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RESEARCH LETTER

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Key Points:

- To clarify the debate on the Recharge Oscillator index, we develop an objective approach optimizing equation fit to observations
- The recharge index must be based on the slow component of sea level/thermocline depth, taken independently from the fast zonal tilt mode: this reconciles usual metrics
- The optimal index is this independent component averaged in the equatorial and southwestern Pacific. It is better suited for operational diagnostics

Supporting Information:

Supporting Information may be found in the online version of this article.

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Improving and Harmonizing El Niño Recharge Indices

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Abstract El Niño Southern Oscillation (ENSO) is the leading mode of interannual climate variability, with large socioeconomical and environmental impacts. The main conceptual model for ENSO, the Recharge Oscillator (RO), considers two independent modes: the fast zonal tilt mode in phase with central-eastern Pacific Temperature (T_e), and the slow recharge mode in phase quadrature. However, usual indices (western or equatorial sea level/thermocline depth h) do not orthogonally isolate the slow recharge mode, leaving it correlated with T_e . Furthermore the optimal index is currently debated. Here, we develop an improved recharge index by objectively optimizing the RO equations fit to observations. (a) T_e -variability is regressed out, to build h_{ind} statistically-independent from T_e . Capturing the pure recharge, h_{ind} reconciles usual indices. (b) The optimum is equatorial plus southwestern Pacific $h_{\text{ind_eq+sw}}$ (because of ENSO Ekman pumping meridional asymmetry). Using $h_{\text{ind_eq+sw}}$, the RO becomes more consistent with observations. $h_{\text{ind_eq+sw}}$ is more relevant for ENSO operational diagnostics.

Plain Language Summary El Niño and La Niña events have important impacts globally. A key element for long-lead forecasts is the recharge state of the tropical Pacific Ocean, as captured in the Recharge Oscillator (RO) conceptual model. The RO considers two independent modes of oceanic variability, a fast adjustment process and a slow recharge/discharge process. However, usual recharge indices mix these two modes of variability, and can thus lead to ambiguous operational diagnostics of the actual oceanic recharge state. Here we develop a better recharge index, independent of the fast mode, which reconciles typical indices and allows us to go beyond the current geographical debate on the optimal metrics. We use an objective approach optimizing the RO resemblance to observations to find the optimal index: the independent sea level (or equivalently thermocline depth) averaged over the equatorial and southwestern tropical Pacific. We recommend this simple and unambiguous index for El Niño operational forecasts diagnostics.

1. Introduction

The El Niño Southern Oscillation (ENSO) is the leading mode of climate interannual variability, with large socioeconomic and environmental impacts (e.g., Clarke, 2008; Jin et al., 2020; Neelin et al., 1998; Timmermann et al., 2018; Wang and Picaut, 2004 reviews). While ENSO predictability skill is now rather good at short leads, it has to be improved at longer leads (e.g., Barnston et al., 2012, 2019). One key element for long-lead seasonal forecasts is the recharge state of the tropical Pacific (be it in terms of Oceanic Heat Content (OHC), thermocline depth h or sea level anomaly (SLA)), as it brings long oceanic memory across ENSO phases. Its role is formalized in the Recharge Oscillator (RO) conceptual model of ENSO (e.g., Clarke, 2010; Clarke et al., 2007; Jin, 1997a, 1997b; Wyrтки, 1985). For example, during a La Niña, easterlies favor a slow accumulation of OHC in the western and equatorial Pacific. This recharge will progressively favor positive Sea Surface Temperature (SST) anomalies in the central-eastern equatorial Pacific (T_e) and thus El Niño onset through the Bjerkness positive feedback. The El Niño event will in turn lead to a discharge favoring a reversal to La Niña conditions. The RO can thus well explain ENSO cyclic nature (cf. Section 3 for RO equations).

Yet there is a debate on the best recharge metric, for example, western or equatorial Pacific, sea level or thermocline depth. In the RO, the equatorial Pacific basin adjustment is separated into two independent modes: (a) the fast adjustment mode associated to a zonal tilt of the thermocline, in phase with zonal equatorial wind stress τ_x and T_e (Figure 1a); (b) the slow adjustment recharge mode in phase quadrature with the fast mode (and thus with τ_x and T_e ; Figure 1b). Several indices have been developed for this slow recharge mode that all bring predictability

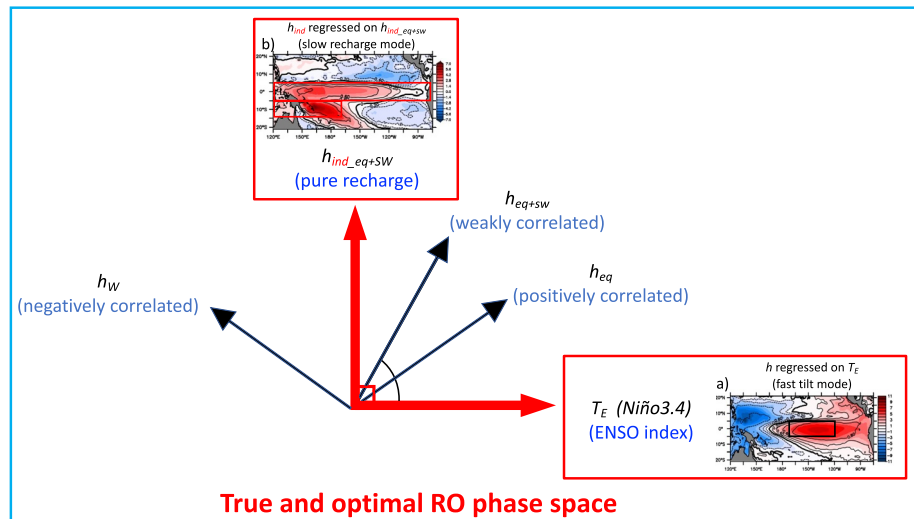


Figure 1. Schematics of the optimal orthonormal phase space for the Recharge Oscillator (RO). Panels a and b show respectively the fast adjustment zonal tilt mode dependent of T_E (h regressed onto T_E , i.e., K) and the pure recharge mode (h_{ind} regressed onto our default best recharge index h_{ind_eq+sw}), independent of (uncorrelated to) T_E (h unit: satellite SLA in cm; c.f. Sections 1 and 3 for details). Black arrows illustrate other used indices based on usual h . They are hence partly correlated to T_E .

skill. Wyrтки (1985) and Jin (1997a, 1997b) originally focused on the western equatorial Pacific h_w , using equivalently SLA, OHC or the actual thermocline depth for h . Jin's sketch, Meinen and McPhaden (2000), and Burgers et al. (2005) focused on the mean equatorial band: h_{eq} (e.g., Warm Water Volume (WWV) based on the 20°C isotherm depth Z20, or SLA, as usual thermocline depth proxies). h_{eq} has become a widely-used ENSO recharge index. Theoretically, in the RO model, h_{eq} is independent (i.e., uncorrelated at lag 0) from the fast tilt mode (and thus from T_E) within Jin (1997a, 1997b) approximations.

This independence/orthogonality property is essential, so that the recharge metric captures solely the *pure* recharge mode and does not mix it with the fast adjustment mode. But in observations, h_{eq} (and its proxies) is not independent (Figure 1; upper-right panel of Figure S2 in Supporting Information S1). It is physically ambiguous, mixing the fast adjustment with the slow recharge mode, and thus potentially misleading: h_{eq} is dominated by a short-term Ekman convergence leading to a temporary *fast* “increase” with *El Niño westerlies* (thus not a true long-term recharge in the RO sense), about two times larger (for SLA-based h_{eq}) than the long-term *slow discharge* expected from the RO theory. h_{eq} is hence first an index of the fast equatorial Kelvin wave rather than of the RO long-term recharge/discharge process (Izumo, Lengaigne, et al., 2018; see also Neske and McGregor, 2018). Thus h_{eq} is strongly positively correlated to the fast mode (and thus to τ_x and T_E). Hence, Izumo, Lengaigne, et al. (2018) recommended the use of a western Pacific index, h_w (in agreement with Ballester, Petrova, et al., 2016; Boschat et al., 2013; Graham et al., 2015; Jin et al., 2020; Lai et al., 2015; Ramesh and Murtugudde, 2013; Petrova et al., 2017). Yet, such western Pacific OHC index is also not independent of T_E . It is partly negatively correlated to the fast zonal tilt mode (Figure 1a). h_w could thus also lead to ambiguous diagnostics of the actual oceanic state.

Therefore the fast adjustment mode needs to be removed in order to obtain an operationally-useful indicator of the fully-isolated recharge process. Here we will hence develop an improved recharge index h_{ind} independent of the fast mode. We will show that previously-defined indices converge when using h_{ind} . We will develop an objective approach optimizing the skill of the RO differential equations fit to observations for the (T_E, h_{ind}) pair to find the optimal averaging region for h_{ind} : h_{ind_eq+sw} .

2. Data and Methods

Here we use classical observations and reanalyzes datasets, indices and statistical methods, detailed in Text S1 in Supporting Information S1 (statistics robust thanks to a sufficiently-large number of effective degrees of freedom, ~ 85 to ~ 140). The ENSO index T_E is Niño3.4 relative Sea Surface Temperature (RSST, i.e.,

SST minus its 20°N–20°S tropical mean), as recommended by Izumo et al. (2020) and Van Oldenborgh et al. (2021) because atmospheric tropical deep convection interannual anomalies are rather related to RSST than to SST. Theoretically, SST is the variable directly involved for the term $F_1 * h$ in the dT_E/dt equation (cf. Section 3). Yet, the recharge process is driven by windstress, itself directly driven by atmospheric deep convection and thus by RSST. Therefore, Niño3.4 RSST is better for the term $F_2 * T_E$ in the dh/dt equation (Text S3 in Supporting Information S1). Using SST instead of RSST, or Niño3 instead of Niño3.4, makes T_E slightly less correlated to equatorial Pacific τ_x (i.e., ocean-atmosphere coupling), but leads to very similar results (Table S2 in Supporting Information S1).

3. Improving the Recharge Oscillator Recharge Index

3.1. Traditional RO Framework Revisited

To derive RO dT_E/dt tendency equation (see Jin et al., 2020 review for derivation), some physically-reasonable assumptions are used. (a) τ_x is proportional to T_E , that is, tropical deep convection and related τ_x respond quickly to T_E . (b) The fast oceanic response (i.e., quasi-instantaneous, timescales faster than ~2–3 months) to τ_x leads to a positive Bjerkness feedback term in the dT_E/dt equation (through both the zonal advective and thermocline feedbacks) that is proportional to τ_x and thus to T_E : $R_{BJ,o} T_E$. (c) Atmospheric fluxes are approximated as a weak Newtonian damping proportional to T_E : $-r_{damp,o} T_E$. (d) A deepening of the thermocline depth h related to a recharge favors positive T_E on time scales longer than 2–3 months: $F_1 h$ (see Text S2 in Supporting Information S1 on mechanisms). Therefore:

$$\frac{dT_E}{dt} = R_o T_E + F_1 h \quad (1)$$

the first term on the right hand side representing the net effect of Bjerkness positive feedback and Newtonian damping ($R_o = R_{BJ,o} - r_{damp,o}$) and the second one, F_1 , the recharge/discharge influence on T_E (following Jin et al., 2020 notations).

Concerning dh/dt equation, in the RO, the slow recharge mode response is the temporal integral of τ_x (e.g., Izumo et al., 2014). Negative T_E associated with easterly anomalies will progressively recharge the equatorial Pacific (see Section 3.3 and Text S2 in Supporting Information S1). This is formalized as a term $-F_2 T_E$ in the dh/dt equation:

$$\frac{dh}{dt} = -F_2 T_E - \epsilon_o h \quad (2)$$

the second term $-\epsilon_o h$ being formally a Newtonian damping, expected to be weak.

That is, the tendency equation for the vector $\begin{pmatrix} T_E \\ h \end{pmatrix}$ in matrix form is:

$$\frac{d}{dt} \begin{pmatrix} T_E \\ h \end{pmatrix} = \begin{pmatrix} R_o & F_1 \\ -F_2 & -\epsilon_o \end{pmatrix} \begin{pmatrix} T_E \\ h \end{pmatrix} \quad (3)$$

This RO linear equation is simple, but it remains unclear which geographical box to use for h . Furthermore, a standard multivariate linear regression fit minimizing rms error (second method in Burgers et al., 2005) gives significantly different coefficients for the classical normalized metrics h_w and h_{eq} : $R_o = \epsilon_o = +0.06 \pm 0.04$ and -0.18 ± 0.05 months⁻¹ for h_w and h_{eq} respectively, $F_1 = F_2 = 0.15 \pm 0.04$ and 0.25 ± 0.05 months⁻¹ respectively. The fact that R_o and ϵ_o can change sign so easily for different classical recharge metrics makes it hard to interpret them physically. It evidences some physical inconsistency (Figure 1).

