



Past and new technological developments at LOV for core and new BGC applications

E. Leymarie, A. Poteau, C. Penkerc'h, N. Alem, A. Pierret, V. Taillandier, F. D'Ortenzio, H. Claustre *Laboratoire d'Océanographie de Villefranche*



Acknowledgements

Technological developments are always a team work !

LOV : Antoine Poteau, Christophe Penkerc'h, A. Pierret,
V. Taillandier, N. Alem, F. D'Ortenzio, H. Claustre

Strong and good collaboration with Ifremer and NKE





Presentation Outline

Provor CTS4 : A float developed for the BGC core Argo mission

Provor CTS5 : A float developed for R&D and demanding application

- R&D facilities at LOV
- Past developments
- On going developments

Conclusion and perspectives.

Development of the CTS4 profiler Collaboration LOV - IFREMER - NKE



Nice results:

- More than 200 floats
- First float "Full BGC" deployed
- Highly flexible BGC Argo float





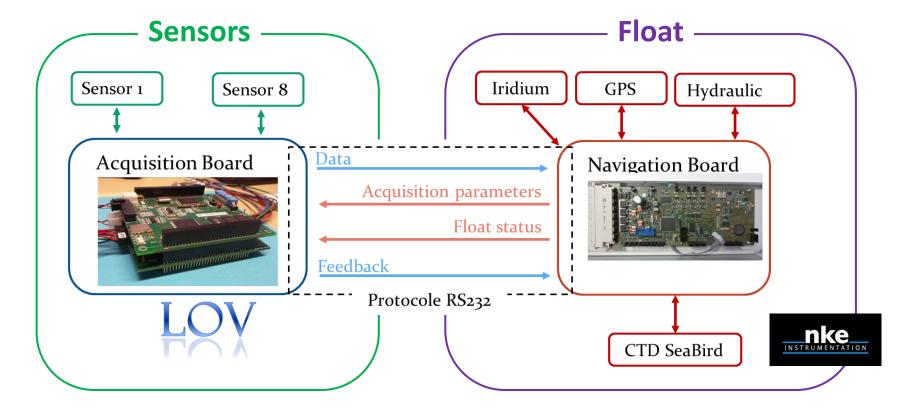
But not easy to explore new applications





Development of the CTS5 profiler

How to integrate safely, at LOV, new applications ?
→ dual board strategy. The CTS5 support a protocol to communicate with a user electronic board.



