



# Past and new technological developments at LOV for core and new BGC applications

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## Acknowledgements

Technological developments are always a team work !

LOV : Antoine Poteau, Christophe Penkerc'h, A. Pierret,
V. Taillandier, N. Alem, F. D'Ortenzio, H. Claustre

Strong and good collaboration with Ifremer and NKE





## **Presentation Outline**

Provor CTS4 : A float developed for the BGC core Argo mission

Provor CTS5 : A float developed for R&D and demanding application

- R&D facilities at LOV
- Past developments
- On going developments

Conclusion and perspectives.

### **Development of the CTS4 profiler** Collaboration LOV - IFREMER - NKE



Nice results:

- More than 200 floats
- First float "Full BGC" deployed
- Highly flexible BGC Argo float





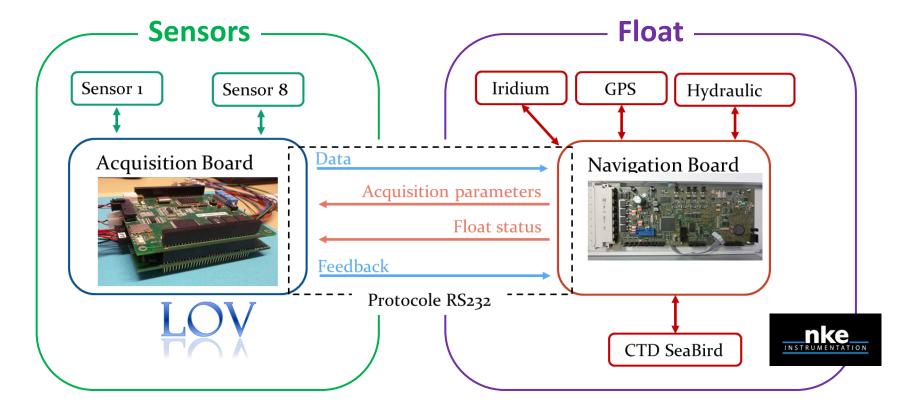
### **But not easy to explore new applications**





## **Development of the CTS5 profiler**

How to integrate safely, at LOV, new applications ?
→ dual board strategy. The CTS5 support a protocol to communicate with a user electronic board.



