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► **To cite this version:**

Grégoire Sergeant-Perthuis. Functoriality of inference on diagrams in the category of Markov kernels.. Non Commutative Geometry & Higher Structures, P. Batakidis; F. Bonechi; A. S. Cattaneo; N. Ciccoli; F. D' Andrea; D. Fiorenza; M. Jotz; F. Petalidou; M. Schiavina; P. Xu, Sep 2024, Thessaloniki, Greece. hal-04706267v1

**HAL Id: hal-04706267**

**<https://hal.sorbonne-universite.fr/hal-04706267v1>**

Submitted on 23 Sep 2024 (v1), last revised 26 Sep 2024 (v2)

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# Functoriality of inference on diagrams in the category of Markov kernels.

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Non Commutative Geometry & Higher Structures  
Thessaloniki 21/9/24

Papers: [arXiv:2201.11876](https://arxiv.org/abs/2201.11876), [arXiv:2403.16104](https://arxiv.org/abs/2403.16104) (SYCO 12), [hal-04527780](https://hal.archives-ouvertes.fr/hal-04527780) (ACT 7)

## Introduction to geometric deep learning [BBCV21]:

- Deep learning  $\leftarrow$  curse of dimensionality
- Accounting for symmetry
  - $\rightarrow$  Translation  $\rightsquigarrow$  CNN
  - $\rightarrow$  Other groups [SPMBO22]
- Geometry  $\rightsquigarrow$  discretize
  - $\rightarrow$  Graph NN [BBCV21]
  - $\rightarrow$  Nodes share same features
  - $\rightarrow$  Limitations: heterogeneous data
- Heterogeneity
  - $\rightarrow$  Cellular sheaves [Cur13]
  - $\rightarrow$  Cell complex, faces  $\rightsquigarrow$  feature space, inclusions  $\rightsquigarrow$  linear maps
  - $\rightarrow$  Functor from a poset to **Vect** [SP22, SP24a, SPR24, SP24b]
  - $\rightarrow$  Sheaf Neural Networks [BGC<sup>+</sup>22]

- Our focus:
  - Bayesian inference, graphical models, Markov random fields, factor graphs

### Context:

Let  $X$  be a random variable taking values in a finite measurable space  $E_X$ , and  $\theta \in \Theta \subseteq \mathbb{R}^d$  that parametrizes a collection of probability measures  $P(x|\theta)$ , where  $x \in E_X$ .

Assume that one is given a prior  $Q \in \mathbb{P}(\Theta)$ , where  $\mathbb{P}(\Theta)$  denotes the space of probability measures on  $\Theta$ . For any observation  $x_0 \in E_X$ , one computes the posterior using Bayes' rule:

$$P(\theta|x) = \frac{P(x|\theta)Q(\theta)}{\int P(x|\theta)Q(\theta) d\theta}$$

- Problem: When  $\theta = (\theta_i, i \in [0, N])$  is a collection of variables, where each  $\theta_i \in E$ .
- $\sum_{\theta} P(x|\theta)Q(\theta) = \sum_{\theta_0} \cdots \sum_{\theta_N} P(x|\theta_0, \dots, \theta_N)Q(\theta_0, \dots, \theta_N)$ 
  - Number of operations:  $\mathcal{O}(|E|^N)$
- Notation: For a set of indices  $I$  and a subset  $a \subseteq I$ ,  $\theta_a := (\theta_i \in E_i, i \in a)$ .
- In what follows, all the sets in which variables take values will be finite:  $E_i$  are finite sets.