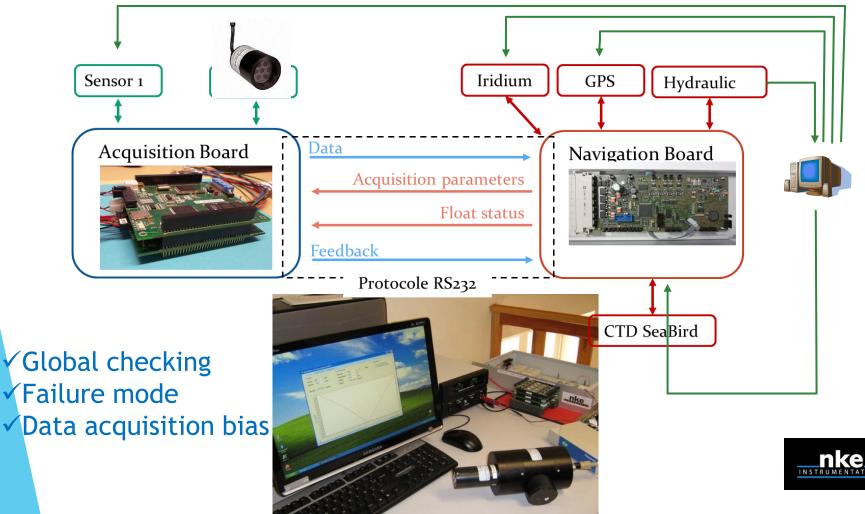
Modifiable at LOV = Flexibility

Stable = Security

Collaboration LOV - NKE

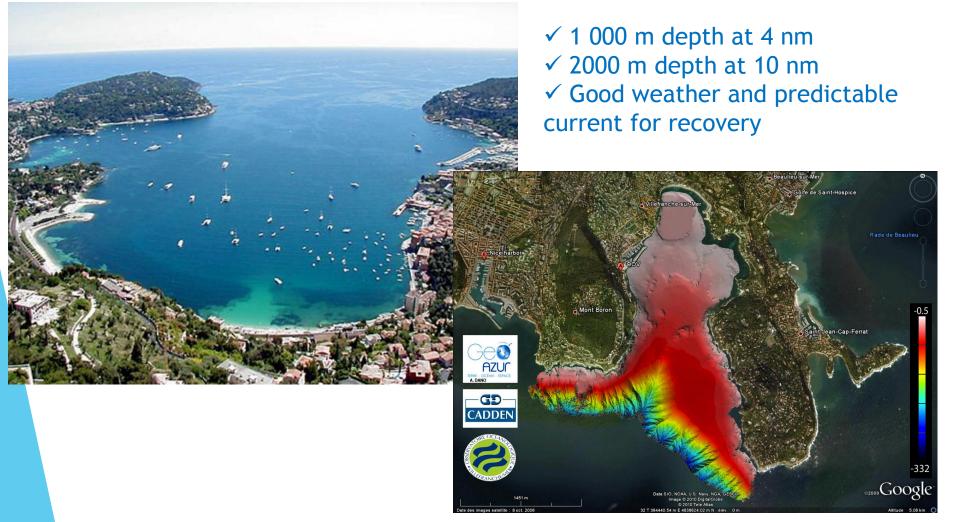
Development of the CTS5 profiler

How to test our development? 1- Hardware Bench Simulator



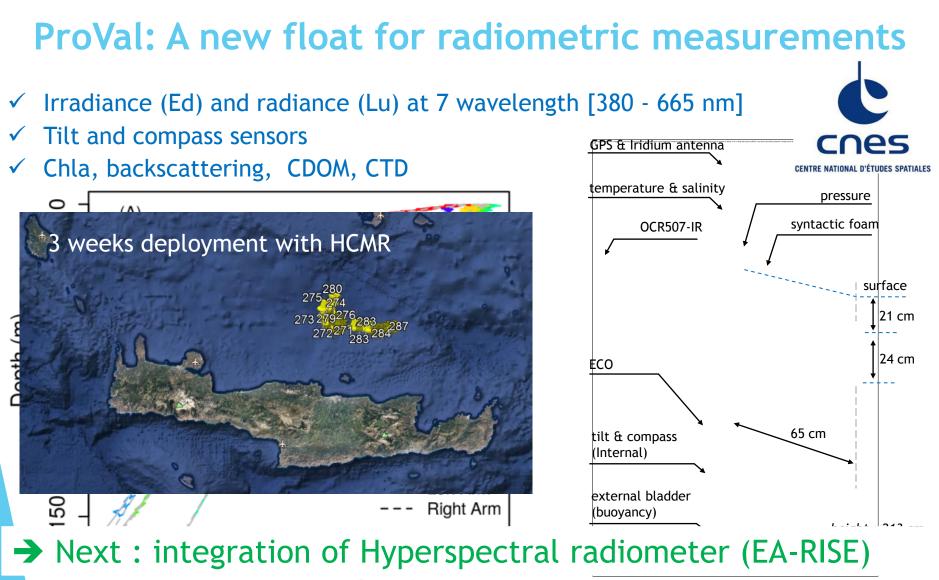
Development of the CTS5 profiler

How to test our development ? 2- In-situ testing at LOV



CTS5 profiler Past and on-going developments

- 1. ProVal float
- 2. Proice float
- 3. UVP6 sensor
- 4. Passive acoustic



Irradiance (µW.cm⁻².nm⁻¹)