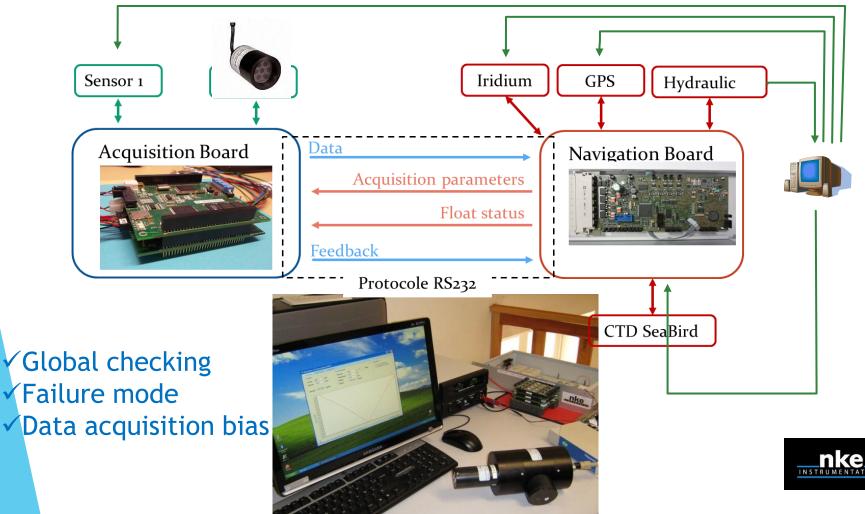
**Modifiable at LOV = Flexibility** 

**Stable = Security** 

Collaboration LOV - NKE

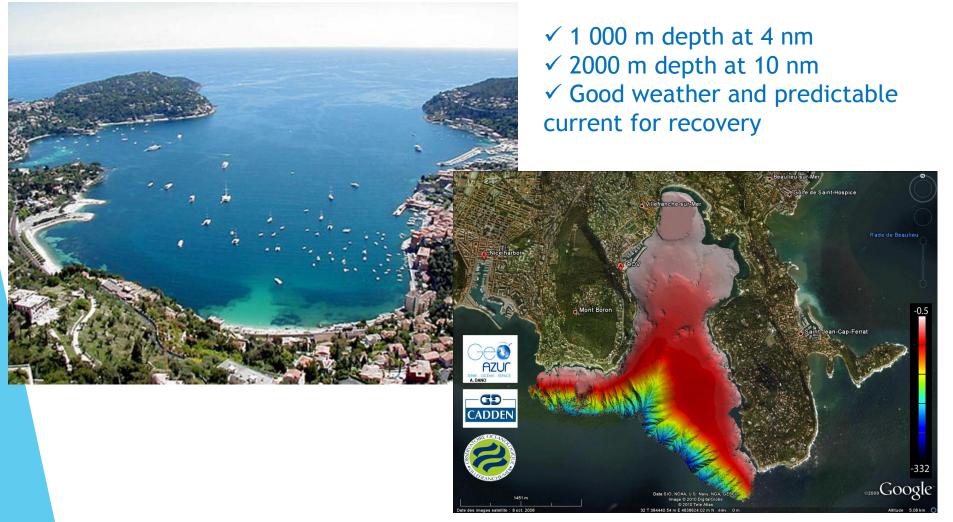
## **Development of the CTS5 profiler**

#### How to test our development? 1- Hardware Bench Simulator



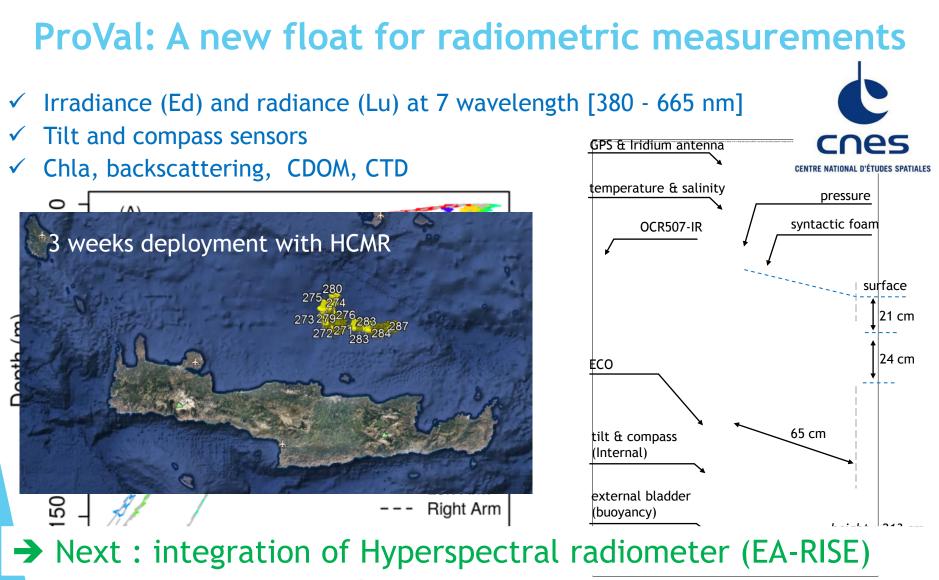
## **Development of the CTS5 profiler**

How to test our development ? 2- In-situ testing at LOV



## CTS5 profiler Past and on-going developments

- 1. ProVal float
- 2. Proice float
- 3. UVP6 sensor
- 4. Passive acoustic



Irradiance (µW.cm<sup>-2</sup>.nm<sup>-1</sup>)