- One relation to statistical mechanics:

Let  $\theta = (Y_i \in E_i, i \in I)$  be the unobserved variables, and  $X = (X_j \in F_j, j \in J)$  the observed variables. Both  $I$  and  $J$  are finite sets, and  $E_j$  for  $j \in J$  and  $F_i$  for  $i \in I$  are finite sets.

$$\ln P(\theta, X) = -\beta \sum_{a \subseteq I \cup J} H_a(X_{a \cap J}, Y_{a \cap I})$$

Given an observation  $x = (x_j, j \in J)$ , computing  $\ln P(\theta|x)$  is equivalent to computing:

$$\ln \sum_{(y_i, i \in I)} e^{-\beta \sum_{a \subseteq I \cup J} H_a(x_{a \cap J}, y_{a \cap I})}$$

This is the same as:

$$\ln Z(x) := \ln \sum_{\theta \in \prod_i E_i} e^{-\beta \tilde{H}_x(\theta)}$$

- Similar frameworks but different names: Bayesian networks, graphical models, factor graphs, Markov random fields.

### Definition (Factorisation Space)

Let  $I$  be a finite set, and let  $\mathcal{A} \subseteq \mathcal{P}(I)$ , where  $\mathcal{P}(I)$  is the power set of  $I$ . Let  $(E_i, i \in I)$  be a collection of sets, and let  $E_a = \prod_{i \in a} E_i$  for any  $a \in \mathcal{P}(I)$ . For  $x \in \Omega$ , we denote by  $x_a$  its projection onto  $E_a$ . The factorisation space over  $\mathcal{A}$  is defined as follows:

$$\text{Fac}_{\mathcal{A}} = \left\{ P \in \mathbb{P}(\Omega) : \exists (f_a \in \mathbb{R}_{>0}^{E_a}, a \in \mathcal{A}) \text{ s.t. } \forall x \in \Omega, P = \prod_{a \in \mathcal{A}} f_a(x_a) \right\}$$

Consider an undirected graph  $G = (I, A)$  that is **acyclic**. Denote  $\mathcal{A}(G)$  as the *partially ordered set* (poset) with elements  $V = I \sqcup A$  and the following relations:

- $\forall i \in I, i \leq i$ , and  $\forall e \in A, e \leq e$
- $\forall i \in I, \forall e \in A, i \leq e \iff i \in e$

### Proposition (Factorization on Acyclic Graphs)

Let  $I$  be a finite set, and let  $\Omega = \prod_{i \in I} E_i$  be a product of finite sets, and  $X_i, i \in I$ , a collection of random variables taking values respectively in  $E_i$ . Let  $G = (I, A)$  be a finite acyclic graph.  $P_X \in \mathbb{P}_{>0}(E)$  factors according to  $\mathcal{A}(G)$ , i.e.,  $P_X \in \text{Fac}_{\mathcal{A}(G)}$ , if and only if for any  $\omega \in \Omega$ ,

$$P_X(\omega) = \frac{\prod_{e \in A} P_{X_e}(\omega_e)}{\prod_{i \in I} P_{X_i}^{d(i)-1}(\omega_i)},$$

where  $d(i)$  is the degree of node  $i \in I$ .



- Bayesian inference is maximizing (relative) entropy.

- **Entropy:**

$$S(Q) = - \sum_{\omega \in E} Q(\omega) \ln Q(\omega) \quad (0.1)$$

- Recall that minimizing Gibbs free energy gives Helmholtz free energy:

$$\beta \frac{-\ln Z}{\beta} = \inf_{Q \in \mathbb{P}(E)} (\mathbb{E}_Q[\beta H] - S(Q))$$

- Set  $\beta = 1$ .

- But entropy:

$$S(P_X) = \sum_{e \in A} S(P_{X_e}) - \sum_{i \in I} (d(i) - 1) S(P_{X_i})$$

- Inclusion-exclusion formula:  $c(e) = 1$ ,  $c(i) = -(d(i) - 1)$
- Remarkably, Bayesian inference is the same as minimizing [YFW05, YFW03]:

$$F_{\text{Bethe}}(Q) = \sum_{a \in V} c(a) (\mathbb{E}_{Q_a}[H_a] - S(Q_a))$$

where  $Q := (Q_a \in \mathbb{P}(X_a), a \in V)$  with compatibility by marginalization:

- If  $a$  is an edge and  $i$  a vertex in  $a$
- $\pi_i^e : E_e \rightarrow E_i$
- We ask that  $\pi_{i*}^e(Q_e) = Q_i$

- Bayesian inference corresponds to computing  $\ln Z$  for a Hamiltonian  $H : \prod_{i \in I} E_i \rightarrow \mathbb{R}$ , with  $Z = \sum_x e^{-\beta H(x)}$ .
- From now on, set  $\beta = 1$ ; notation  $E = \prod_{i \in I} E_i$ .
- It is computationally costly to compute directly, but note that

$$-\ln Z = \inf_{Q \in \mathbb{P}(E)} (\mathbb{E}_Q[H] - S(Q))$$

- The previous problem can be reformulated as minimizing:

$$F_{\text{Bethe}}(Q_a, a \in \mathcal{A}(G)) = \sum_{a \in \mathcal{A}(G)} c(a) (\mathbb{E}_{Q_a}[H_a] - S(Q_a))$$

with  $Q_i(x_i) = \sum_{y \in X_{i'}} Q_e(x_i, y)$  when  $e = \{i, i'\}$ .

- Belief propagation is an algorithm of complexity  $\mathcal{O}(|A||E_i|^2)$  to solve this optimization problem, when  $E_i = E_j$  for all  $i, j \in I$ .

- Extension to higher-order interactions: not just graphs.
- I did not invent it [Pel20, YFW05]... but no name?

## Definition (Graphical Presheaves)

Let  $I$  be a finite set and  $\mathcal{A} \subseteq \mathcal{P}(I)$  be a sub-poset of the powerset of  $I$ . Let  $E_i, i \in I$  be finite sets. For  $a \in \mathcal{A}$ , define  $E_a := \prod_{i \in a} E_i$ . Let  $F(a) := E_a$ , and for  $b \subseteq a$ , let  $F_b^a : E_a \rightarrow E_b$  be the projection map from  $\prod_{i \in a} E_i$  to  $\prod_{i \in b} E_i$ . We call  $F$  a graphical presheaf from  $\mathcal{A}$  to  $\mathbf{Mes}^f$ .

- Only projections.
- Only products of variables, and subcollections of variables.

- Consider any map, not just projections:
  - Any measurable maps for  $b \rightarrow a$  and even Markov kernels, i.e., stochastic matrices when the source and target are finite sets.
- Account for possible heterogeneity, incompleteness, and incompatibility in the description of variables:
  - Agents with different world models that communicate their beliefs.
  - Broader class of effective potentials in computational chemistry.

Extension done in previous work [SP22, SPR24, SP24a]

- **Kern<sup>f</sup>**: objects are finite measurable spaces, morphisms are Markov kernels (stochastic matrices).
- $F$  is a contravariant functor from  $\mathcal{A}$  to **Kern<sup>f</sup>**;  $F_b^a : F(a) \rightarrow F(b)$  is denoted element-wise as  $F_b^a(\omega_b | \omega_a)$ , with  $\omega_b \in F(b)$ ,  $\omega_a \in F(a)$ .
  - $F$  encodes all the ways our data can interact.
  - $\mathcal{A}$  is any poset, not just a collection of subsets.
  - Maps are not just projections.
- $Q = (Q_a \in \mathbb{P}(F(a)), a \in \mathcal{A})$
- $F_{\text{Bethe}}(Q) = \sum_{a \in \mathcal{A}} c(a) (\mathbb{E}_{Q_a}[H_a] - S(Q_a))$ ;  $c(a) = \sum_{b \geq a} \mu(b, a)$  is the generalization of the inclusion-exclusion formula associated with  $\mathcal{A}$ .