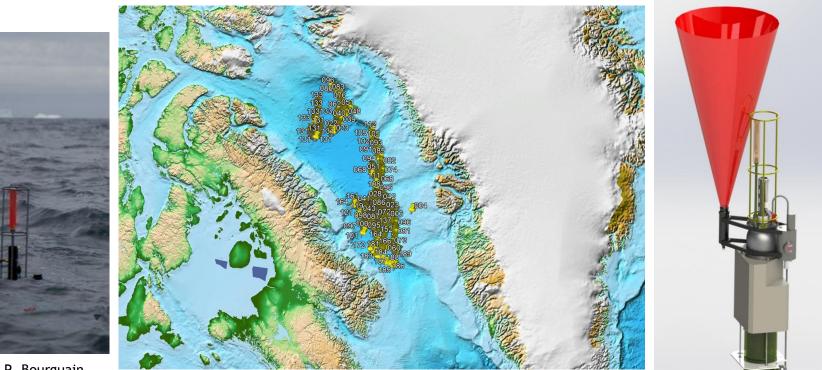
Already 3 floats and more than 600 profiles. *Frontiers in mar. Sc.* https://www.frontiersin.org/articles/10.3389/fmars.2018.00437/full



Joint work with C. Marec, J. Lagunas, E. Rehm and M. Babin from Takuvik

✓ Ice avoidance : ISA adapted to Baffin Bay, Altimeter and date criteria programmed on the LOV acquisition board

✓ Change of configuration under-ice (date criteria)



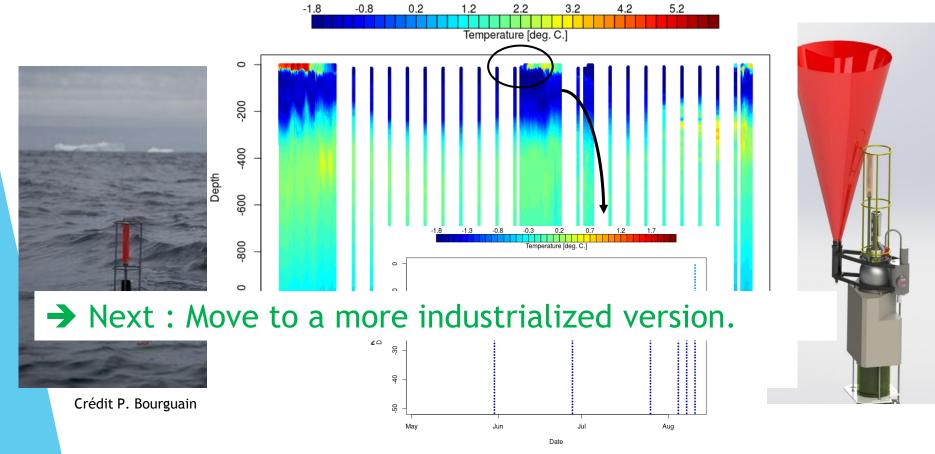
Crédit P. Bourguain

Proice: A BGC float for arctic condition TAKUVIK

Joint work with C. Marec, J. Lagunas, E. Rehm and M. Babin from Takuvik

✓ Ice avoidance : ISA adapted to Baffin Bay, Altimeter and date criteria programmed on the LOV acquisition board

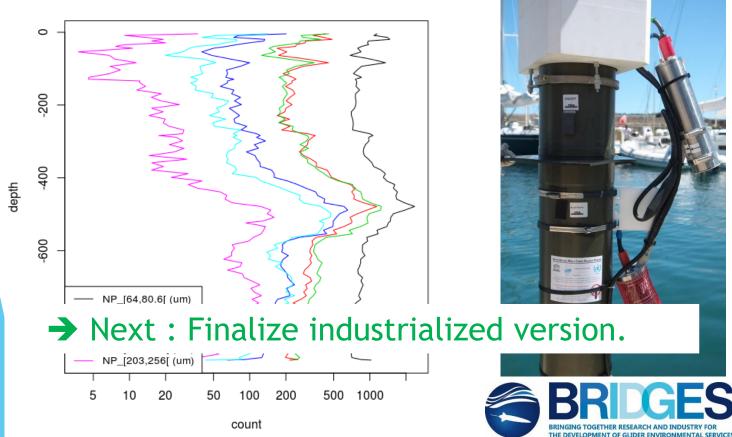
Change of configuration under-ice (script based - date criteria)



UVP6-LP : Miniaturized Under Vision Profiler

Low power, image based, particle size counter (18 size class, 64 to 4100 μ m) Sensor developed at LOV M. Picheral *et al*.