To resolve these geographical debate and physical issues objectively, an empirical way to find the best h is to have no a priori on the best region and index. Thus, one may intuitively think of searching for the $h(x, y, t)$ region that statistically optimizes the skill of Equation 3. We will actually show later that we need two steps to construct

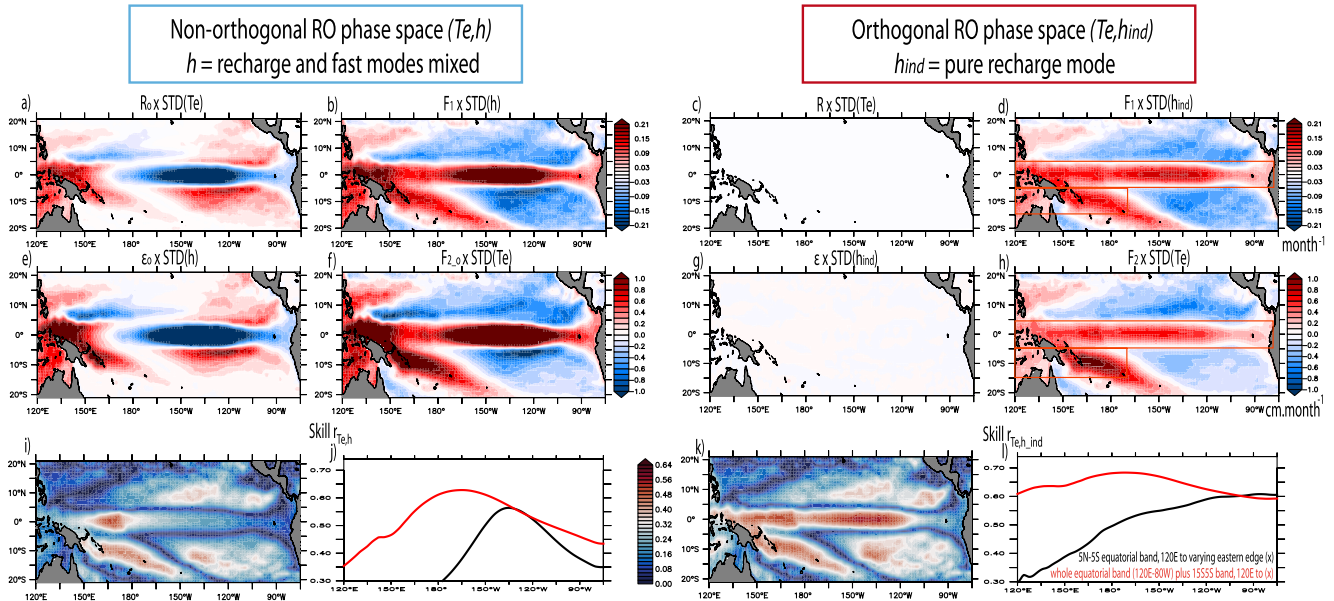


Figure 2. Searching for the optimal recharge index h , representing the actual slow recharge mode independent of the fast mode in RO equations. Usual non-orthogonal basis (T_E, h) in the left set of panels, and orthogonal basis (T_E, h_{ind}) in the right one. Panels a and b show respectively the coefficients $R_0(x, y)$ and $F_1(x, y)$ for the multivariate regression of $dT_E/dt(t)$ onto $T_E(t)$ and $h(x, y, t)$ (Equation 4), multiplied by the STDs of $T_E (=1)$ and of $h(x, y, t)$ respectively, to measure their respective contributions to $dT_E/dt(t)$. Panels e and f are as a and c, but for coefficients for $dh(x, y, t)/dt$ regression. Panel i shows $r_{Te,h}$ skill using $h(x, y, t)$. Black line in panel j shows this skill for h averaged over: the equatorial band (5°N – 5°S) with its western edge fixed to 120°E and its eastern edge varying, given by the x-axis. Red line is for a two-rectangle region, the classical equatorial box (5°N – 5°S , 120°E – 80°W) plus a southern 5°S – 15°S box with the same 120°E fixed western edge and its eastern edge varying. The right set of panels is the same for the here-developed orthogonal basis (T_E, h_{ind}) . The boxes overlaid represents the two-rectangle equatorial + SouthWest ($eq + sw$) optimal region finally chosen to average h_{ind} . This defines the suggested improved index: h_{ind_eq+sw} . See text for details.

a better index: (a) independence to T_E , (b) geographical optimization of the averaging region. Let us first try the geographical optimization alone:

$$\frac{d}{dt} \begin{pmatrix} T_E(t) \\ h(x, y, t) \end{pmatrix} = \begin{pmatrix} R_0(x, y) & F_1(x, y) \\ -F_{2_0}(x, y) & -\epsilon_0(x, y) \end{pmatrix} \begin{pmatrix} T_E(t) \\ h(x, y, t) \end{pmatrix} + \begin{pmatrix} \text{residual}_T(x, y, t) \\ \text{residual}_h(x, y, t) \end{pmatrix} \quad (4)$$

In practice we do at each spatial point (x, y) a fit with two multivariate linear regressions, one for Equation 1 and one for Equation 2, with Pearson correlation skill r_{Te} and r_h respectively. The squareroot of the RV-coefficient (Rho-Vectoriel; Escoufier & Robert, 1976), “ $r_{Te,h}$,” is the equivalent of the Pearson correlation for matrix form, that is, a measure of the skill for the 2D Equation 4. Where the skill is the highest (residuals variance minimized) should inform us of the best h region to capture the RO processes. The highest skill is in the equatorial and south-western tropical Pacific (Figure 2i), suggesting that the best region for averaging $h(x, y, t)$ could combine these two regions. However, the regression coefficients contributions have a puzzling spatial distribution (Figures 2a, 2b, 2e, and 2f). They are highly spatially-correlated with large opposing signs. In the central Equatorial Pacific, T_E and h influences on dT_E/dt would be very large, but negative for R_0 and positive for F_1 respectively, which is unphysical. This is actually a statistical artifact because $T_E(t)$ and $h(x, y, t)$ are not statistically independent (i.e., not orthogonal), which makes it difficult to interpret physically the regression coefficients. It therefore suggests that the (T_E, h) basis is not ideal.

3.2. Toward New RO Tendency Equations for T_E and Independent h_{ind}

A large component of h responds rapidly to τ_x and T_E . This fast response component of h is correlated to (i.e., linearly dependent of) T_E at timescales longer than ~ 2 – 3 months in the equatorial Pacific: Figure 1a shows the downwelling pattern along the central to eastern equatorial Pacific and the zonal seesaw pattern in the western Pacific, that is, the fast adjustment mode. We suggest to regress out from $h(x, y, t)$ this rapidly-responding component correlated to $T_E(t)$, so as to only focus on the slowly-responding independent component of h , hereafter h_{ind}

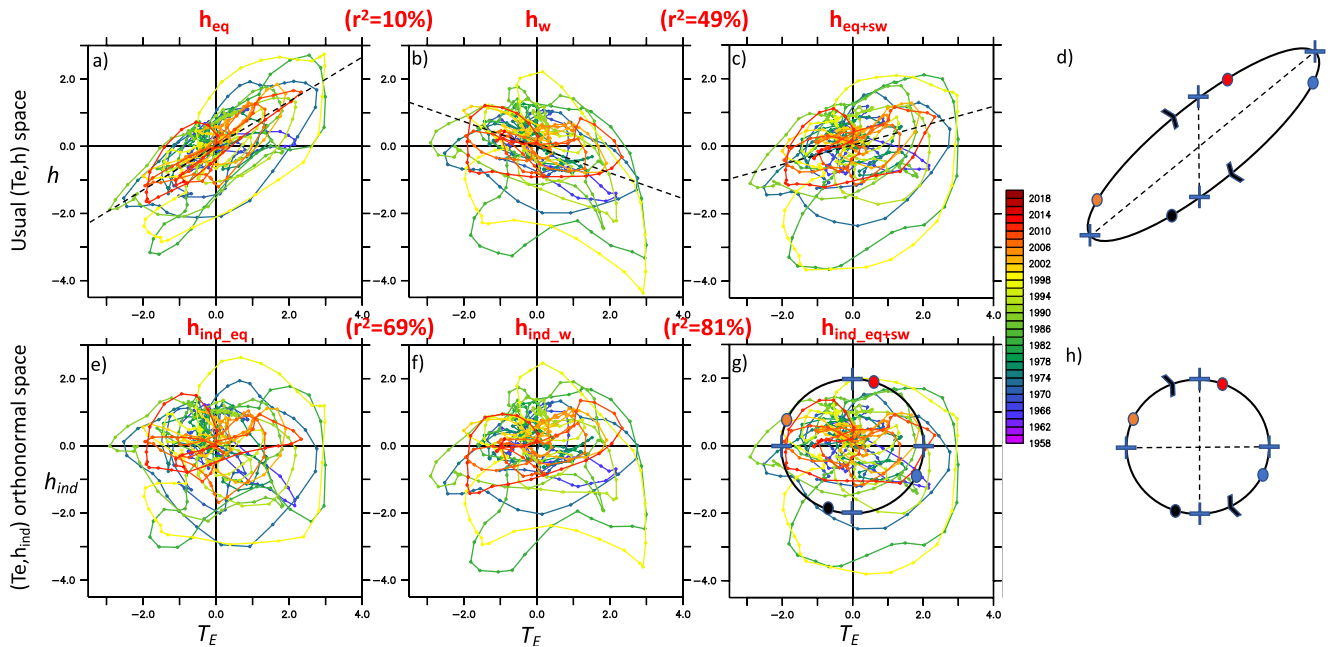


Figure 3. Observed trajectories of the RO in the usual (T_E, h) space (upper panels) and new orthonormal (T_E, h_{ind}) space (lower panels), for classical h_{eq} and h_w indices (1st and 2nd columns), and optimal h_{eq+sw} index (3rd column). (a) Trajectory of the system for the pair of coordinates (T_E, h_{eq}) , T_E in horizontal axis, h in vertical axis, each month being a point, with year indicated in color, for ORASS SLA. Other panels are similar, but for other recharge indices. Indices are all normalised. The shared variance (square of correlation) between recharge indices is shown in parenthesis. (d) schematized elliptical trajectory if the recharge index is positively correlated to T_E , such as h_{eq} . Such index is ambiguous. For example, a positive anomaly does not necessarily correspond to an actual recharge state (blue dot). (h) circular trajectory for the recharge index independent component, consistent with ideal RO trajectory, and unambiguous. Color dots indicate different positions in the cycle.

(Figure 3b of Izumo, Lengaigne, et al., 2018). h_{ind} corresponds to the slow recharge mode related to the slower basin adjustment in disequilibrium with wind stress (e.g., Alory & Delcroix, 2002; Clarke, 2010; Fedorov, 2010; Jin, 1997a, 1997b; Masuda et al., 2009; Thual et al., 2013; Zhu et al., 2017; Izumo, Lengaigne, et al., 2018). Thus, we can formally decompose h :

$$h(x, y, t) = h_{fast_mode(dependent, corr. to T_E)} + h_{slow_recharge_mode(independent, uncorr. to T_E)}$$

$$h(x, y, t) = K(x, y) T_E(t) + h_{ind}(x, y, t) \quad (5)$$

$K(x, y)$ being the regression coefficient of h onto T_E (Figure 1a).

h_{ind} is the pure recharge component, that allows us to describe the system with an orthonormal basis: (T_E, h_{ind}) (Figure 1). An orthonormal basis is more acceptable physically and mathematically.

With this linear transform, Equation 4 can then be rewritten as:

$$\frac{d}{dt} \begin{pmatrix} T_E(t) \\ h_{ind}(x, y, t) \end{pmatrix} = \begin{pmatrix} R(x, y) & F_1(x, y) \\ -F_2(x, y) & -\varepsilon(x, y) \end{pmatrix} \begin{pmatrix} T_E(t) \\ h_{ind}(x, y, t) \end{pmatrix} + \begin{pmatrix} residual_T(x, y, t) \\ residual_{h_{ind}}(x, y, t) \end{pmatrix} \quad (6)$$

with $R = R_o + K F_1$, $F_2 = F_{2,o} + \varepsilon_o K + K R_o + K^2 F_1$, $\varepsilon = \varepsilon_o + K F_1$ and $residual_{h_{ind}} = residual_h - K residual_T$.

So the F_1 term representing the recharge influence on T_E remains the same for h_{ind} , and the physics behind is also the same. F_2 represents the influence of easterly anomalies related to T_E on the h_{ind} recharge. It differs from $F_{2,o}$.

Figures 2c, 2d, 2g, and 2h show the coefficients obtained from the multivariate regression onto (T_E, h_{ind}) . R and ε are uniformly negligible ($\sim 0.00 \pm 0.03$ months⁻¹). F_1 and F_2 vary spatially similarly, with highest values in the equatorial and southwest Pacific corresponding to the highest skill (Figure 2k and Figure S1 in Supporting Information S1). Hence the best h_{ind} region should combine these two regions. The picture is also clearer and more consistent with RO theory: ε is negligible, consistent with a weak damping (due mainly to oceanic mixing,

e.g., Fedorov, 2010). $r_{Te,h_{ind}}$ is larger than $r_{Te,h}$ (Figure 2i), further confirming that (T_E, h_{ind}) is a better basis of RO phase space.