For a finite poset  $\mathcal{A}$ ,

- the ‘zeta-operator’ of  $\mathcal{A}$ , denoted  $\zeta$ , from  $\bigoplus_{a \in \mathcal{A}} \mathbb{R}$  to  $\bigoplus_{a \in \mathcal{A}} \mathbb{R}$  is defined as, for any  $\lambda \in \bigoplus_{a \in \mathcal{A}} \mathbb{R}$  and any  $a \in \mathcal{A}$ ,  $\zeta(\lambda)(a) = \sum_{b \leq a} \lambda_b$
- its inverse is denoted as  $\mu$ ;  $(\mu(a, b), b \leq a)$  Möbius function of  $\mathcal{A}$ .

We want to do Bayesian inference on these diagram.

- Constraint: the  $Q_a$  must be compatible under the actions of the  $F_b^a$ , i.e.  $F_b^a \circ Q_a = Q_b$
- Problem: find an algorithm to ‘solve’ the optimization problem.  
→ New message passing algorithm!

$F$  induces several actions: on probabilities, on probabilities seen as vectors, on their dual...

- $\tilde{F}_b^a : \mathbb{P}(F(a)) \rightarrow \mathbb{P}(F(b))$  is linear map that sends probability distributions  $\rho \in \mathbb{P}(F(a))$  to  $F_b^a \circ \rho$ , we still note  $\tilde{F}$  the linear map from  $\mathbb{R}^{F(a)}$  to  $\mathbb{R}^{F(b)}$ .
- $\tilde{F}^*$  is the functor obtained by dualizing the morphisms  $\tilde{F}_b^a$ , i.e.  $\tilde{F}_a^{*b} : \tilde{F}(b)^* \rightarrow \tilde{F}(a)^*$  sends linear maps  $l_b : \tilde{F}(b) \rightarrow \mathbb{R}$  to  $l_b \circ \tilde{F}_b^a : \tilde{F}(a) \rightarrow \mathbb{R}$ .

$\mu$  can be extended to account for  $\tilde{F}$  through  $\tilde{F}^*$ :

- for a functor  $G$  from  $\mathcal{A}$  to  $\mathbb{R}$ -vector spaces, we define  $\mu_G$  as, for any  $a \in \mathcal{A}$  and  $v \in \bigoplus_{a \in \mathcal{A}} G(a)$ ,  $\mu_G(v)(a) = \sum_{b \leq a} \mu(a, b) G_a^b(v_b)$ .
- $\zeta_G$  is its inverse,  $\zeta_G(v)(a) = \sum_{b \leq a} G_a^b(v_b)$ .



Recall we want to solve  $\inf F_{\text{Bethe}} = \sum_a c(a)F(Q_a)$  under

- Constraint: the  $Q_a$  must be compatible under the actions of the  $F_b^a$ , i.e.,  $F_b^a \circ Q_a = Q_b$ 
  - i.e.,  $Q \in \lim \tilde{F}$
  - In fact, no... need to add the condition that the distribution sums to one.
  - But it's okay!

image-act.png

- $FE : \prod_{a \in \mathcal{A}} \mathbb{P}(E_a) \rightarrow \prod_{a \in \mathcal{A}} \mathbb{R}$  defined as  $FE(Q) = (\mathbb{E}_{Q_a}[H_a] - S_a(Q_a), a \in \mathcal{A})$ , which sends a collection of probability measures over  $\mathcal{A}$  to their Gibbs free energies.
- $d_Q FE$  denotes the differential of  $FE$  at the point  $Q$ .

## Proposition

Let  $\mathcal{A}$  be a finite poset, and let  $F$  be a contravariant functor from  $\mathcal{A}$  to  $\mathbf{Kern}^f$ . Let  $H_a : F(a) \rightarrow \mathbb{R}$  be a collection of (measurable) functions. The critical points of  $F_{\text{Bethe}}$  are the  $Q \in \lim \tilde{F}$  such that:

$$\mu_{\tilde{F}^*} d_Q FE|_{T \lim \tilde{F}} = 0$$

$T \lim \tilde{F}$  is the underlying vector space of the affine space  $\lim \tilde{F}$