Octopus NPart_Class1-6



Projet GOPPI



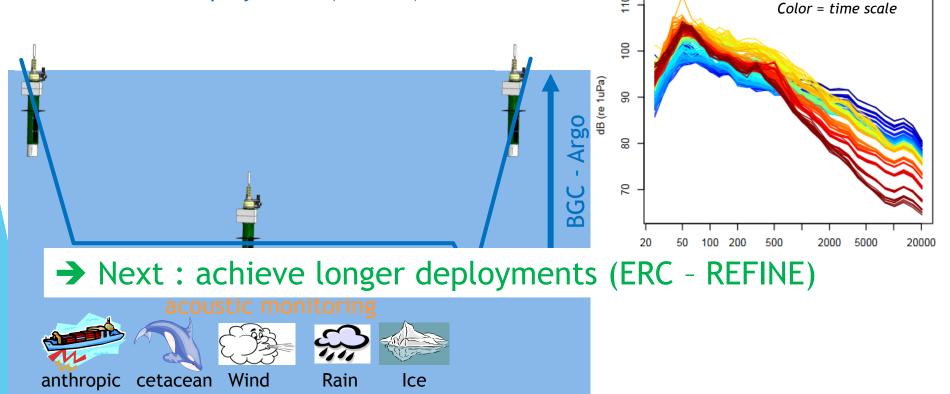
Passive Acoustic Monitoring



Joint work with J. Bonnel (Whoi) and D. Cazau (ENSTA)

→ Estimate wind speed and rainfall from parking depth

- Passive acoustic recorder (RTSys) and transmission of 30 FFT bands (1/3 octave) per acquisition
- ✓ Several short deployments (1 week)



Overview and future developments.

Conclusion on the acquisition board managed by LOV

- Created a lot of opportunities for testing new applications
- > But difficulties when you want to industrialize these applications

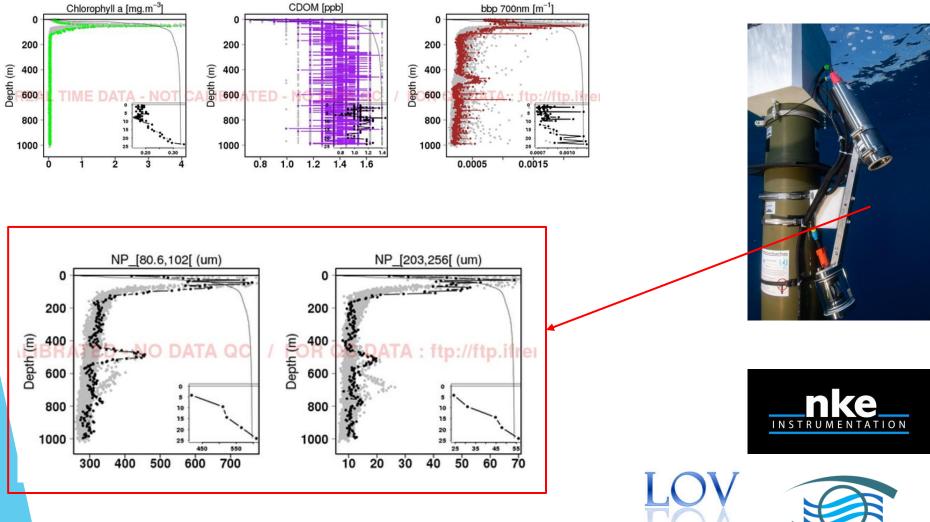
➔ New Development with NKE : CTS5 - USEA

- Increased capabilities for BGC-Core Argo
 - \checkmark Mission and sampling flexibilities
 - ✓ Increased Rudics speed
 - ✓ GUI configuration tools
- Room for new applications developed by LOV but with easier industrialization
 - ✓ New sensor
 - ✓ Advanced On-Board Processing





CTS5 - USEA : First Results Integration of the UVP6 sensor as commercial product



Thanks to C. Schmechtig, JP Rannou and T. Carval for data handling



Perspectives

- A lot of new applications are waiting to be implemented on floats
- Very significant progress is being made to reduce sensor power consumption (ex. UVP → 20 times less in 10 years) opening new applications for Argo floats
- The bottleneck for the next decade is the telemetry !