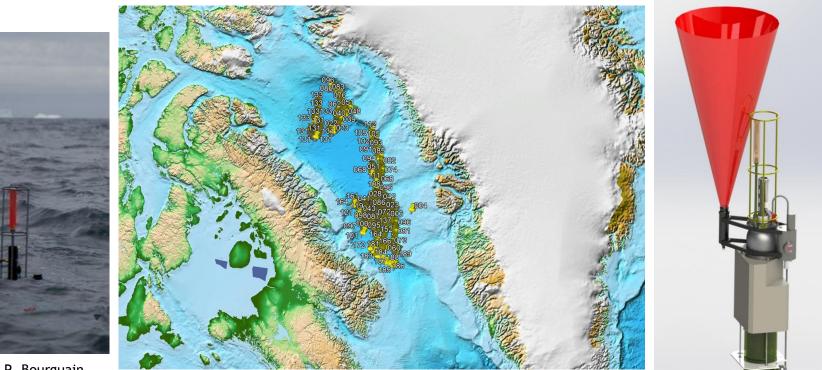
Already 3 floats and more than 600 profiles. *Frontiers in mar. Sc.* https://www.frontiersin.org/articles/10.3389/fmars.2018.00437/full



Joint work with C. Marec, J. Lagunas, E. Rehm and M. Babin from Takuvik

#### ✓ Ice avoidance : ISA adapted to Baffin Bay, Altimeter and date criteria programmed on the LOV acquisition board

✓ Change of configuration under-ice (date criteria)



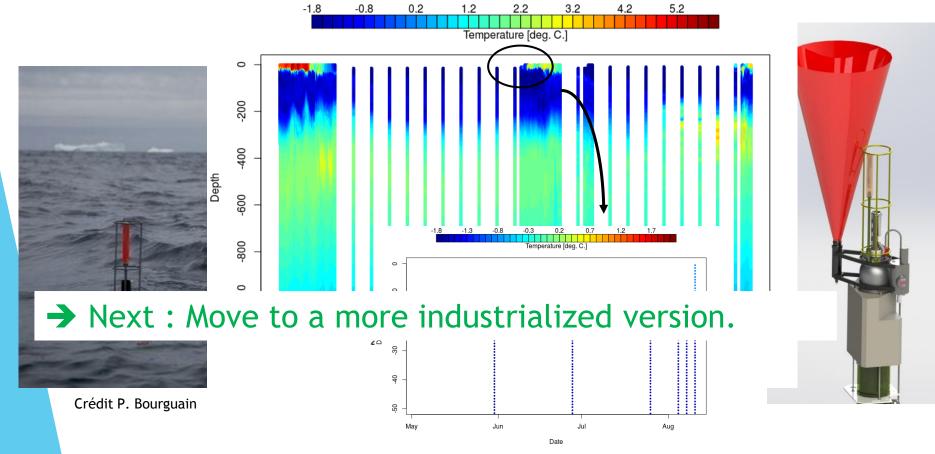
Crédit P. Bourguain

# Proice: A BGC float for arctic condition TAKUVIK

Joint work with C. Marec, J. Lagunas, E. Rehm and M. Babin from Takuvik

#### ✓ Ice avoidance : ISA adapted to Baffin Bay, Altimeter and date criteria programmed on the LOV acquisition board

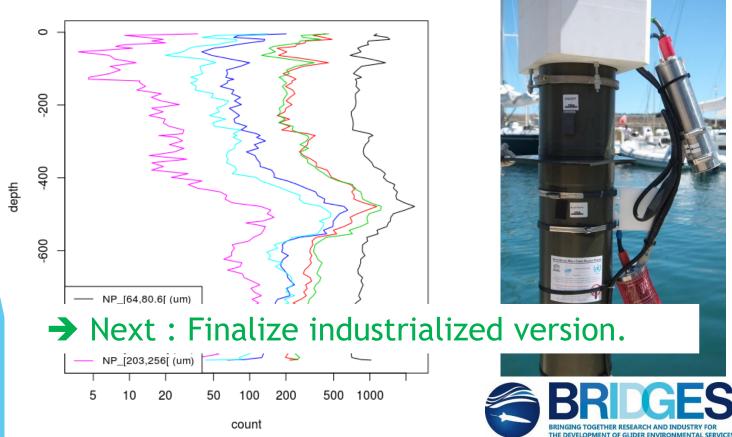
Change of configuration under-ice (script based - date criteria)



## **UVP6-LP : Miniaturized Under Vision Profiler**

Low power, image based, particle size counter (18 size class, 64 to 4100  $\mu$ m) Sensor developed at LOV M. Picheral *et al*.