Pose  $I_a(Q_a) = \mathbb{E}_{Q_a}[H_a] - S(Q_a)$

## Theorem (GSP)

$F$  a functor from  $\mathcal{A}^{op}$  to vector spaces. An element  $u \in \lim \tilde{F}$  is a critical point of the  $F_{\text{Bethé}}$  if and only if there is  $(m_{a \rightarrow b} \in \bigoplus_{\substack{a,b \\ b \leq a}} \tilde{F}(b)^*)$  such that for any  $a \in \mathcal{A}$ ,

$$d_u I_a = \sum_{b \leq a} \tilde{F}_b^{a*} \left( \sum_{c \leq b} \tilde{F}_c^{b*} m_{b \rightarrow c} - \sum_{c \geq b} m_{c \rightarrow b} \right) \quad (\text{CP})$$

- To understand in greater detail these propositions and the previous algorithm, we need to extend the setting of the optimization problem.
- Change the loss:
  - Replace entropy with a "local loss."
  - $S(Q_a) \rightsquigarrow I_a(v_a)$
- Change the functor:
  - Replace  $F$  with a contravariant functor from a poset  $\mathcal{A}$  to **Vect**.
- Result: we can extend the message passing algorithm to solve:

$$\min_v \sum_{a \in \mathcal{A}} c(a) I_a(v_a)$$

with  $v := (v_a, a \in \mathcal{A})$  under the constraint  $v \in \lim F$ .

- This approach is different and on some points more general than decentralized optimization on cellular sheaves [HG19].

For  $F$  a functor from  $\mathcal{A}^{op}$  to vector spaces, critical points  $u$  of  $\sum_{a \in \mathcal{A}} c(a)l_a(v_a)$  are  $u \in \bigoplus_{a \in \mathcal{A}} F(a)$  such that:

$$[\mu_{F^*} d_u l] |_{\lim F} = 0$$

where,  $l(v) = (l_a(v_a), a \in \mathcal{A})$ ,  $d_u l(a) = d_{u_a} l_a$  and,

$$[\mu_{F^*} d_u l](a) = \sum_{b \leq a} \mu(a, b) d_{u_b} l_b \circ F_b^a$$

$$0 \rightarrow \lim F \rightarrow \bigoplus_{a \in \mathcal{A}} F(a) \xrightarrow{\delta_F} \bigoplus_{\substack{a, b \in \mathcal{A} \\ a \geq b}} F(b)$$

where for any  $v \in \bigoplus_{\substack{a, b \in \mathcal{A} \\ a \geq b}} F(b)$  and  $a, b \in \mathcal{A}$  such that  $b \leq a$ ,

$$\delta_F(v)(a, b) = F_b^a(v_a) - v_b$$

This is simply stating that  $\ker \delta = \lim F$ .

Understanding expression of critical points:

$$0 \leftarrow (\lim F)^* \leftarrow \bigoplus_{a \in \mathcal{A}} F(a)^* \xleftarrow{d_F} \bigoplus_{\substack{a, b \in \mathcal{A} \\ a \geq b}} F(b)^*$$

Pose  $d = \delta^*$ . For any  $l_{a \rightarrow b} \in \bigoplus_{\substack{a, b \in \mathcal{A} \\ a \geq b}} F(b)^*$  and  $a \in \mathcal{A}$ ,

$$dm(a) = \sum_{a \geq b} F_b^{a*}(m_{a \rightarrow b}) - \sum_{b \geq a} m_{b \rightarrow a}$$



$$\mu_F^* d_U l \in \text{im } d$$

is the same as the fact that there is  $(m_{a \rightarrow b} \in F(b)^* \mid a, b \in \mathcal{A}, b \leq a)$  such that,

$$d_U l = \zeta_F^* dm$$

Assume that the local losses  $l_a$ ,  $a \in \mathcal{A}$  are such that there is a collection of functions  $g_a$ ,  $a \in \mathcal{A}$  that inverses the relation induced by differentiating the local losses, i.e.

$$d_{u_a} l_a = y_a \iff u_a = g_a(y_a)$$

It is the case for the free energy  $\mathbb{E}_{Q_a}[H_a] - S(Q_a)$ .