Here we explain the spatial patterns of Figure 2's various panels (full explanation in Text S2 in Supporting Information S1), robust among datasets and periods (cf. Figure S2 in Supporting Information S1), and why there are similarities among some of them. F_2 map shows us how $h_{ind}(x, y, t)$ would look like if ENSO windstress anomalies would blow for a long time, for example, because of long-lasting La Niña conditions. The slow recharge is as expected in the western and central equatorial Pacific, through: (a) downwelling equatorial Rossby waves to the west (Jin, 1997a, 1997b; Wyrтки, 1985), and off-equatorial ones in the southwest; (b) upwelling equatorial Kelvin waves to the east forcing coastal Kelvin waves propagating poleward along the eastern boundary and thus leading to a leakage of negative OHC anomalies toward the poles along the eastern boundary (Izumo, Lengaigne, et al., 2018; Wyrтки, 1985).

Interestingly the recharge is also in the southwest, because of asymmetric Ekman pumping (poleward shift of the South Pacific Convergence Zone; SPCZ) forcing locally downwelling (in the La Niña case) and thus slow off-equatorial downwelling Rossby waves progressively recharging the southwestern Pacific. Note that the western boundary coastline meridional asymmetry would conversely favor a larger northwest recharge, as shown by sensitivity experiments with the LCS model (Linear Continuously Stratified model; McCreary, 1980; configuration of Izumo, Lengaigne, et al., 2018; Figure S3 in Supporting Information S1). F_1 physically represents the slow recharge mode influence on T_E through several mechanisms (Text S2 in Supporting Information S1).

R_o , ϵ_o and $F_{2,o}$ spatial patterns can be explained as follow: $R_o \approx \epsilon_o \approx -KF_1$ and $F_{2,o} \approx F_2 + K^2F_1$ (as $\epsilon \approx 0$ and $R \approx 0$). These relationships explain the paradox (pointed out in Section 3.1) with large positive and negative R_o and ϵ_o values found for classical h_w and h_{eq} respectively: $R_o \approx \epsilon_o > 0$ (because $K < 0$ in the west) for h_w and $R_o \approx \epsilon_o < 0$ (because $K > 0$) for h_{eq} , even if the actual damping ϵ and net feedback R are weak. So the “damping” term (ϵ_o) and the “positive feedback” (R_o) would be artificially large. This further confirms that we should use h_{ind} rather than the full h polluted by the fast mode that biases the RO model.

Such transforms from observable variables to new variables that are more relevant physically are often done in physics and geosciences, for example, to create potential temperature, relative SST, rotating PCs (Takahashi et al., 2011), decomposition into baroclinic modes, spherical harmonics... We just want to clearly isolate the independent influence of the slow recharge mode from the fast tilt mode, and to optimize the RO understanding and metrics (we are not trying to add new physical processes).

Considering h_{ind} instead of h allows us to go beyond the RO metrics debate, by reconciling indices: they become much closer when considering their independent component. For example, h_{ind_w} and $h_{ind_{eq}}$ are much better correlated (r^2 increases from 10% to 69%) with now similar coefficients (Figures S4, S5 and Table S2 in Supporting Information S1). And Z20 and SLA-based indices become even closer (Figure S6 in Supporting Information S1). Trajectories in the (T_E, h_{ind}) phase diagram (Dommenget & Al-Ansari, 2022; Kessler, 2002) also become closer (Figure 3; shown here for longer ORAS5 SLA data set to have a larger density; see Figures S7 and S8 in Supporting Information S1 for satellite SLA and ORAS5 Z20). The transform is geometrically simply a linear transform of coordinates from the (T_E, h) to the (T_E, h_{ind}) orthogonal coordinate space. Trajectories in the latter space are more circular, closer to idealized RO model circular trajectory.

To conclude, h_{ind} reconciles various recharge metrics such as h_{ind_w} and $h_{ind_{eq}}$. Here below we would like to further improve them by objectively finding h_{ind} optimal averaging region.

3.3. Objectively Finding the Optimal Region: Equatorial + South-West ($h_{ind_{eq+sw}}$)

The optimal region for $h_{ind}(x, y, t)$ will be the one optimizing the skill $r_{Te,h_{ind}}$ of the RO tendency Equation 6

for $\begin{pmatrix} T_E \\ h_{ind} \end{pmatrix}$:

$$\frac{d}{dt} \begin{pmatrix} T_E \\ h_{ind} \end{pmatrix} = \begin{pmatrix} R & F_1 \\ -F_2 & -\epsilon \end{pmatrix} \begin{pmatrix} T_E \\ h_{ind} \end{pmatrix} \quad (7)$$

$r_{Te,h_{ind}}$ (Figure 2k) is the largest in the equatorial ($\sim 5^{\circ}\text{N}$ – 5°S) and southwest ($\sim 5^{\circ}\text{S}$ – 15°S) Pacific. The combination of these two boxes should be our optimal region, and $r_{Te,h_{ind}}$ should be even better thanks to the spatial averaging (reducing noise). To choose objectively the optimal averaging region, we have tested several options. We have first tested rectangular boxes, for example, by averaging $h_{ind}(x, y, t)$ from the usual fixed 120°E western end to a varying eastern edge, for various latitudinal bands. For the classical 5°N – 5°S band, the best skill ($r_{Te,h_{ind}} = 0.61$) is found for an eastern edge around ~ 90 – 80°W (Figure 2l, black line), consistent with classical h_{eq} (5°N – 5°S , 120°E – 80°W). Another relevant band is the 5°N – 15°S , 120°E to $\sim 150^{\circ}\text{W}$, leading to a similarly high skill (not shown). A “hybrid” choice with two rectangles is even better. Adding to the optimal classical equatorial band (5°N – 5°S , 120°E – 80°W) a second box in the southwest, along the 5°S – 15°S band, from the same 120°E western edge to a varying eastern edge, further improves the skill to $r_{Te,h_{ind}} = 0.69$ for an optimal eastern edge around $\sim 170^{\circ}\text{W}$ (Figure 2l, red line). We have similarly tested all the other edges of this two-rectangle region, also testing ORAS5 SLA and Z20 (Figures S9a, S9b, and S10 in Supporting Information S1). This is our best allround and sufficiently-simple index, hereafter $h_{ind_{eq+sw}}$ (note that $h_{ind_{eq+sw}} = h_{eq+sw_{ind}}$, the regression being linear). Interestingly, this choice also conveniently minimizes the correlation between h_{eq+sw} and T_E (Figures S9c and S9d in Supporting Information S1), making h_{eq+sw} closer to $h_{ind_{eq+sw}}$. The skill increase from $h_{ind_{eq}}$ to $h_{ind_{eq+sw}}$ is statistically significant, more thanks to $r_{h_{ind}}$ ($p = 0.0110.00110.001$) than to r_{Te} ($p = 0.0910.0110.23$) for satSLA|ORAS5_SLA|ORAS5_Z20 respectively). And trajectories are even smoother (Figure 3g). Including the southwest agrees with Izumo et al. (2018a; see also Santoso et al., 2017; Ramesh and Murtugudde, 2013). $h_{ind_{eq+sw}}$ is now our default best recharge index.

Using normalized $h_{ind_{eq+sw}}$, we obtain: $F_1 \approx F_2 \approx 0.17 \pm 0.03$, $R \approx \varepsilon \approx 0.00 \pm 0.03 \text{ months}^{-1}$. These coefficients are robust among datasets and periods (Table S1 in Supporting Information S1). R and ε are negligible. This reduces the parameter space. And the RO equations system has the form of a harmonic oscillator excited by noise (Burgers et al., 2005), with $d^2X(t)/dt^2 \approx -F_1F_2X(t)$, $X(t)$ being T_E or h_{ind} , and angular frequency being the Wyrтки index $W = (F_1F_2)^{1/2} \approx F_1 \approx F_2$ (i.e., reasonable eigenperiod of ~ 3.1 year). Even if theoretically undamped, the oscillator is actually still damped because $residual_T$ is not a pure red noise but includes non-linear terms neglected in our first order linear approximation (Table S2 in Supporting Information S1).

4. Conclusion

4.1. Summary

Here we have defined a simple Pacific recharge index h_{ind} independent of the fast mode, by regressing out T_E -related variability. It unambiguously represents the slow recharge mode, with more physically-consistent RO parameters, conversely to classical recharge indices. h_{ind} harmonizes recharge indices: by taking h_{ind} , averages over the usual western/equatorial Pacific regions based on Z20/OHC/SLA have much more similar time series, equation parameters and phase trajectories, so that all indices converge to a single one. We have also objectively searched for the optimal averaging region to have the most realistic RO tendency equations. The optimal index is $h_{ind_{eq+sw}}$ averaged over the classical equatorial band (5°N – 5°S , 120°E – 80°W), extended in the southwest until 15°S (5°S – 15°S , 120°E – 170°W).

In practice, obtaining $h_{ind_{eq+sw}}$ is straightforward: (a) average SLA over “eq + SW” box and then normalize, (b) remove its dependent part KT_E : $h_{ind_{eq+sw}} = h_{eq+sw} - K_{eq+sw}T_E$, with regression coefficient $K_{eq+sw} \approx 0.26$ (details in Text S1 in Supporting Information S1).

4.2. Discussion

For ENSO operational diagnostics, the $(T_E, h_{ind_{eq+sw}})$ basis is more relevant to describe the system trajectory than the usual (T_E, h_{eq}) and (T_E, h_w) pairs (Figure 3). If the latter are used, a situation with anomalous h is ambiguous. Independent $h_{ind_{eq+sw}}$ better represents actual precursory recharge anomalies. Only with h_{ind} sign (recharged/discharged state) can one get dT_E/dt sign directly (while h sign is not sufficient, as the fast tilt mode signal could blur a weaker long-term build-up; see yellow/blue dots in idealized schematics Figures 3d and 3h).

To compare $h_{ind_{eq}}$ and $h_{ind_{eq+sw}}$ forecasting skills, we have done a preliminary assessment by using the simple multivariate linear regression model combining the recharge index, Indian Ocean Dipole (IOD) index and T_E , all in September–November, to hindcast T_E peak in November–January 14 months later. Adding the Southwest

improves the skill for all datasets/periods, more clearly for SLA than for Z20 (Table S3 in Supporting Information S1; since we have statistically-significant contributions from $h_{\text{ind_eq+sw}}$ and IOD, but not from T_E itself, this new recharge index and updated datasets confirm earlier studies of Izumo et al., 2010, 2014, 2016; Dayan et al., 2014; Jourdain et al., 2016).

Results are robust among datasets. Only some subtle second order differences remain between SLA and Z20 (OHC being inbetween) for h_{ind} , likely related to different weighting of the first baroclinic modes (Figures S2, S6, S8, and S10 in Supporting Information S1). Note that we are not trying to address “how to best estimate the thermocline depth” (Vijayeta et al., 2020), but rather “how to best isolate the recharge mode.” SLA and Z20 each have their own advantages with presently-available datasets: Z20 seems better in a perfectly-observed and non-warming ocean (Tables S1 and S3 in Supporting Information S1), but SLA is observed globally by satellite in near real-time and is more available in climate models outputs (e.g., Coupled Model Intercomparison Project, CMIP).

Here we have neglected possible seasonal cycles of parameters and asymmetries/non-linearities for the sake of simplicity. Knowing ENSO seasonal phase-locking, taking into account such seasonal cycles could be one next step. We could include asymmetrical/non-linear terms (Table S2 in Supporting Information S1). To have a simple h_{ind} definition, we have also neglected a weak non-linearity in the fast response of h to T_E (Figure 3c; Figures S7c and S8c in Supporting Information S1) likely due to τ_x anomalies longitudinal position, further to the east during El Niño than during La Niña, favoring a larger discharge. This non-linearity would lead to a quadratic term in the dh_{ind}/dt equation.

Our method is based on a statistical optimisation of regression coefficients from observations to fit the RO model, by projecting on an orthogonal basis, which is conceptually satisfying, and practically necessary to determine eigenmodes. But correlations do not mean causality, and this study therefore does not aim to challenge RO physical validity. Although using the physical h variable is necessary to infer causality and derive RO equations, we still argue that having orthogonal coordinates thanks to h_{ind} allows for clearer recharge diagnostics, and a properly isolated recharge mode.

Some studies, using usual h indices, have put in question the RO and suggested that the delayed oscillator (DO, Suarez and Schopf, 1988; Battisti & Hirst, 1989) is more realistic (e.g., Graham et al., 2015; Linz et al., 2014). One reason for this “RO versus DO” debate could be the misleading character of usual h indices because of fast tilt mode (dependent) component, which tends to artificially reduce RO skill. It would be interesting to compare the RO to the other ENSO oscillators, using $h_{\text{ind_eq+sw}}$ instead, to clarify whether theories, climate models and observations would better agree.

