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► **To cite this version:**

Grégoire Sergeant-Perthuis, Nils Ruet. Inference on diagrams in the category of Markov kernels (Extended abstract). 2024. hal-04527780

**HAL Id: hal-04527780**

**<https://hal.sorbonne-universite.fr/hal-04527780>**

Preprint submitted on 30 Mar 2024

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# Inference on diagrams in the category of Markov kernels (Extended abstract)

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Graphical models are widely used families of probability distributions that capture conditional independence relations between a collection of variables  $X_i, i \in I$ ; celebrated examples are Hidden Markov models and Bayesian Networks [1]. Graphical models are built from directed and undirected graphs  $G = (I, A)$  where nodes  $i \in I$  are uniquely identified with the variables  $X_i$ . Inference in graphical models ultimately boils down to inference for an undirected graphical model, achieved through the Belief Propagation algorithm [2]. Such Inference constitutes a specific instance of variational inference as it revolves around a free energy termed the Bethe free energy [2]. Adopting a variational inference perspective for graphical models has facilitated the extension of the Belief Propagation algorithm to encompass broader classes of probability distributions, enabling the accommodation of interactions among more than 2 variables in contrast to traditional graphical models (factor graphs [3]); this is achieved through the introduction of the Kikuchi free energies [4]. Let us denote  $\mathbf{Mes}^f, \mathbf{Kern}^f$ , the categories with objects finite measurable spaces and respectively with morphisms measurable maps and the second Markov Kernels (stochastic matrices).  $\mathbf{Mes}^f$  can be seen as a subcategory of  $\mathbf{Kern}^f$ . As exhibited in [5–7], what underlies variational inference for those classes of probability distributions are presheaves from a finite poset to  $\mathbf{Mes}^f$ , which morphisms are epimorphisms. We will call them the ‘graphical’ presheaves. Our contribution is to extend the Generalized Belief Propagation [5] to any presheaf from a finite poset to  $\mathbf{Kern}^f$ . This work is contained in Chapter 9 of [8] and Appendix 1 of unpublished [9], where we consider the more general problem of optimizing a collection of cost functions over a presheaf of signals.

## 1. Motivation and related work

Consider a collection of agents represented by vertices  $i \in I$  that can communicate their beliefs to neighboring vertices  $\partial i$  through undirected edges  $e \in A$ . Each agent has its own representation of its environment, denoted by  $E_i$ . They can share their beliefs with neighboring nodes  $j \in \partial i$  through a measurable map  $f_e^i : E_i \rightarrow E_e$ . Graphical models and their extensions do not allow us to account for such heterogeneity in the way each agent models their environment. Such setting is better captured by cellular sheaves [10] and applications [11], important examples of which are Sheaf Neural Networks [12], are limited to functors from the poset associated to a graph ( $i \leq e \iff i \in e$ ) to the category of finite vector spaces  $\mathbf{Vect}^f$ . We are interested in the more general case where beliefs transfer through a hierarchy, i.e. a poset, and we provide an algorithm for inference in such case where Sheaf Neural Networks can’t be used; by convention, we consider presheaves instead of functors: ‘orders’ are given top-down. More generally, cellular sheaves are restricted to the face poset of a cell complex and hence don’t apply to all hierarchies and therefore not to our case.

## 2. Free energy for poset shaped diagrams in $\mathbf{Kern}^f$ and message passing algorithm

**Definition 1** (Graphical presheaves). Let  $I$  be a finite set and  $\mathcal{A} \subseteq \mathcal{P}(I)$  be a sub-poset of the powerset of  $I$ . Let  $E_i, i \in I$  are finite sets. For  $a \in \mathcal{A}$   $E_a := \prod_{i \in a} E_i$ , let  $F(a) := E_a$ , and for  $b \subseteq a$ , let  $F_b^a : E_a \rightarrow E_b$

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be the projection map from  $\prod_{i \in a} E_i$  to  $\prod_{i \in b} E_i$ .  $F$  is called a graphical presheaf from  $\mathcal{A}$  to  $\mathbf{Mes}^f$ .

For  $\mathcal{A}$  a finite poset, the ‘zeta-operator’ of  $\mathcal{A}$ , denoted  $\zeta$ , from  $\bigoplus_{a \in \mathcal{A}} \mathbb{R}$  to  $\bigoplus_{a \in \mathcal{A}} \mathbb{R}$  is defined as, for any  $\lambda \in \bigoplus_{a \in \mathcal{A}} \mathbb{R}$  and any  $a \in \mathcal{A}$ ,  $\zeta(\lambda)(a) = \sum_{b \leq a} \lambda_b$ .  $\zeta$  is invertible [13], we denote  $\mu$  its inverse; its matrix expression  $(\mu(a, b), b \leq a)$  defines the Möbius function of  $\mathcal{A}$ . Let  $F$  be a presheaf from  $\mathcal{A}$  to  $\mathbf{Kern}^f$ ;  $F_b^a : F(a) \rightarrow F(b)$  is denoted element-wise as  $F_b^a(\omega_b | \omega_a)$ , with  $\omega_b \in F(b)$ ,  $\omega_a \in F(a)$ . It induces a presheaf  $\tilde{F}$  from  $\mathcal{A}$  to  $\mathbf{Vect}^f$ , where  $\tilde{F}_b^a : \mathbb{P}(F(a)) \rightarrow \mathbb{P}(F(b))$  is the linear map that sends probability distributions  $p \in \mathbb{P}(F(a))$  to  $F_b^a \circ p$ . Following [5], we introduce a free energy  $\mathcal{F}(Q) = \sum_{a \in \mathcal{A}} c(a) (\mathbb{E}_{Q_a}[H_a] - S(Q_a))$ ;  $c(a) = \sum_{b \geq a} \mu(b, a)$  is the generalization of the inclusion-exclusion formula associated to  $\mathcal{A}$ .  $S(Q_a) = -\sum_{\omega_a \in F(a)} Q_a(\omega_a) \ln Q_a(\omega_a)$  is the entropy of  $Q_a$ . We propose to solve  $\inf_{Q \in \lim \tilde{F}} \mathcal{F}(Q)$ .  $\tilde{F}^*$  is the functor obtained by dualizing the morphisms  $\tilde{F}_b^a$ , i.e.  $\tilde{F}_b^{*,b} : \tilde{F}(b)^* \rightarrow \tilde{F}(a)^*$  sends linear maps  $l_b : \tilde{F}(b) \rightarrow \mathbb{R}$  to  $l_b \circ \tilde{F}_b^a : \tilde{F}(a) \rightarrow \mathbb{R}$ .

