z=0.3 m	296	120	240	225	X
z=0.5 m	271	221	215	233	302
z=0.7 m	266	304	257	224	284
<i>z=1 m</i>	271	282	263	292	276
z=1.5 m	277	279	249	280	248

575 Table 1(c)

	L=0.5 m	L=0.7 m	L=1 m	L=1.5 m	L=2 m
z=0.3 m	217	205	185	222	224
z=0.5 m	318	247	249	255	241
z=0.7 m	289	280	258	272	276
z=1 m	280	287	260	283	275
z=1.5 m	273	277	179	311	284

577 Table 1(d)

578

579

Different instrument configurations used	Inverted susceptibility contrast (x 10 ⁻⁵ SI) for
	5 layers
5 configurations : PERP 1 m, PERP 1.5 m,	Layer 1 (centered et 0.26m) 219.5
VCP 0.7 m, VCP 1 m and PARA 1.5 m	Layer 2 (centered at 0.38 m) 219.8
	Layer 3 (centered at 0.50 m) 220.2
	Layer 4 (centered at 0.62 m) 220.4
	Layer 5 (centered at 0.74 m) 220.5
6 configurations : PERP 0.7 m, PERP 1 m,	Layer 1 217.6
PERP 1.5 m,	Layer 2 218.0
VCP 0.7 m, VCP 1 m	Layer 3 218.3
and PARA 1.5 m	Layer 4 218.5
	Layer 5 218.6
7 configurations : PERP 0.7 m, PERP 1 m,	Layer 1 219.1
PERP 1.5 m,	Layer 2 219.5
VCP 0.7 m, VCP 1 m, VCP 1.5 m	Layer 3 219.8
and PARA 1.5 m	Layer 4 220.4
	Layer 5 220.5

580 Table 2

Apparatus	Geometrical	Inter-coil	Frequency	Height of the
	configuration	separation (m)	(kHz)	coils (m)
SH3	PARA	1.5		
PRP6	PERP	0.6		
PRP10	PERP	1.0		
PRP15	PERP	1.5	8.0	0.2
VCP6	VCP	0.6		
VCP10	VCP	1.0	1	
VCP15	VCP	1.5	1	

584 Table 3



587 Fig. 1



-5

-0

-5

-5

-0

-5

-5

-0

--5

10 m

10 m

Fig. 3 594



-5

-0

-5



600 Fig. 5



Balloy neolithic enclosure









606 Fig. 7









621 Fig. 11a