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Data Availability Statement

All data used is open data: OISSTv2 (<https://psl.noaa.gov/data/gridded/data.noaa.oisst.v2.html>), CMAP1 (<https://psl.noaa.gov/data/gridded/data.cmap.html>), ERA5-ORAS5 (<https://www.ecmwf.int>), Copernicus SLA (<https://doi.org/10.48670/moi-00148>), and HadISST (<https://www.metoffice.gov.uk/hadobs/hadisst/>). We acknowledge use of NOAA pyferret open source software for analyses and figures.

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Supporting Information for

Improving and harmonizing El Niño recharge indices

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Contents of this file

Texts S1 to S3; Tables S1 to S3; Figures S1 to S10

Introduction

The supplementary information contains 3 supplementary texts, 3 tables and 10 figures:

- Supplementary Text S1. *Data and methods*
- Supplementary Text S2. *Discussion on the mechanisms behind T_E and h_{ind} tendency equations*
- Supplementary Text S3. *Discussion on the choice of relative SST*

- Suppl. Table S1. Comparison of the $r_{T_E, h_{ind}}$ skill (using optimal $h_{ind, eq+sw}$) between various data, periods, fields, filtering and ENSO indices.
- Suppl. Table S2. Robustness of the (T_E, h_{ind}) tendency equation coefficients.

- Suppl. Table S3. 14-month lead ENSO hindcasts based on various recharge indices and IOD.
- Suppl. Fig. S1. Respective contributions of the r_{T_E} and $r_{h_{ind}}$ skills to the $r_{T_E, h_{ind}}$ skill.
- Suppl. Fig. S2. Equivalent (partly) to Fig. 2 but for ORAS5 reanalysis (1959-2018), comparing SLA, OHC and Z20.
- Suppl. Fig. S3. ENSO asymmetrical Ekman pumping.
- Suppl. Fig. S4. Regression maps of $h(x,y,t)$ or $h_{ind}(x,y,t)$ onto $h(t)$ or $h_{ind}(t)$ indices.
- Suppl. Fig. S5. Harmonizing the various recharge indices by using h_{ind} index.
- Suppl. Fig. S6. Comparing ORAS5 SLA and satellite SLA, and comparing SLA, Z20 and OHC in ORAS5, for $h_{ind_{eq+sw}}$ index (shown from 1993).
- Suppl. Fig. S7: as Fig. 3, but for satellite SLA (1993-2021).
- Suppl. Fig. S8. As Fig. 3, but for ORAS5 Z20.
- Suppl. Fig. S9. Finding the best averaging box for h_{ind} to optimize both T_E and h_{ind} tendency equations of RO.
- Suppl. Fig. S10. Same as S9ab for ORAS5 SLA and Z20.

Supplementary Text S1. *Data and methods*

Here we use classical monthly datasets: Optimum Interpolation SST OISSTv2 based on *in situ* observations and satellite measurements for the recent period (November 1981-Mar2022; Reynolds et al. 2002), HadISSTv1.1 SST (1870-Mar2022; Rayner et al. 2003) when using longer SLA/Z20/OHC from ECMWF ORAS5 oceanic reanalysis extended version (1959-2018; Zuo et al. 2019; similar results with ORAS5 SST instead of HadISST; not shown), CMAP1 precipitation (from 1979; Xie and Arkin 1997), and windstress from the latest ECMWF ERA5 atmospheric reanalysis (from 1979 also; Hersbach et al. 2020; using former ERA-Interim reanalysis giving similar results; not shown).

We mostly use SLA as an accurate proxy of thermocline depth/OHC anomalies (e.g. Rebert et al. 1985; Gasparin and Roemmich 2017; Palanisamy et al. 2015), measured from satellites (1993-mid2021; Copernicus product), allowing a better and more homogeneous spatio-temporal sampling than the usual 20°C isotherm depth Z20. We also verified that the results are robust with sensitivity tests shown in Supplementary Tables S1, S2 and S3 and Supplementary Figures S2, S6, S7, S8 and S10. Results are similar at 1st order with SLA, OHC and Z20 in ORAS5. For SLA, we subtract the 60°S-60°N global average at each time step to remove sea level rise global trend due to global warming, and we also remove any additional regional trend through a linear regression (results are similar without this regional detrending).

For the ENSO index, T_E , we use the usual Niño3.4 region (170°W-120°W, 5°N-5°S), a reasonable compromise to capture central Pacific as well as eastern Pacific ENSO events (e.g. Takahashi et al. 2011, Capotondi et al. 2015; the present study focusses on typical ENSO events and neglect 2nd order spatial diversity). We define T_E as Niño3.4 relative SST (RSST, i.e. SST minus its 20°N-20°S tropical mean), as recommended by Izumo et al. (2020) and Van Oldenborgh et al. (2021) because atmospheric tropical deep convection interannual anomalies are rather related to RSST than to SST, notably in the

presence of external forcing (see also Johnson and Kosaka 2016; Khodri et al. 2017; Izumo, Khodri et al. 2018; Williams and Patricola 2018, and Okumura 2019). The deep convection threshold $SST > \sim 27-28^\circ\text{C}$ (e.g. Gadgil et al. 1984) translates into $RSST > \sim 1^\circ\text{C}$, a threshold that remains valid with global warming (e.g. Johnson and Xie 2010). See Supplementary Text S3 for an extensive discussion justifying the relevance of RSST for RO equations.

T_E is normalized (divided by its standard deviation; STD), so that a 1-value represents typical ENSO amplitude. h is normalized when a regional average is done (e.g. usual $5^\circ\text{N}-5^\circ\text{S}$, $120^\circ\text{E}-80^\circ\text{W}$ for h_{eq} and $5^\circ\text{N}-5^\circ\text{S}$, $120^\circ\text{E}-155^\circ\text{W}$ for h_w , and for $h_{ind_{eq+sw}}$), but not when taken at each (x,y) point, so that related regression maps represent typical anomalous amplitudes (cm for SLA, m for Z20). Using SST instead of RSST, or Niño3 instead of Niño3.4 region, makes T_E slightly less correlated to equatorial Pacific τ_x (i.e. ocean-atmosphere coupling), confirming that Niño3.4 RSST is a relevant choice. They anyway lead to very similar results (Suppl. Text S3), with slightly weaker skills when using Niño3 (Suppl. Table S1).

Here we use typical statistical methods. The monthly seasonal cycle (computed by averaging each month of the year over the whole period) is removed and intraseasonal variations are filtered out by a 4-month Hanning filter (3-point Hanning filter in pyferret software for monthly time series), so that periods lower than $\sim 2-3$ months are removed (considering a fast adjustment to be with timescales less than $\sim 2-3$ months). For ORAS5 analysis over its whole extended period 1959-2018, we use in addition to the intraseasonal low-pass filter a highpass Hanning filter (14-year window; i.e. 7 years cut on each side) to remove interdecadal variability with cutting frequency at periods of ~ 10 -year (results are robust without this highpass filter, with just some increased interdecadal noise). Coefficients obtained from multivariate linear regression fits are shown multiplied by the STD of their multiplying variable (h or h_{ind} , cf. section 3; $STD(T_E)$ is already 1), so as to represent typical amplitudes.

For statistical significance, we use Steigers Z-method for difference between two dependent correlations from a single sample (Hotelling William method giving similar results; using <https://www.quantitativeskills.com/sisa/statistics/correl.htm>) and typical two-tailed Student t-tests for 90% confidence intervals. Using formulae (30) of Bretherton et al. (1999), we have about one effective degree of freedom every 4 months, i.e. ~ 85 for 1993-mid2021 satellite SLA period (~ 140 for filtered ORAS5 data), a sufficiently large number leading usually to strong statistical significances of the results.

Here we explain how to obtain $h_{ind_{eq+sw}}$ in details (and give the K dependance to data chosen for h): 1) average over $eq+sw$ box (equatorial box $5^\circ\text{N}-5^\circ\text{S}$, $120^\circ\text{E}-80^\circ\text{W}$ + southwest box $5^\circ\text{S}-15^\circ\text{S}$, $120^\circ\text{E}-170^\circ\text{W}$) the SLA (using $h(x,y,t) \sim SLA(x,y,t)$, detrended, smoothed, with seasonal cycle removed; cf. start of this text S1) and then normalize, 2) remove its dependent part KT_E : $h_{ind_{eq+sw}} = h_{eq+sw} - K_{eq+sw} T_E$, T_E being Niño3.4 relative SST anomaly (smoothed and normalized) with regression coefficient $K_{eq+sw} \approx 0.26 [0.30/0.21]$ for satellite SLA[ORAS5_SLA/Z20] (K_{eq+sw} is conveniently already small thanks to sw addition to eq region, conversely to usual eq and w regions, for which $K_{eq} = +0.70 [+0.68/+0.38]$ and $K_w = -0.40 [-0.36/-0.51]$ respectively).

Supplementary Text S2. Discussion on the mechanisms behind T_E and h_{ind} tendency equations

Here we explain physically and mathematically the spatial patterns of Fig. 2's various panels, very robust among datasets and periods (cf. Suppl. Fig. S2). And why there are similarities among some of them. Along these explanations we discuss the mechanisms behind the various tendency equations terms (descriptions done here by convention in the recharge case related to previous La Niña conditions; *vice versa* in the discharge case related to previous El Niño conditions).

F_2 map (Fig. 2h; and its equivalents in Suppl. Fig. S2) shows us how $h_{ind}(x,y,t)$ would look like if ENSO windstress anomalies would blow for a long time, e.g. after long-lasting La Niña conditions. This physical meaning of F_2 is mathematically because the temporal integral of dh_{ind}/dt equation (6) corresponds to the regression of $h_{ind}(x,y,t)$ onto the temporal integral of T_E , as ε is negligible. The slow recharge in the western and central equatorial Pacific shown by F_2 map is consistent with former EOF analyses (e.g. Meinen and McPhaden 2000, Alory and Delcroix 2002, Clarke et al. 2007, Clarke 2010, Kumar and Hu 2014). As mentioned in the main manuscript, this western and equatorial recharge is through: 1) downwelling equatorial Rossby waves to the west (Wyrтки 1985, Jin 1997a, 1997b), and off-equatorial ones in the southwest; 2) upwelling equatorial Kelvin waves to the east forcing coastal Kelvin waves propagating poleward along the eastern boundary and thus a leakage of negative h anomalies towards the poles along the eastern boundary (Wyrтки 1985, Izumo, Lengaigne et al. 2018; *vice versa* for El Niño case). The recharge has also been suggested to be through Sverdrup transport towards the equator (Jin 1997a,b) but this is now debated (Clarke 2010; Zhu et al. 2018; Izumo, Lengaigne et al. 2018). Whatever the mechanisms, they are all formally well represented at 1st order by the term $-F_2T_E$.

Concerning the recharge meridional asymmetry with a larger recharge in the southwest shown by F_2 map, it is caused by Ekman pumping asymmetry, but not by the western boundary coastline meridional asymmetry, as mentioned in the main manuscript. This asymmetrical Ekman pumping is mainly due south of $\sim 7^\circ\text{S}$ to windstress curl related to a poleward shift of the SPCZ (Suppl. Fig. S3). It forces locally downwelling (in the La Niña case) and thus slow off-equatorial downwelling Rossby waves progressively recharging the southwestern Pacific (see also Alory and Delcroix 2002; Cibot et al. 2005).

F_1 physically represents the slow recharge mode influence on T_E . F_1 tends to have a similar pattern to F_2 , statistically because h_{ind} tends to co-vary in the west and southwest Pacific (as the spatial pattern of ENSO-related windstress remains at first order similar among ENSO events). Physically, the thermocline depth deepening related to a recharge (La Niña case) favors positive T_E through the thermocline feedback in the central Pacific (where coupling with convection is large; Clarke et al. 2007) and eastern Pacific (Wyrтки 1985, Jin 1997ab). Southwest and equatorial thermocline deepening can also increase T_E by increasing the transport-weighted temperatures T_{conv} and T_{EUC} of STCs (Shallow Subtropical/Tropical meridional overturning Cells) lower branches. These are the meridional pycnocline convergence T_{conv} (knowing that pycnocline convergence is larger in the southwest than in the northwest) and the equatorial undercurrent (EUC) T_{EUC} (e.g. Izumo 2005, Ballester et al. 2015, 2016ab). These influences could be formalized as two terms, $F_{conv}T_{conv}$ and $F_{EUC}T_{EUC}$, in the dT_E/dt equation (where F_{conv} and F_{EUC} are constant

at 1st order). As T_{conv} and T_{EUC} anomalies are at 1st order proportional to h (Izumo 2005; with proportionality coefficients C_{conv} and C_{EUC}), we would have these terms in the dT_E/dt equation:

$$F_{conv} T_{conv} = F_{conv} C_{conv} h_{eq+sw} = F_{I_{conv}} h_{eq+sw} = F_{I_{conv}} h_{ind_{eq+sw}} + K F_{I_{conv}} T_E$$

$$F_{EUC} T_{EUC} = F_{EUC} C_{EUC} h_{eq+sw} = F_{I_{EUC}} h_{eq+sw} = F_{I_{EUC}} h_{ind_{eq+sw}} + K F_{I_{EUC}} T_E$$

So their influences on T_E can also be formalized as a term linearly proportional to $h_{ind_{eq+sw}}$ plus one related to T_E . Thus they are implicitly included in the final term F_I .