For a functor  $G$  from  $\mathcal{A}$  to  $\mathbb{R}$ -vector spaces, we define  $\mu_G$  as, for any  $a \in \mathcal{A}$  and  $v \in \bigoplus_{a \in \mathcal{A}} G(a)$ ,  $\mu_G(v)(a) = \sum_{b \leq a} \mu(a, b) G_a^b(v_b)$ . Let us define the function  $FE : \prod_{a \in \mathcal{A}} \mathbb{P}(E_a) \rightarrow \prod_{a \in \mathcal{A}} \mathbb{R}$  as  $FE(Q) = (\mathbb{E}_{Q_a}[H_a] - S_a(Q_a), a \in \mathcal{A})$ , which sends a collection of probability measures over  $\mathcal{A}$  to their Gibbs free energies. For any  $Q \in \prod_{a \in \mathcal{A}} \mathbb{P}(E_a)$ , let us denote  $d_Q FE$  as the differential of  $FE$  at the point  $Q$ .

**Theorem 1.** *Let  $\mathcal{A}$  be a finite poset, let  $F$  be a presheaf from  $\mathcal{A}$  to  $\mathbf{Kern}^f$ . Let  $H_a : F(a) \rightarrow \mathbb{R}$  be a collection of (measurable) functions. The critical points of  $\mathcal{F}$  are the  $Q \in \lim \tilde{F}$  such that,*

$$\mu_{\tilde{F}^*} d_Q FE|_{\lim \tilde{F}} = 0 \quad (1)$$

The message-passing algorithm we consider is Algorithm 1; it specializes to the General Belief Propagation for graphical presheaves. For two elements  $a, b \in \mathcal{A}$ , such that  $b \leq a$ , two types of messages are considered: top-down messages  $m_{a \rightarrow b} \in \mathbb{R}^{F(b)}$  and bottom-up messages  $n_{b \rightarrow a} \in \mathbb{R}^{F(a)}$ .

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**Algorithm 1:** Message passage algorithm for presheaves from  $\mathcal{A}$  to  $\mathbf{Kern}^f$

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**Data:** Initialization:  $(m_{a \rightarrow b}^0 \in \mathbb{R}^{F(b)}, b, a \in \mathcal{A} \text{ s.t. } b \leq a)$ , a poset  $\mathcal{A}$ , a presheaf  $F : \mathcal{A} \rightarrow \mathbf{Kern}^f$ ;

- 1 **for**  $t \leq T$  **do**
- 2     **for**  $a \in \mathcal{A}, b \in \mathcal{A}$  such that  $b \leq a$  **do**
- 3          $\forall \omega_a \in F(a), \quad n_{b \rightarrow a}(\omega_a) \leftarrow \prod_{\substack{c: b \leq c \\ c \not\leq a}} \sum_{\omega'_b \in F(b)} m_{c \rightarrow b}(\omega'_b) \cdot F_b^a(\omega'_b | \omega_a)$
- 4     **end**
- 5     **for**  $a \in \mathcal{A}, b \in \mathcal{A}$  such that  $b \leq a$  **do**
- 6          $b_a = e^{-H_a} \prod_{\substack{b \in \mathcal{A} \\ b \leq a}} n_{b \rightarrow a}$
- 7          $p_a = \frac{b_a}{\sum_{\omega_a} b_a(\omega_a)}$
- 8          $m_{a \rightarrow b} \leftarrow m_{a \rightarrow b} \cdot \frac{\tilde{F}_b^a(p_a)}{p_b}$
- 9     **end**
- 10 **end**

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A criterion to stop the algorithm is when the beliefs do not change, i.e., when  $p_a^{t+1} \approx p_a^t$ . The fixed points of the previous message-passing algorithm correspond to critical points of  $\mathcal{F}$  over  $\lim F$  (Corollary of Theorem 2.2 [9]v2). Theorem 1 differs from a similar characterization of critical points of a free energy for specifications in [14] by the fact that the  $\mu_{\tilde{F}^*}$  and  $\lim \tilde{F}$  are applied to the same presheaf  $\tilde{F}$  and not two different presheaves/functors  $(G, F)$ .

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