Octopus NPart\_Class1-6



**Projet GOPPI** 



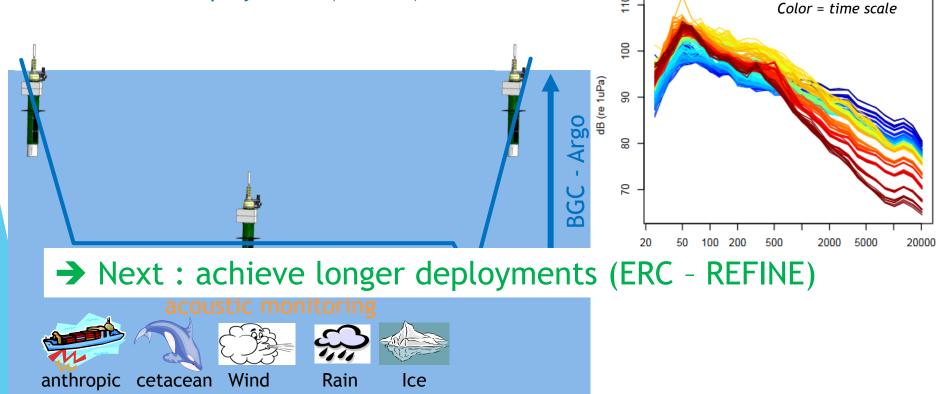
## **Passive Acoustic Monitoring**



Joint work with J. Bonnel (Whoi) and D. Cazau (ENSTA)

→ Estimate wind speed and rainfall from parking depth

- Passive acoustic recorder (RTSys) and transmission of 30 FFT bands (1/3 octave) per acquisition
- ✓ Several short deployments (1 week)



## **Overview and future developments.**

Conclusion on the acquisition board managed by LOV

- Created a lot of opportunities for testing new applications
- > But difficulties when you want to industrialize these applications

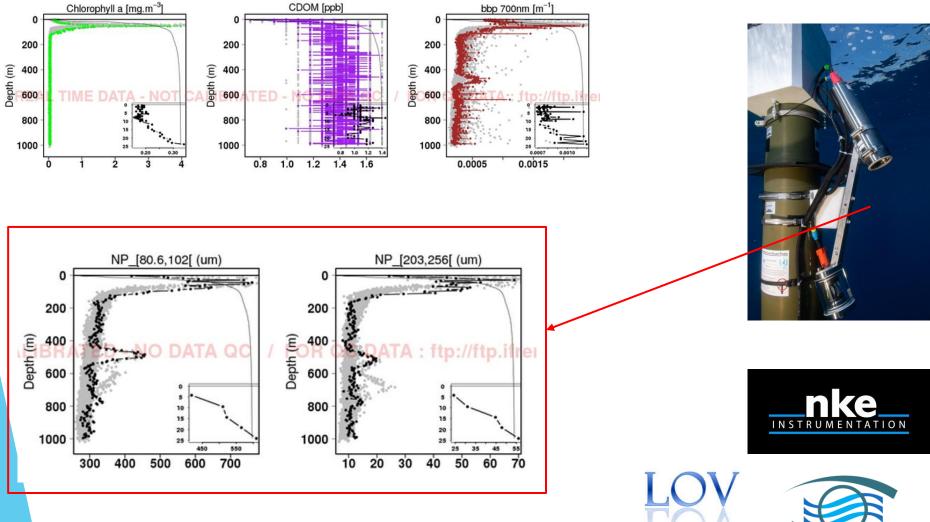
## ➔ New Development with NKE : CTS5 - USEA

- Increased capabilities for BGC-Core Argo
  - $\checkmark$  Mission and sampling flexibilities
  - ✓ Increased Rudics speed
  - ✓ GUI configuration tools
- Room for new applications developed by LOV but with easier industrialization
  - ✓ New sensor
  - ✓ Advanced On-Board Processing





### **CTS5 - USEA : First Results** Integration of the UVP6 sensor as commercial product



Thanks to C. Schmechtig, JP Rannou and T. Carval for data handling



## **Perspectives**

- A lot of new applications are waiting to be implemented on floats
- Very significant progress is being made to reduce sensor power consumption (ex. UVP → 20 times less in 10 years) opening new applications for Argo floats
- The bottleneck for the next decade is the telemetry !