Another mechanism that possibly also participate in the role of the southwest Pacific recharge is the following. The off-equatorial downwelling Rossby waves associated with the southwest Pacific recharge propagate to the western boundary coastal wave guide and then to the equatorial wave guide as Kelvin waves. They can also increase T_E through the thermocline feedback and STCs transport-weighted temperatures. Whatever the relative contributions of these mechanisms, their influences on T_E are implicitly included in F_I .

Supplementary Text S3. Discussion on the choice of relative SST

Here we discuss the insensitivity of the results to our choice of using relative SST rather than usual SST. First of all, we have verified that the results are almost similar whatever the choice of SST or relative SST, with similar skill $r_{Te,h_{ind}}$ (table S1): the skill differences are really weak, of ~ 0.01 , not statistically significant at a high level, and much weaker than the skill improvement from former usual indices h_{eq} and h_w to $h_{ind_{eq+sw}}$.

If we go into details, there are some subtle 2nd order differences in the maps (not shown). For Niño3.4 SST, we have slightly less weight on central-eastern equatorial Pacific for dependent component (as compared to Fig. 1e), *i.e. the fast mode is not removed as efficiently, being essentially forced by equatorial Pacific $\tau_{x,eq}$, which is more related to RSST through atmospheric deep convection*. Indeed, the correlation between T_E and $\tau_{x,eq}$ is 0.80 (*i.e.* explained variance of 64%) instead of 0.75 (57%) when using Niño3.4 RSST instead of Niño3.4 SST [and 0.75 (56%) instead of 0.71 (51%) for Niño3 region].

SST is theoretically the variable directly driven by the recharge process represented by the term $F_I * h$ in the dT_E/dt equation. Yet, the recharge process is driven by windstress, which is itself directly driven by atmospheric deep convection and thus by RSST. Therefore, Niño3.4 RSST is better than usual SST for the term $F_2 * T_E$ in the dh/dt equation. Hence, theoretically, both choices could be considered.

Yet, in practice, RSST is what matters for ENSO global impacts through teleconnections and better captures coupled ocean-atmosphere anomalies related to ENSO (Okumura 2019; Izumo et al. 2020; Van Oldenborgh et al. 2021), especially with external forcing such as global warming (e.g. Vecchi and Soden 2008; Johnson and Xie 2010) or volcanic forcing (Khodri et al. 2016; Izumo et al. 2018b). Thus RSST is the variable we want to diagnose and possibly forecast seasonally. This is why we have chosen RSST.

<i>r_{Te,h_ind}</i> skill <i>Comparing satellite/ORAS5</i>	Sat. SLA (1993-2021)	Sat. SLA (1993-2018)	ORAS5 SLA (1993-2018)	ORAS5 Z20 (1993-2018)	ORAS5 OHC (1993-2018)
from 1993	0.69	0.68	0.66	0.71	0.65
<i>Comparing SLA/Z20/OHC in ORAS5</i>	SLAfilt	Z20filt	SLA	Z20	OHC
from 1959	0.66	0.72	0.63	0.65	0.60
<i>Testing ENSO indices</i>	Sat. SLA (1993-2021)	ORAS5 SLA	ORAS5 Z20	ORAS5 SLAfilt	ORAS5 Z20filt
Niño3.4 RSST	0.69	0.64	0.67	0.66	0.72
Niño3.4 SST	0.70	0.65	0.66	0.68	0.72
Niño3 RSST	0.65	0.62	0.66	0.66	0.72
Niño3 SST	0.66	0.63	0.65	0.64	0.72

Suppl. Table S1. Comparison of the r_{Te,h_ind} skill (using optimal h_{ind_eq+sw}) between different data, periods, fields, filtering and ENSO indices. *Upper rows:* comparison between satellite and ORAS5 on the same period, from 1993 (also verifying the unsensitivity to the change of the final year from 2021 to 2018). *Central rows:* skill stable over the long period 1959-2018 using ORAS5, with interdecadal variations filtered out (*'filt'*) or not. *Bottom rows:* verifying equivalence between ENSO indices. We have also verified the non-sensitivity to SST datasets: e.g. ORAS5 SST leads to almost no change (here we use OISST for recent periods and HadiSST for long periods from 1959).

Comparison for satellite SLA (1993-2021)				
	R_o	F_1	F_2_o	ϵ_o
h_w	0.06±0.04	0.15±0.04	0.15±0.04	0.06±0.04
h_{eq}	-0.18±0.05	0.25±0.05	0.25±0.05	-0.18±0.05
h_{eq+sw}	-0.05±0.03	0.18±0.03	0.18±0.04	-0.05±0.04
	R	F_1	F_2	ϵ
$h_{ind w}$	0.00±0.04	0.13±0.04	0.13±0.04	0.00±0.04
$h_{ind eq}$	0.00±0.04	0.16±0.04	0.17±0.04	0.00±0.04
$h_{ind eq+sw}$	0.00±0.04	0.18±0.04	0.18±0.04	0.00±0.04
Comparison with ORAS5 (for $h_{ind eq+sw}$)				
	R	F_1	F_2	ϵ
ORAS5 SLA (1993-2018)	0.00±0.02	0.17±0.02	0.17±0.02	0.00±0.02
ORAS5 SLAfilt (1959-2018)	0.00±0.03	0.16±0.03	0.16±0.03	0.00±0.02
ORAS5 Z20filt (1959-2018)	0.00±0.03	0.16±0.03	0.16±0.02	0.00±0.02

Suppl. Table S2. Robustness of the (T_E , h_{ind}) tendency equation coefficients. The sensitivity tests here show that, when using independent h_{ind} instead of usual h , values of the regression coefficients become stable for different recharge indices, data, fields (SLA and Z20) and periods: $F_1 \sim F_2 \sim 0.16$ to 0.18 ± 0.03 , $R \sim \epsilon \sim 0.0 \pm 0.03$ (for normalized indices, i.e. unit in month⁻¹; 90% confidence intervals shown). Conversely, for usual h -based indices, the coefficients are not stable (cf. section 3).

Note that the RO, even if theoretically undamped as R and ϵ are negligible, is actually still damped because $residual_T$ (equation 6) is not a pure red noise but includes non-linear terms neglected in our 1st order linear approximation. Indeed, if we add to the T_E tendency equation a simple non-linear term cT_E^2 (quadratic term notably related to the non-linear response of convection to T_E ; e.g. Jin et al. 2020; see An et al. 2020 review on more complicate possibilities, e.g. a multiplicative noise, see also e.g. Jin et al. 2007, Graham et al. 2015, their equation (23)), the fit gives $c = +0.05 \pm 0.03$ and $R = -0.01 \pm 0.03$ month⁻¹. R becomes weakly negative (not at the 90% level but robust for longer ORAS5 SLA and Z20; not shown), suggesting that the oscillator is weakly damped.

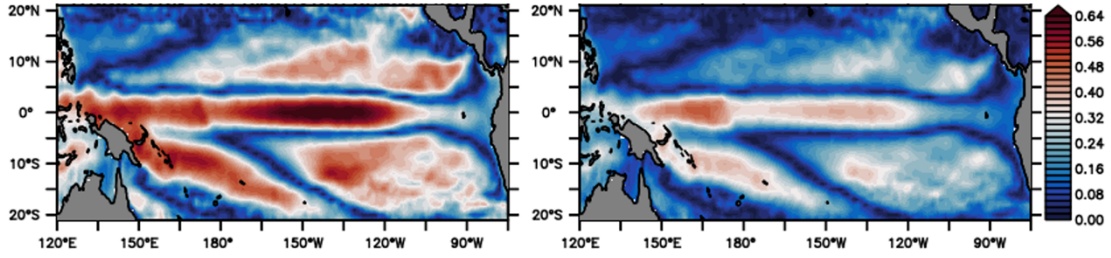
	$r_{T_E, h_{ind}}$ skill	a (IOD)	b (h_{ind})	c (T_E)
For satellite SLA (1993-2022):				
$h_{ind\ eq}$	0.50	-0.55 ±0.36	0.24±0.28	0.30±0.36
$h_{ind\ eq+sw}$	0.58	-0.48 ±0.34	0.39 ±0.26	0.26±0.34
For ORAS5 SLAfilt (1966-2011):				
$h_{ind\ eq}$	0.54	-0.50 ±0.28	0.32 ±0.21	0.10±0.28
$h_{ind\ eq+sw}$	0.60	-0.43 ±0.27	0.42 ±0.20	0.05±0.26
For ORAS5 Z20filt (1966-2011):				
$h_{ind\ eq}$	0.65	-0.43 ±0.25	0.48 ±0.19	0.05±0.25
$h_{ind\ eq+sw}$	0.68	-0.40 ±0.25	0.52 ±0.18	0.03±0.24

Suppl. Table S3. 14-month lead ENSO hindcasts based on IOD (Indian Ocean Dipole) and various recharge indices. 14-month lead hindcasts of T_E in NDJ_{yr1} (November of year 1 to January of year 2) using $a\ IOD + b\ h_{ind} + c\ T_E$ in SON_{yr0} (September to November of year 0), with coefficients a , b , c of the multivariate linear regression estimated from least-square fit. The 90% confidence intervals are shown, with the regression coefficients in bold when significantly different from zero at the 90% level.

Main messages of Table S3 are:

- 1) adding the SouthWest box (5°S-15°S, 120°E-170°W) improves the skill for all datasets/periods, more clearly for SLA than for Z20.
- 2) ORAS5 Z20 skill is better than ORAS5 SLA one, suggesting that thermocline depth metrics could perform better in a perfectly-observed ocean. Yet SLA has the advantage of being observed by satellite in near real-time, and the additional advantage of being more available in climate models outputs (e.g. CMIP) than Z20.
- 3) we have statistically-significant contributions from $h_{ind\ eq+sw}$ and IOD , but not from T_E itself (the IOD contribution a is always significantly negative, while the coefficient c for ENSO itself is never significant at 90% level). Hence this improved recharge index with updated datasets confirms earlier studies emphasizing the IOD influence on following year's ENSO phase (Izumo et al. 2010, 2014, 2016, Dayan et al. 2014, Jourdain et al. 2016). Regression coefficients have qualitatively similar values among datasets/periods.

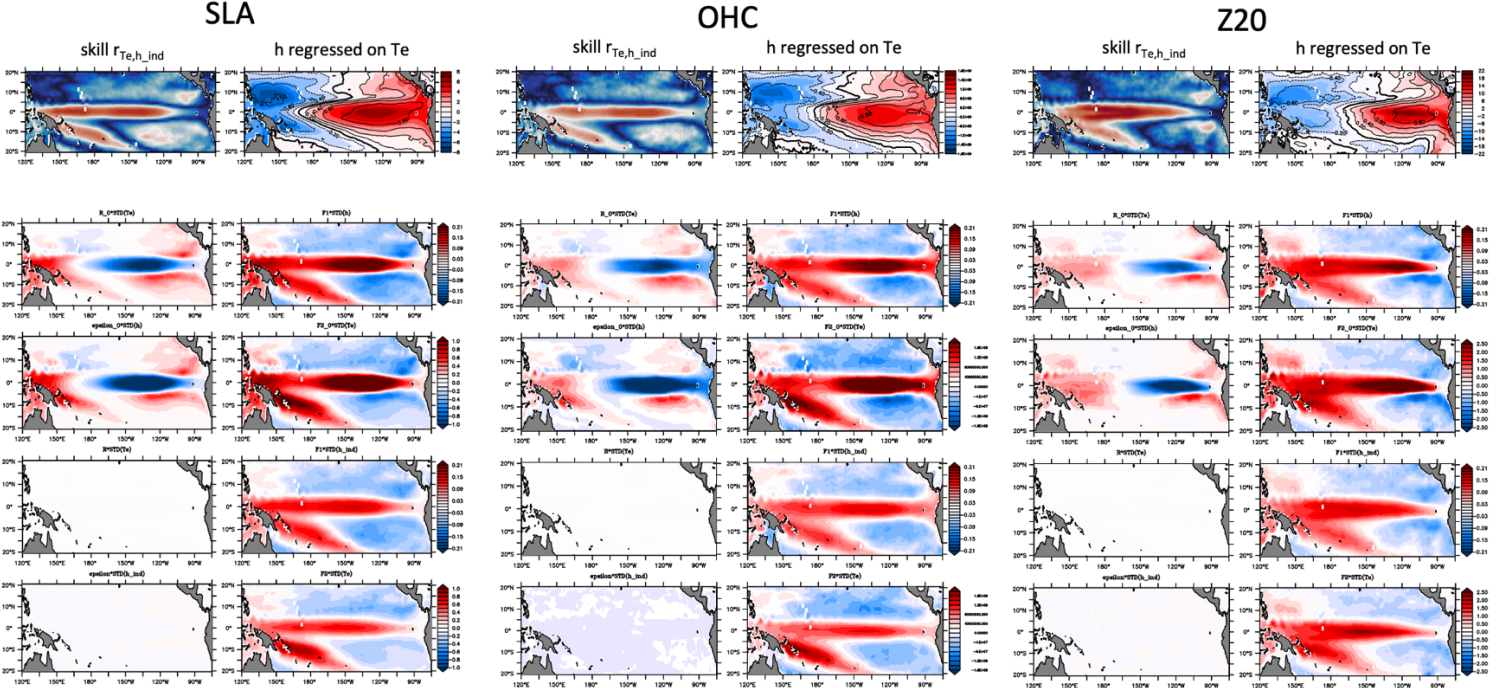
a) skill of the regression of dT_E/dt onto (T_E, h_{ind}) : r_{Te} b) skill of the regression of dh_{ind}/dt onto (T_E, h_{ind}) : $r_{h_{ind}}$



Suppl. Fig. S1. Respective contributions of the r_{Te} skill and $r_{h_{ind}}$ skill to the $r_{Te, h_{ind}}$ skill. a) Pearson correlation skill r_{Te} for the regression of dT_E/dt onto $(T_E(t), h_{ind}(x, y, t))$ (equation 4). b) same but for $r_{h_{ind}}$ for the regression of dh_{ind}/dt .