Messages:

$$m(t) \in \bigoplus_{\substack{a,b: \\ b \leq a}} F(b)^*: m_{a \rightarrow b} \text{ for } b \leq a$$

## Understanding this choice of message passing algorithm:

$g$  sends Lagrange multipliers  $m$  to  $u \in \bigoplus_{a \in \mathcal{A}} F(a)$ .  $\delta_F(u) = 0$  defines the constraints on  $u$ .

$\delta_F g \zeta_{F^*} d_F$  sends a Lagrange multiplier  $m \in \bigoplus_{\substack{a, b \in \mathcal{A} \\ a \geq b}} F(b)^*$  to a constraint  $c \in \bigoplus_{\substack{a, b \in \mathcal{A} \\ a \geq b}} F(b)$  defined as, for  $a, b \in \mathcal{A}$  such that  $b \leq a$ ,

$$c(a, b) = \delta_F g \zeta_{F^*} d_F m(a, b) = F_b^a g_a(\zeta_{F^*} d_F m(a)) - g_b(\zeta_{F^*} d_F m(b)) \quad (0.2)$$

We are interested in  $c = 0$ , i.e.

$$\delta_F g \zeta_{F^*} d_F m = 0$$

Understanding this choice of message passing algorithm:

Choice of algorithm on the Lagrange multipliers so that

$$\delta_F g \zeta_{F^*} \mathbf{d}_F m = 0,$$

$$m(t+1) - m(t) = \delta_F g \zeta_{F^*} \mathbf{d}_F m(t)$$

Any other choice would also be a good candidate!

The message passing algorithm is defined as:

$$\delta m := \delta_{\tilde{F}} g \zeta_{\tilde{F}^*} d_{\tilde{F}} m$$

Define  $BP_{F,H} := \delta_{\tilde{F}} g \zeta_{\tilde{F}^*} d_{\tilde{F}}$ .

When differentiating the free energy:

$$y_a = H_a + \ln q_a + 1$$

Therefore,  $g_a(y_a) = e^{y_a - H_a - 1}$ .

- Joint work with Toby St Clere Smithe, in progress.
- Consider a natural transformation  $\phi : F \rightarrow F_1$  where  $\phi_a$  is a deterministic map, not a Markov kernel.
- The map  $\phi$  extends into maps between  $\tilde{F} \rightarrow \tilde{F}_1$  and  $\tilde{F}^* \rightarrow \tilde{F}_1^*$ .
- $\phi$  induces maps between  $\bigoplus_b \tilde{F}(b) \rightarrow \bigoplus_b \tilde{F}_1(b)$  and  $\bigoplus_{b \leq a} \tilde{F}(b) \rightarrow \bigoplus_{b \leq a} \tilde{F}_1(b)$ . It also induces a map  $\phi^* : \bigoplus_b \tilde{F}_1^*(b) \rightarrow \bigoplus_b \tilde{F}^*(b)$  and  $\phi^* : \bigoplus_{b \leq a} \tilde{F}_1^*(b) \rightarrow \bigoplus_{b \leq a} \tilde{F}^*(b)$ .

Pose:

$$\tilde{H}_a = \ln \sum_{\omega' : \phi_a(\omega') = \omega} e^{-H_a(\omega')}$$

Then we showed that:

$$BP_{F_1, \tilde{H}} = \phi \circ BP_{F, H} \circ \phi^*$$

- Few results on characterizing critical points of the Bethe free energy.
- Use transformations on the underlying functor to reduce to simpler cases (Hamiltonians, posets).

What about base change?  $\phi : \mathcal{A} \rightarrow \mathcal{A}_1$

- When a right adjoint to the pullback exists, results on natural transformations can be reused.
- When  $\mathcal{A}$  is isomorphic to a full subposet of  $\mathcal{A}_1$ , similar result holds.

Thank you for your attention

Thank you for your attention!



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