Main messages of Fig. S1:

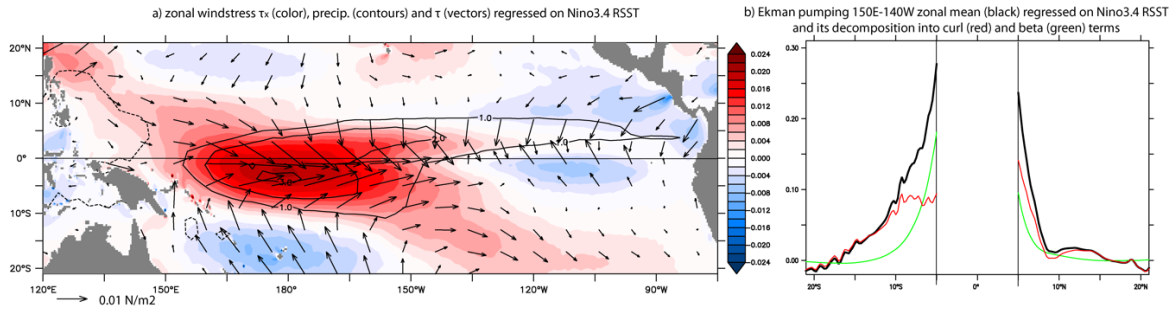
Both r_{Te} and $r_{h_{ind}}$ contribute to the skill $r_{Te, h_{ind}}$ (square-root of the RV coefficient) shown in Fig. 2k for the tendency equation of the vector (T_E, h_{ind}) , since we can mathematically show that $r_{Te, h_{ind}}^2 \approx (r_{Te}^2 + r_{h_{ind}}^2)/2$ for normalized vectors, as T_E and h_{ind} are by definition uncorrelated, and as their tendencies are also almost uncorrelated (<0.1). Note that r_{Te} tends to have a similar spatial pattern to $r_{h_{ind}}$, but of stronger amplitude (though with also relatively larger central-equatorial values). The similarity of the spatial patterns, notably with the strong skill in the west and southwest Pacific, is likely because h_{ind} tends to vary in phase in the west-central equatorial Pacific and southwest tropical Pacific (cf. Supplementary Text S2). r_{Te} tends to be of larger amplitude than $r_{h_{ind}}$, likely because $dT_E(t)/dt$ is less noisy (T_E being a box average) than $dh_{ind}(x, y, t)/dt$, which is for each (x, y) point. The pair $(T_E(t), h_{ind}(x, y, t))$ can thus more easily explain statistically $dT_E(t)/dt$ variance than dh_{ind}/dt variance.



Suppl. Fig. S2. Equivalent (partly) to Fig. 2 (which is based on 1993-2021 satellite SLA) but for ORAS5 (60-yr long period 1959-2018), comparing SLA (left), OHC (middle) and Z20 (right). First upper-left panel is the skill map, as Fig. 2k (with the same color scale as Fig. 2k). 2nd upper panel is the regression of h onto T_E (the fast adjustment mode), as Fig. 1a. Panels of 2nd and 3rd row panels are for usual non-orthogonal (T_E, h) basis, as Fig. 2a,b,e,f. Panels of 4th and 5th rows are for orthogonal (T_E, h_{ind}) basis, as Fig. 2c,d,g,h. SLA is as in Fig. 2 in cm. OHC is the oceanic heat content from ocean surface to bottom in J (color scale from -1.8×10^9 to $+1.8 \times 10^9$ J in 1st row, and from -1.6×10^8 to $+1.6 \times 10^8$ J in 3rd and 5th rows). Z20 is the 20°C isotherm depth in m (no interdecadal high-pass filter applied here; only weak differences if applied; not shown).

Main messages of Fig. S2 are:

- 1) ORAS5 SLA gives similar results to satellite SLA (we have also tested the sensitivity to the periods chosen: ORAS5-based maps are similar for 1959-2018 and shorter 1993-2018 period; not shown).
- 2) SLA, OHC and Z20 are qualitatively similar, with some differences in patterns and in the correlation between T_E and h . OHC spatial patterns tend to be in between SLA and Z20 patterns, but the skill is weaker. Note that the lag-0 correlation along the central-eastern equatorial Pacific (i.e. for h_{eq} and h_{eq+sw}) with T_E is weaker for Z20 than for SLA, possibly because of 1st baroclinic mode playing more role for Z20 than for SLA, which will be more influenced by higher modes, notably the 2nd baroclinic mode (we have compared each baroclinic mode contribution in the LCS simulation forced by ERA-I windstress of Izumo, Lengaigne et al. 2018; not shown). These different baroclinic mode contributions could partly explain some differences in results between Izumo, Lengaigne et al. (2018) study, based on the LCS model that take into account several baroclinic modes, and Neske and McGregor (2018) study based on a shallow water model, which only simulates the 1st baroclinic mode.

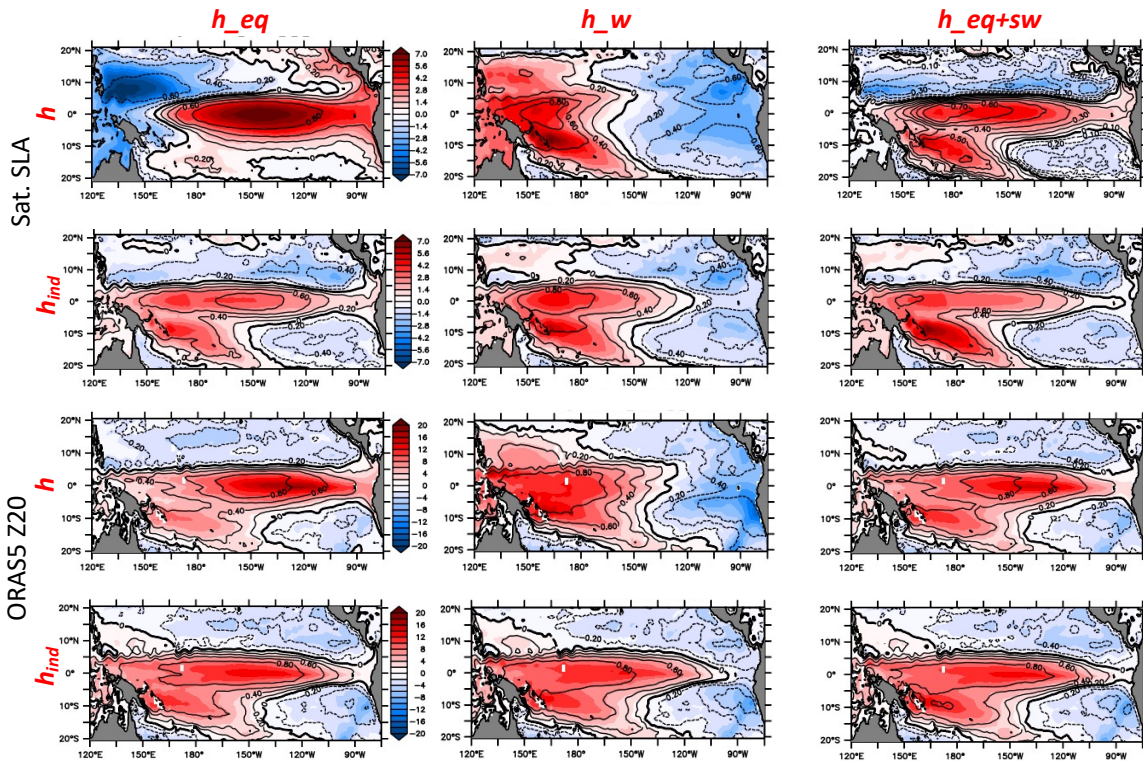


Suppl. Fig. S3. ENSO asymmetrical Ekman pumping. a) Zonal wind stress τ_x (color, $\text{N}\cdot\text{m}^{-2}$), precipitation (contours, $\text{mm}\cdot\text{day}^{-1}$) and wind stress τ (vectors) regressed on T_E . **b)** Regression of the 150°E-140°W zonal mean of Ekman pumping (black, 10^{-5} m/s) on T_E , and Ekman pumping decomposition into its wind stress curl (red) and beta (green) terms, only defined out of the 5°N-5°S equatorial band (shown by vertical lines).

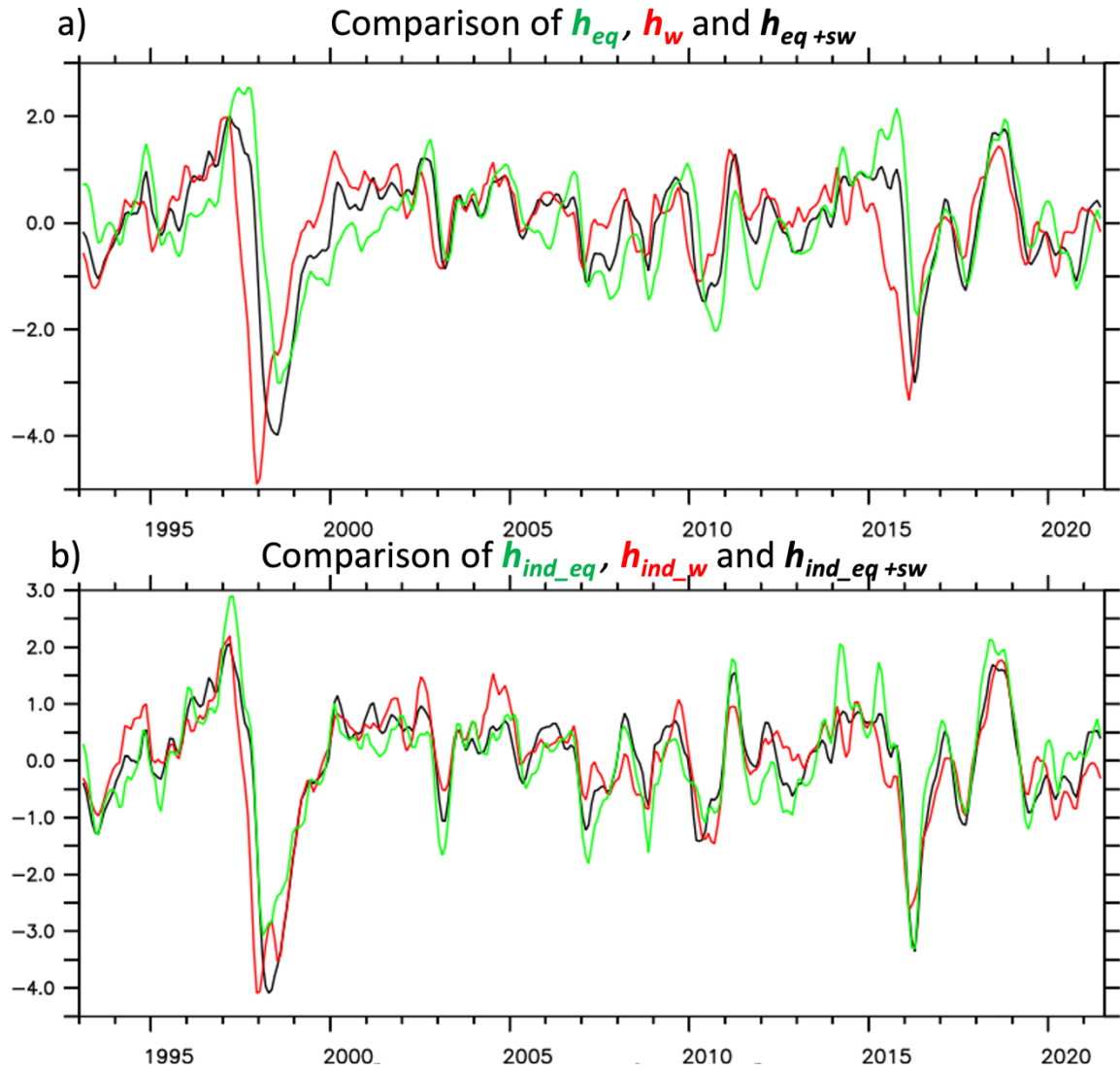
Main messages of Fig. S3:

In the southern hemisphere, the decomposition shows that south of $\sim 7^\circ\text{S}$, the wind stress curl term is the main contributor to Ekman pumping, while north of $\sim 7^\circ\text{S}$, the beta term is also important. Hence, Ekman pumping asymmetry is mainly due to wind stress curl (curl itself mostly due to $-d\tau_x/dy$; not shown), with some added asymmetry from the beta term, proportional to τ_x (Yokoi et al. 2008), large between $\sim 7^\circ\text{S}$ and 5°S .

Note that the western boundary coastline meridional asymmetry would conversely favor a larger northwest recharge (in the La Niña case discussed here below; discharge in the El Niño case), as shown by an LCS (Linear Continuously Stratified model; McCreary 1980) idealized experiment with a symmetric zonal wind stress forcing (Izumo, Lengaigne et al. 2018, their Fig. 5). We have done a similar experiment, but with a more realistic ENSO-like asymmetric windstress (like the one of panel a), with easterlies shifted to the south during La Niña, plus a reversal to westerlies south of $\sim 15^\circ\text{S}$, related to a poleward shift of the SPCZ (vice versa for the El Niño case; see also Alory and Delcroix 2002; Cibot et al. 2005; McGregor et al. 2013). This asymmetry indeed favors a larger southwest recharge (not shown).



Suppl. Fig. S4. Regression maps of $h(x,y,t)$ or $h_{ind}(x,y,t)$ onto various $h(t)$ or $h_{ind}(t)$ recharge indices. Spatial patterns associated with h_{eq} (left column), h_w (middle column) and h_{eq+sw} (right column) look significantly closer for h_{ind} (2nd and 4th rows) than for usual full h (1st and 3rd rows). I.e. h_{ind} harmonizes recharge metrics, making indices converge. First two rows are based on satellite SLA, the last two on ORAS5 Z20filt. Recharge indices are normalized, so that these maps show typical amplitudes (units: cm for SLA and m for Z20).



Suppl. Fig. S5. Using h_{ind} harmonizes the various recharge indices. a) time series of h_{eq} (green), h_w (red) and h_{eq+sw} (black) from satellite SLA. b) as a but for their independent components h_{ind_eq} (green), h_{ind_w} (red) and h_{ind_eq+sw} (black).

Main message of Fig. S5:

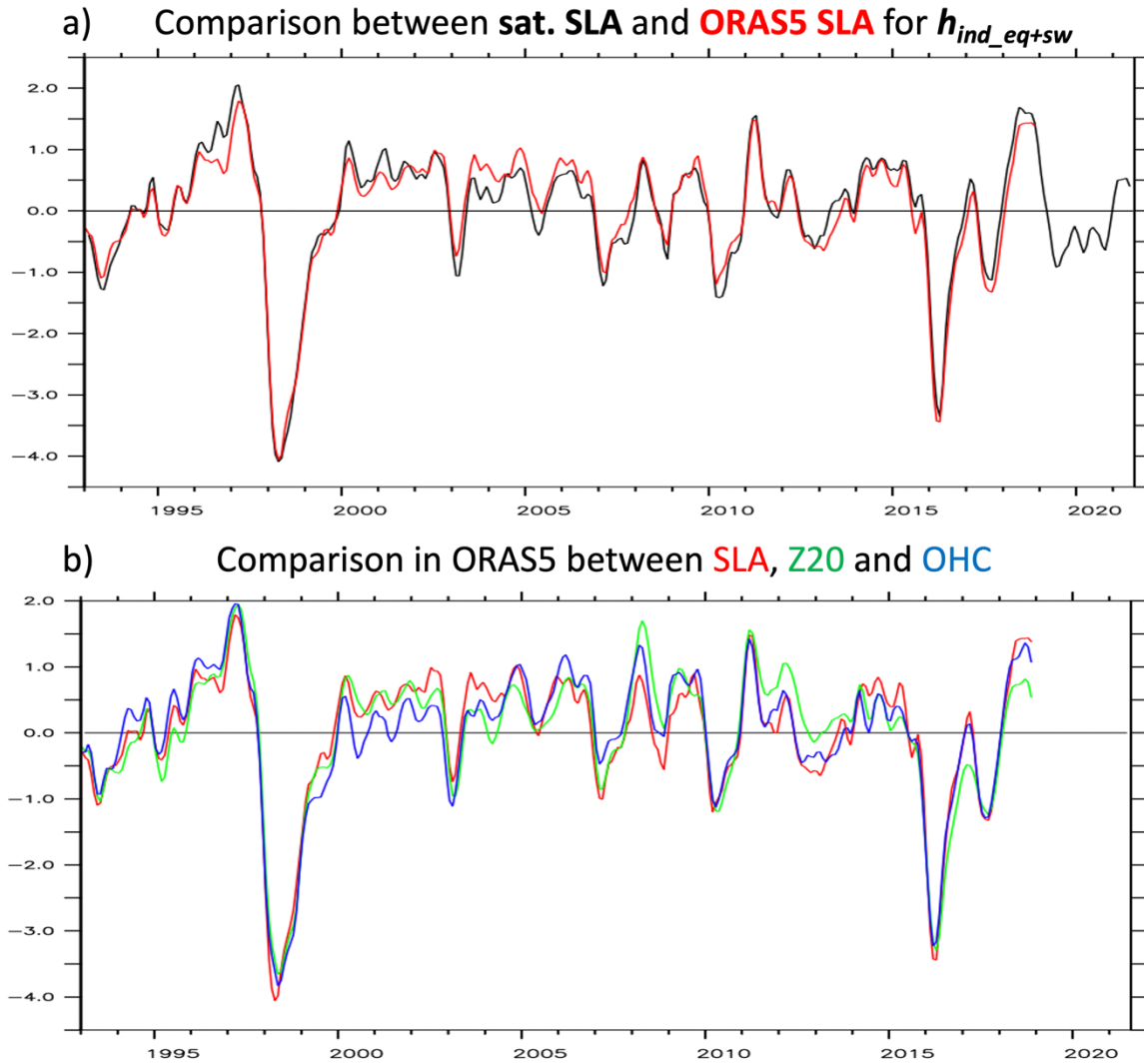
Indices are much better correlated for independent component than for full signal:

$$r(h_{ind_eq}, h_{ind_w}) = 0.79 \text{ (} r^2 = 62\% \text{)} \text{ instead of } 0.18 \text{ (} 3\% \text{)}$$

$$r(h_{ind_eq}, h_{ind_eq+sw}) = 0.91 \text{ (} 82\% \text{)} \text{ instead of } 0.79 \text{ (} 62\% \text{)}$$

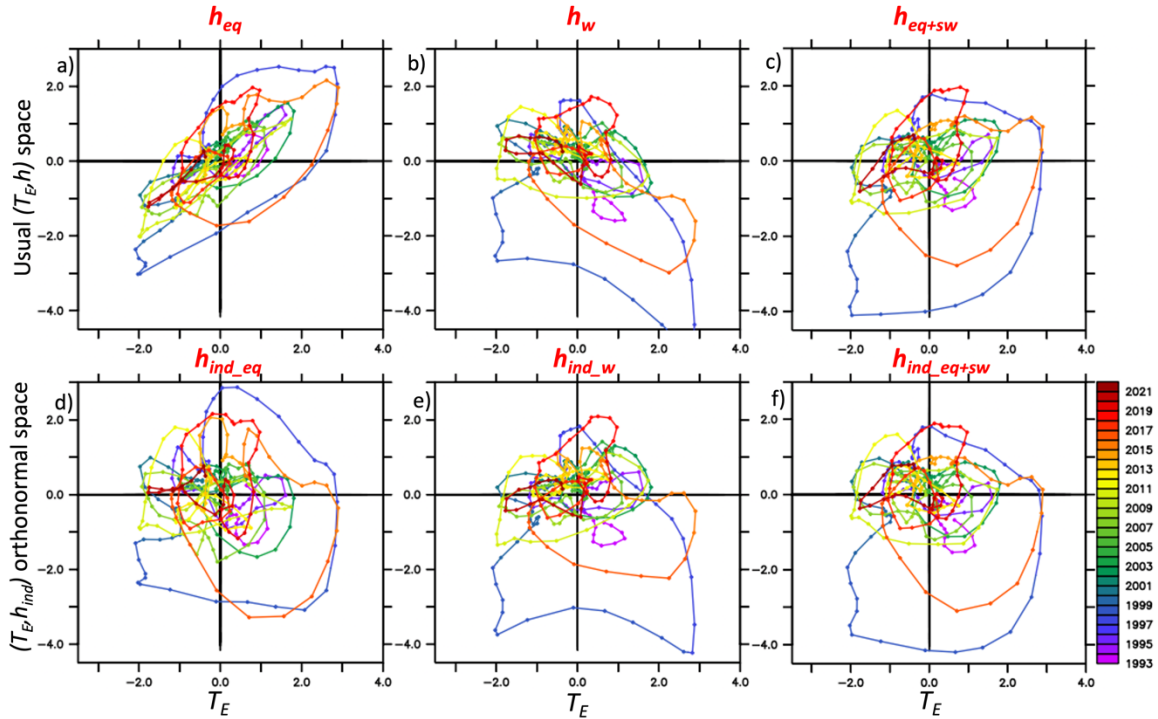
$$r(h_{ind_w}, h_{ind_eq+sw}) = 0.88 \text{ (} 78\% \text{)} \text{ instead of } 0.67 \text{ (} 44\% \text{)}$$

This confirms that using h_{ind} , i.e. removing the dependent component, helps in reconciling and harmonizing the various recharge indices used in the literature. Furthermore, h_{ind_eq+sw} is close both to h_{ind_eq} and h_{ind_w} .

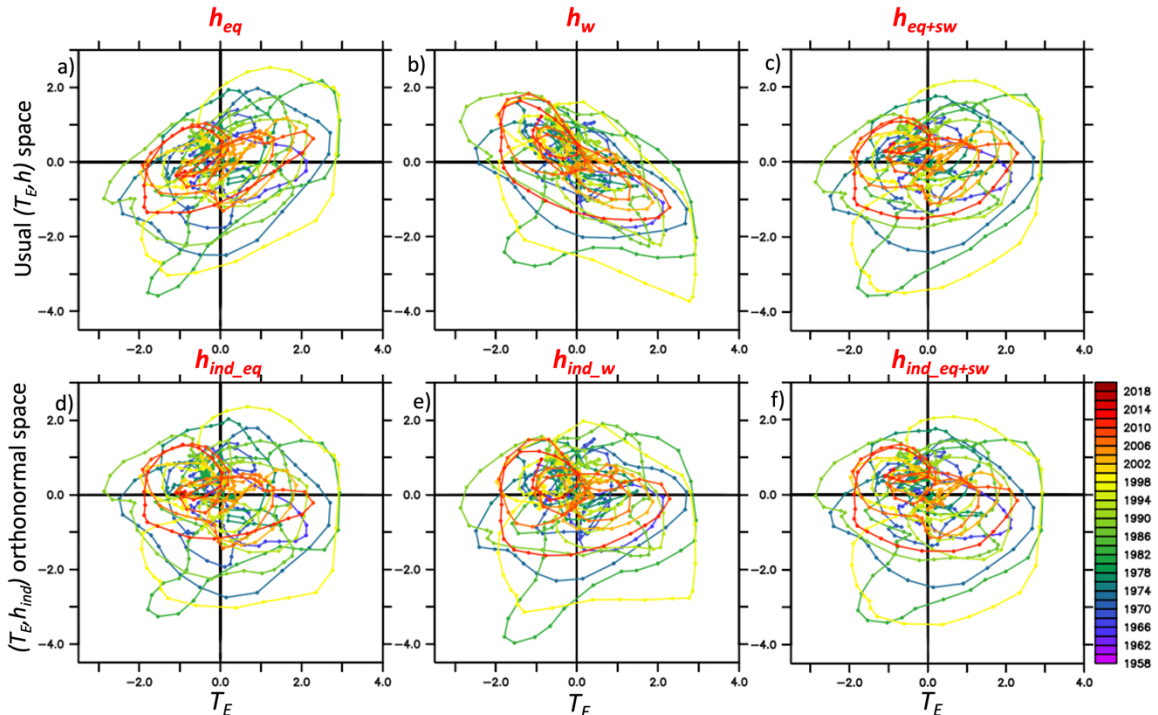


Suppl. Fig. S6. Comparing a) ORAS5 SLA (red) with satellite SLA (black), and b) SLA (red), Z20 (green) and OHC (blue) in ORAS5, for h_{ind_eq+sw} index (shown from 1993). Panel a validates ORAS5 SLA, highly correlated ($r=0.97$; $r^2=95\%$) to observed satellite SLA for h_{ind_eq+sw} (and also for h_{ind_eq} and h_{ind_w} ; not shown; ORAS5 shown here without high-pass decadal filter here for comparison with satellite SLA; note that ORAS5 may not be as good before 1993 before which the reanalysis does not assimilate satellite sea level observations). Panel b shows that, in ORAS5, SLA is highly correlated to Z20 ($r=0.94$; $r^2=88\%$) and OHC ($r=0.96$; $r^2=92\%$), i.e. SLA, Z20 and OHC are almost equivalent for h_{ind_eq+sw} (and also for h_{ind_eq} and h_{ind_w} ; not shown).

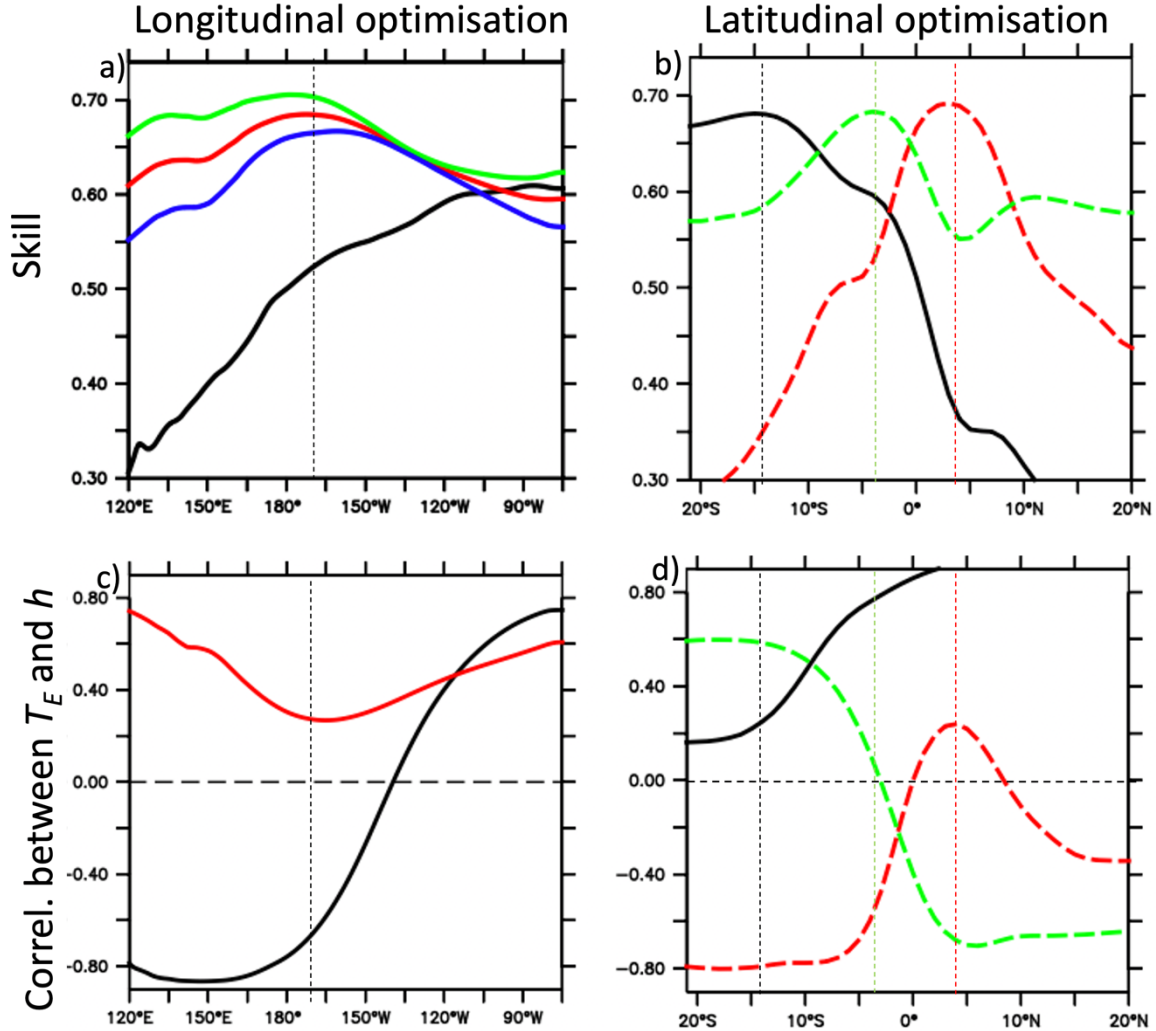
Note that using h_{ind} instead of usual h also harmonizes SLA-based and Z20-based metrics: e.g. the squared correlation between SLA-based h_{eq} and Z20-based h_{eq} is $r^2=81\%$ (88%) instead of 72% (81%). Adding the Southwest further increases r^2 to 85% (90%) for full h_{eq+sw} and even to 88% (92%) for independent h_{ind_eq+sw} . The r^2 value is given over the 1993-2019 period (in parenthesis for whole ORAS5 1959-2018 period with interdecadal high-pass filter applied).



Suppl. Fig. S7: as Fig. 3, but for satellite SLA over its shorter available period (1993-2021).

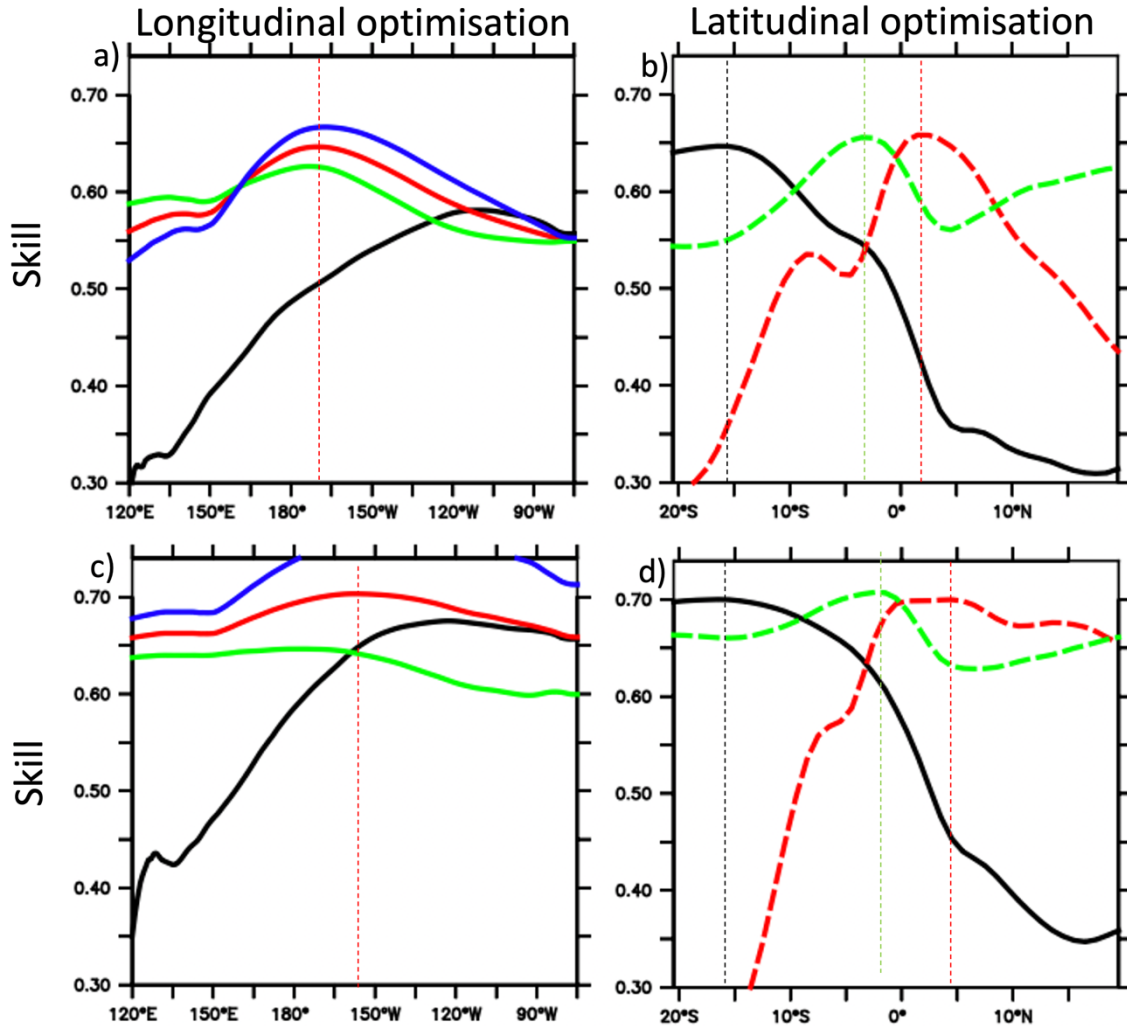


Suppl. Fig. S8. As Fig. 3, but for ORAS5 Z20filt. Results are robust, with only 2nd order differences: e.g. extreme El Niño events cause a weaker discharge in Z20 than in SLA (and thus a weaker El Niño/La Niña asymmetry). Hence, trajectories in bottom panels look even more circular and closer to the ideal RO circular trajectories when using Z20 instead of SLA (and when removing interdecadal variability, as done here).



Suppl. Fig. S9. Finding the best averaging box for h_{ind} to optimize both T_E and h_{ind} tendency equations of RO. Panel a) is almost similar to Fig. 2j, showing the optimization of the eastern edge longitude. The black line shows the skill $r_{Te,h_{ind}}$ for h_{ind} averaged over: the equatorial band ($5^{\circ}N$ - $5^{\circ}S$) with its western edge fixed to $120^{\circ}E$ and its eastern edge varying, given by the x-axis. The black line shows that the optimal eastern edge for the equatorial band is at equatorial Pacific eastern boundary, $80^{\circ}W$. Red line is for a two-rectangle region, this classical equatorial box ($5^{\circ}N$ - $5^{\circ}S$, $120^{\circ}E$ - $80^{\circ}W$) plus a southern $5^{\circ}S$ - $15^{\circ}S$ box with the same western edge fixed at $120^{\circ}E$ and its eastern edge varying. Its optimal is around $170^{\circ}W$ (indicated by a dashed black vertical line, i.e. the optimal $eq+sw$ region). The green and blue lines are similar to the red line, but specifically for r_{Te} and for $r_{h_{ind}}$ respectively. Panel c) shows the associated lag-0 correlation between T_E and h , for the same regions as the black and red lines in panel a). The lag-0 correlation interestingly is almost the lowest for the optimal $eq+sw$ region. This is an additional interest of this region, e.g. the difference between $h_{ind,eq+sw}$ and h_{eq+sw} is much weaker than between $h_{ind,eq}$ and h_{eq} . Concerning the western edge longitude, the optimal is around $100^{\circ}E$ - $120^{\circ}E$, so we have kept $120^{\circ}E$ to stay in Pacific, as Meinen and McPhaden (2000) choice. Right panels are showing the optimization of the latitudinal edges of the h_{ind} two-rectangle averaging region. The black curve is for the southern edge of the southwest rectangle ($120^{\circ}E$ - $170^{\circ}W$, $5^{\circ}S$ to y_{sw} indicated in horizontal axis, the other region being fixed to the classical equatorial box $5^{\circ}N$ - $5^{\circ}S$, $120^{\circ}E$ - $80^{\circ}W$). y_{sw} optimum is around 16 - $12^{\circ}S$ (cf. black dashed vertical line at $14^{\circ}S$), confirming that $15^{\circ}S$ is a good simple choice. The green dashed curve is for the southern edge of the equatorial band rectangle ($120^{\circ}E$ - $80^{\circ}W$; $5^{\circ}N$ -

y_{eqS} , the southwest region being 120°E-170°W, 15°S to y_{eqS}). The optimum is around 6-2°S, confirming that 5°S is a good simple choice. The red curve is for equatorial band northern edge (120°E-80°W; 5°S- y_{eqN} , the southwest region being 120°E-170°W, 15°S to 5°S). The optimum is around 2-6°N, confirming that 5°N is a good simple choice. Note that theoretically, we could even do a multivariate optimization. We have done some tests that confirm our choice (e.g. if y_{sw} =14°S, y_{eqS} =4°S and y_{eqN} =3°N, skill is 0.70, only slightly larger than 0.69 for 15°S, 5°S, 5°N, both skills being much higher than 0.61 for classical h_{eq}), within the range of uncertainties (e.g. differences between satellite SLA shown here and ORAS5 Z20filt in next figure). All these analyses confirm that the optimal (and still simple) region combines the classical equatorial band (5°S-5°N, 120°E-80°W) and the southern band 15°S-5°S, from 120°E to about 170°W, i.e. $h_{ind\ eq+sw}$.



Suppl. Fig. S10. Same as S9ab (based on satellite SLA) but using ORAS5 SLAfilt (upper) or ORAS5 Z20filt (lower). Upper panels show that ORAS5 SLA results are consistent with satellite ones, with similar optimal longitude and latitudes (skill overall slightly weaker). Lower panels show that Z20 is overall consistent with SLA, with however less sharp latitudinal edges and an optimal eastern edge of southwest rectangle at ~155°W instead of ~170°W. But the difference between these two longitude choices is *in fine* not significant anyway (almost similar skill, and correlation of 0.99 between the two definitions). Therefore, SLA and Z20 are almost similar for $h_{ind\ eq+sw}$ (correlation of 0.96, cf. Fig. S6b).